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WROCLAW UNIVERSITY
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Institute of Navigation
University of Stuttgart

THE OVERVIEW OF REAL-TIME GNSS METEOROLOGY @UPWR

- real-time ZTD/IWV accuracy
 - horizontal gradients
 - low-cost GNSS receivers

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MOTIVATION

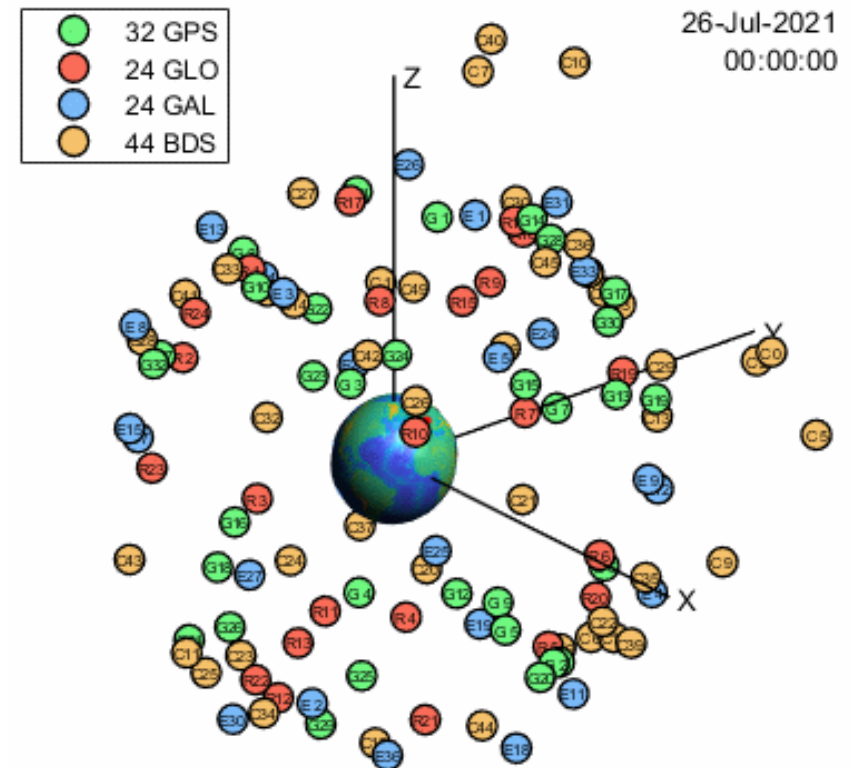
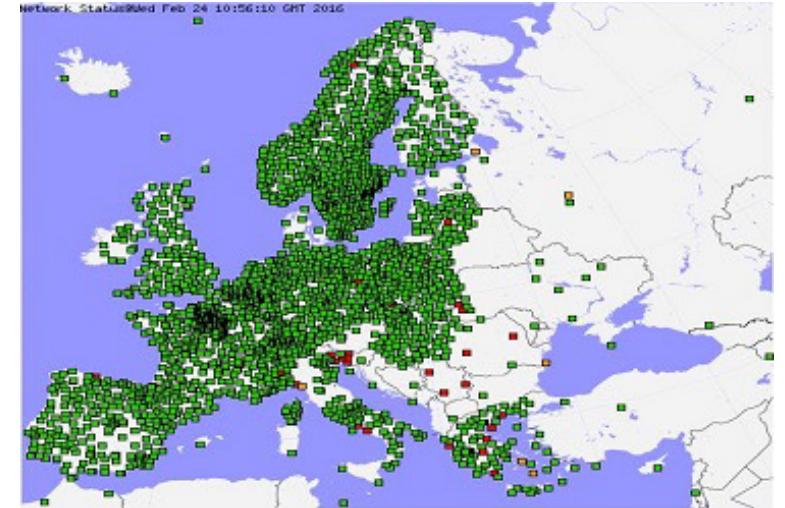
STATUS OF GNSS METEOROLOGY:

- well established tool
- provides Zenith Total Delays (ZTD)
- ZTD => Integrated Water Vapor (IWV)
- latency <1 hour

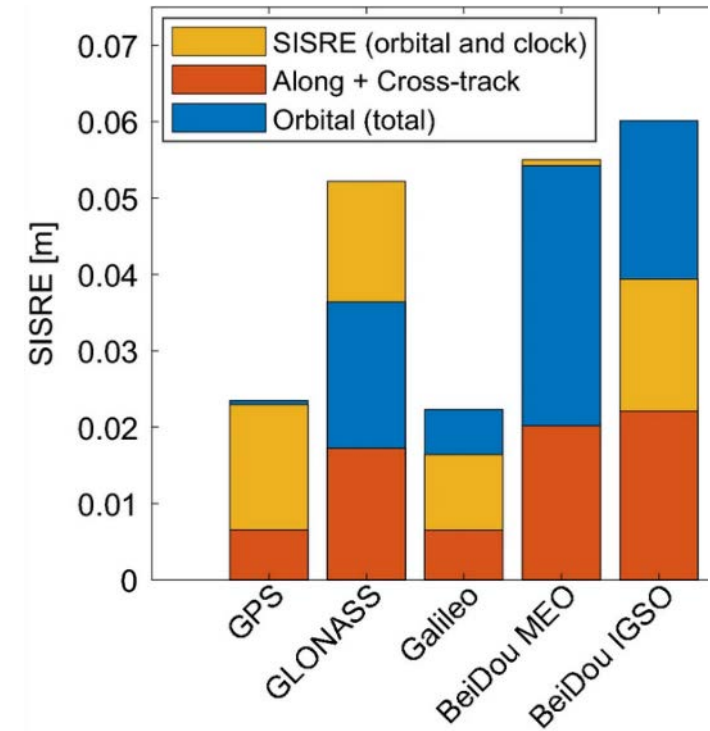
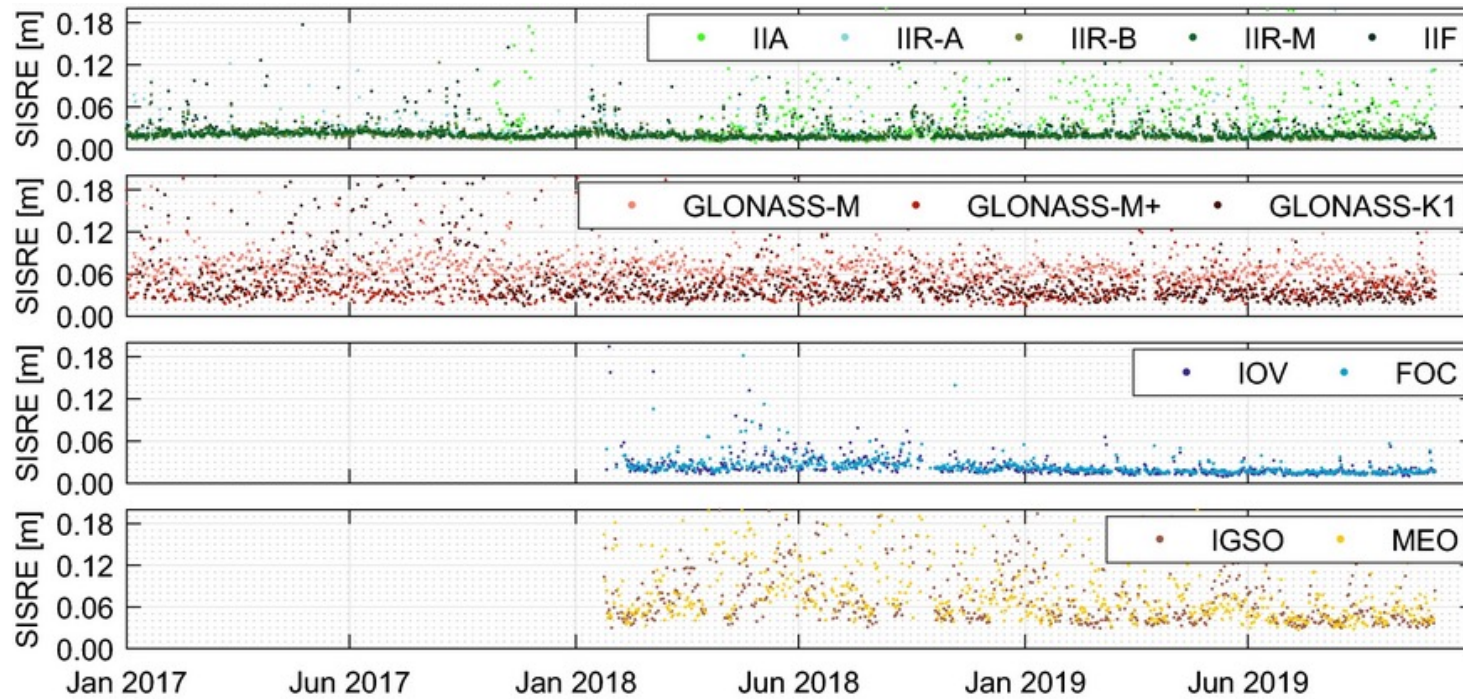
CHALLENGES:

- multi-GNSS multi-frequency solutions
- transition to **real-time**
- estimation of (reliable) horizontal gradients
- monitoring severe weather conditions
- network densification (local scale phenomena)

<https://www.eumetnet.eu>



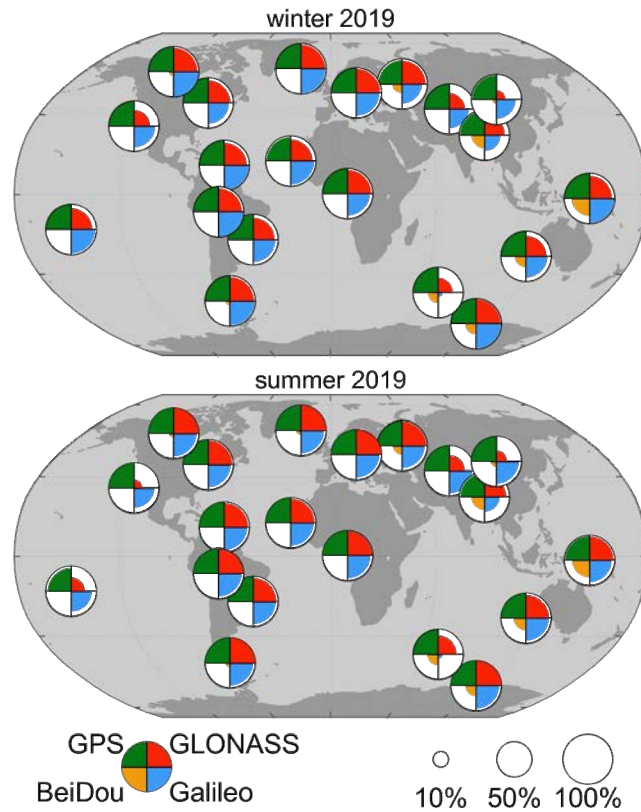
EVOLUTION OF RT ORBITS AND CLOCKS



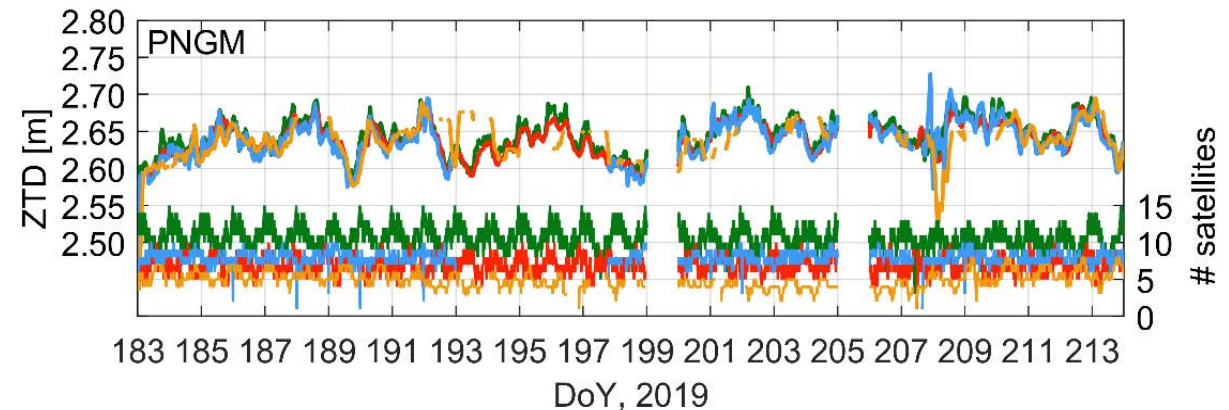
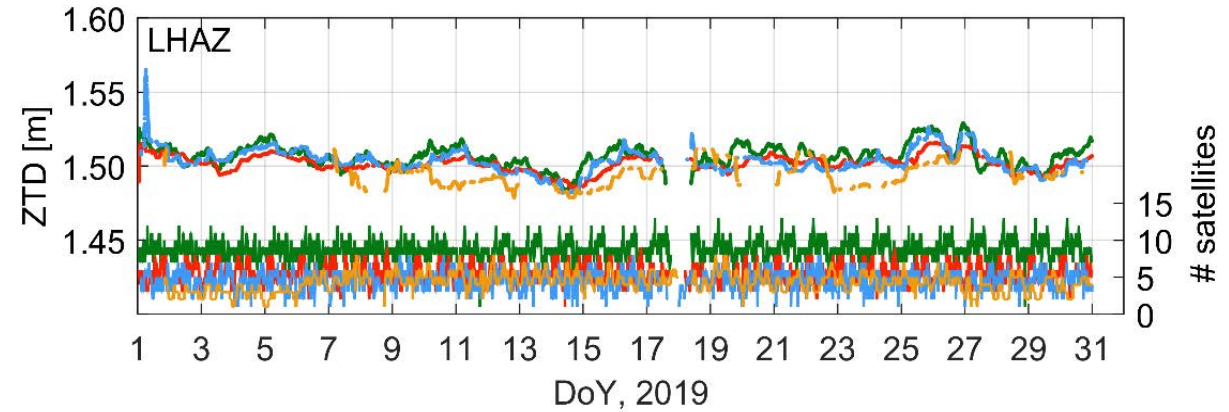
IGS RTS STATUS:

- 11 ACs , 79 mount points (in most cases G+R+E)
- constantly improving accuracy (SISRE)

SINGLE-GNSS ZTD



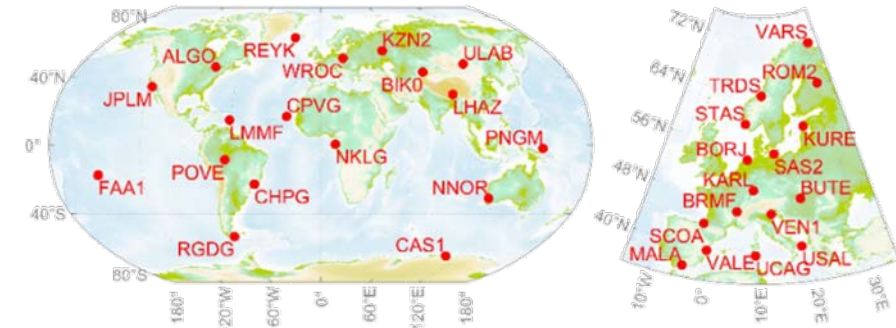
Availability of real-time ZTD from single GNSS processing



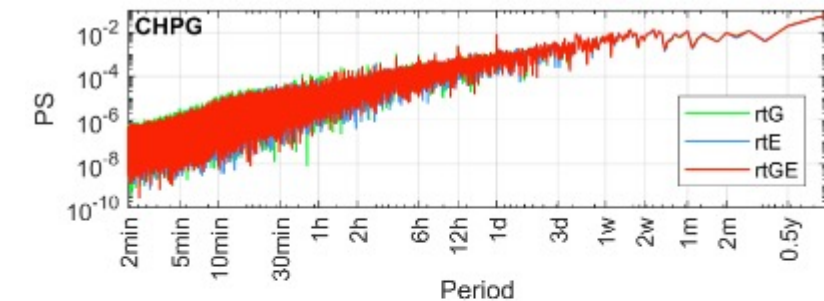
Time series of real-time ZTD from single GNSS processing

- GPS and Galileo result similar RT ZTD ($r=0.97$, $RMSE=8.3mm$)
- BeiDou (2) only in Asia ($r=0.71$, $RMSE=25mm$)

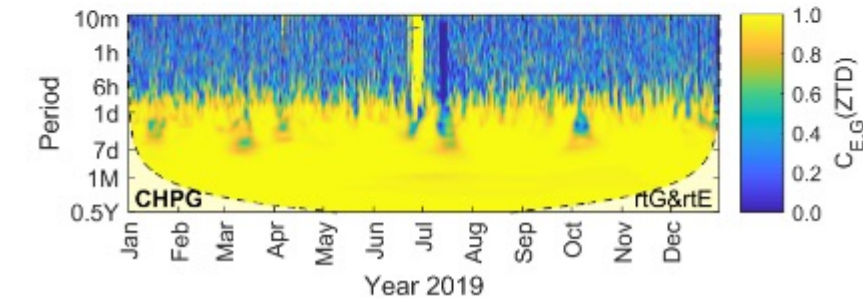
GPS + GALILEO



Location of test stations from IGS and EPN networks.



PS density plot for real-time ZTD



Magnitude squared wavelength coherence between ZTD from the GPS-only and Galileo-only solutions

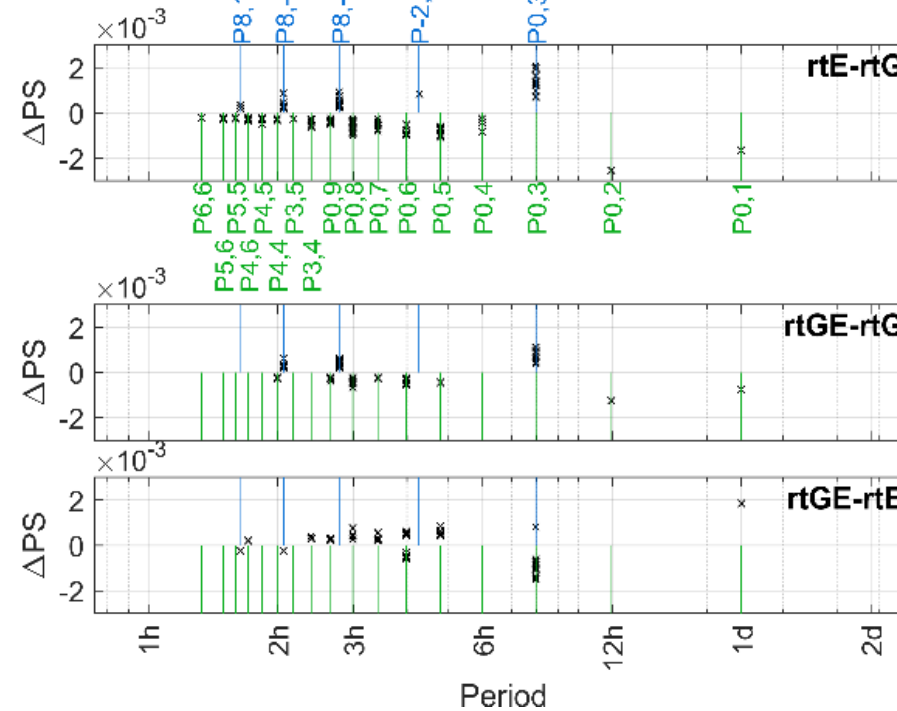
Period P with expected orbit-related artificial signals:

$$P_{n,m}^{-1} = n \cdot f^S + m \cdot f_E$$

f^S – frequency of a satellite constellation period

f_E – frequency of the Earth revolution period

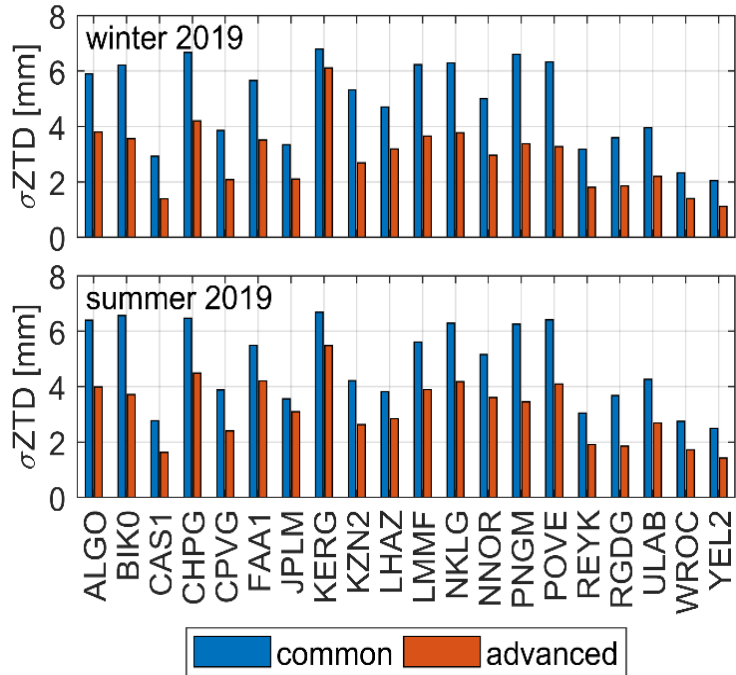
n, m – small integers



Peaks at differential PS (ΔPS) with selected periods of expected orbit-related artificial signals for GPS (green) and Galileo (blue).

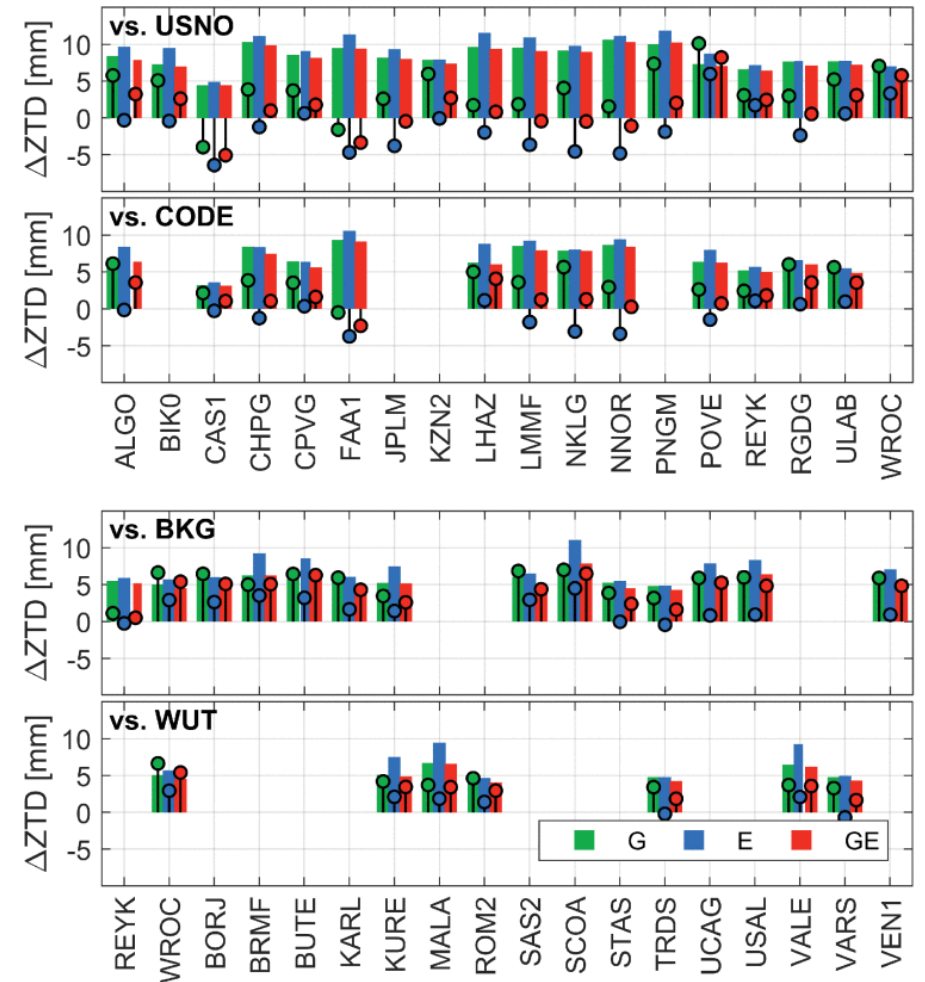
- single-system ZTD suffer from orbit-related artificial signals of high frequency;
- GPS + Galileo suppress such effects

KEY FINDINGS



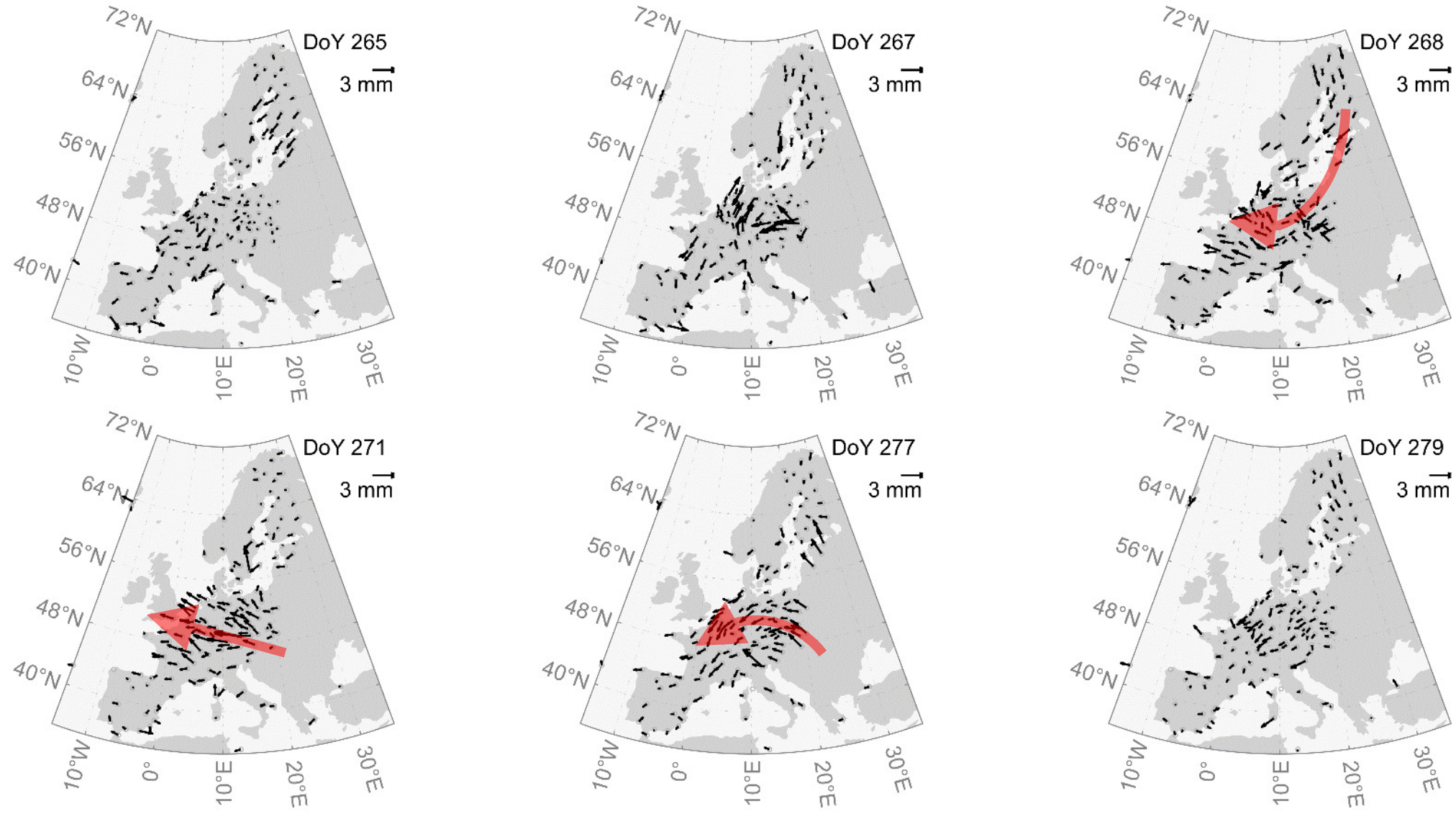
A posteriori standard deviations of estimated ZTD (σ_{ZTD}) obtained with common and advanced strategies

Mean offset (circle) and standard deviation (bar) of ZTD differences between GPS-only, Galileo-only and GPS + Galileo real-time solution and final products from different analysis centers



- definition of superior strategy for RT ZTD: raw PPP, quad-GNSS, weighting, gradients
- RT GPS + Galileo: accuracy similar to quad-GNSS, suppress artificial signals
- RT ZTD accuracy: <10 mm vs GFS NWM; 7-8 mm vs IGS Final ZTD; **5-6 mm** vs EPN

TROPOSPHERE ASYMMETRY – HURRICANE LORENZO (2019)

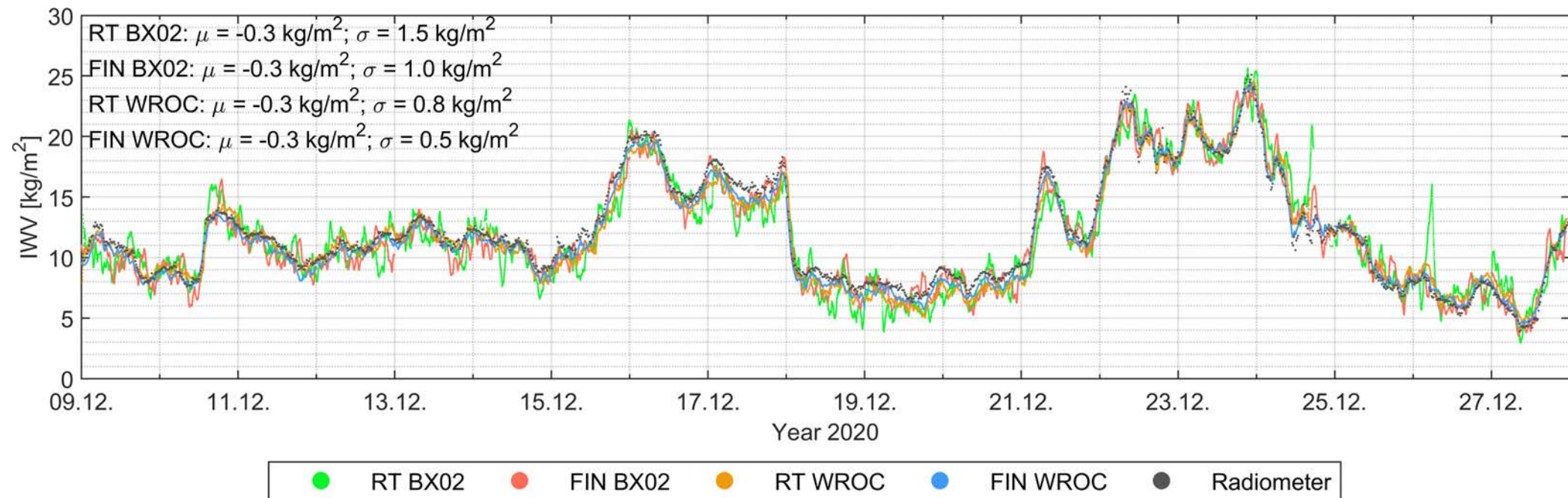


MONITORING RT ZTD/IWV WITH LOW-COST GNSS

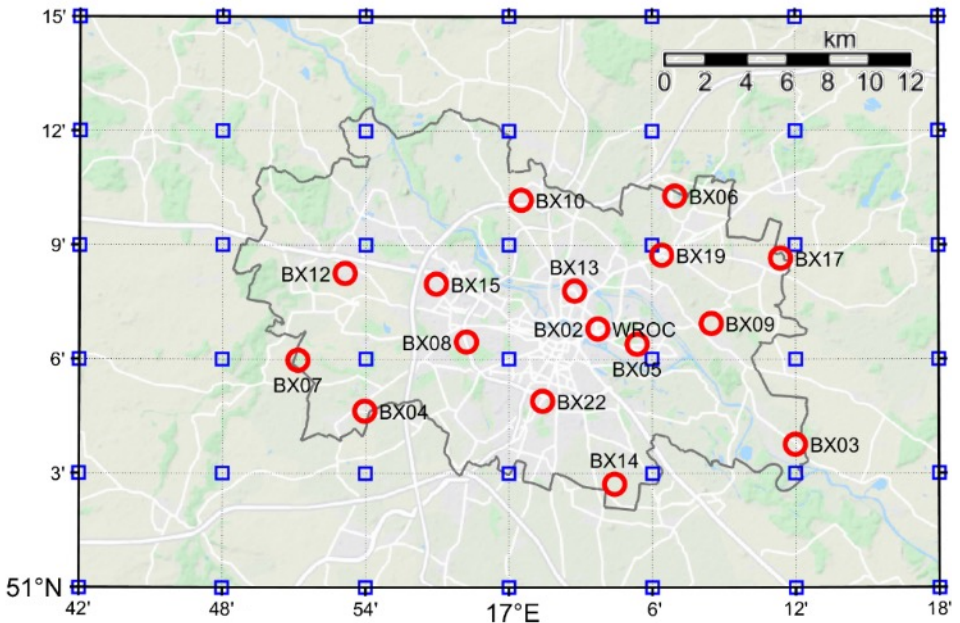


Co-located instruments:

- IGS WROC
- low-cost GNSS (BX02)
- microwave radiometer



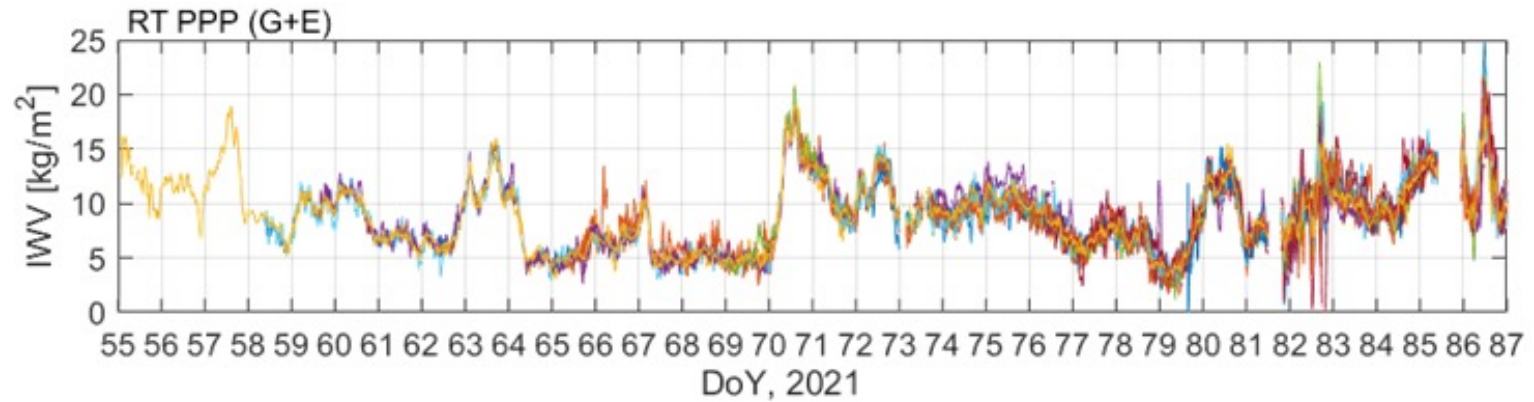
ZTD/IWV DYNAMICS AT A LOCAL SCALE



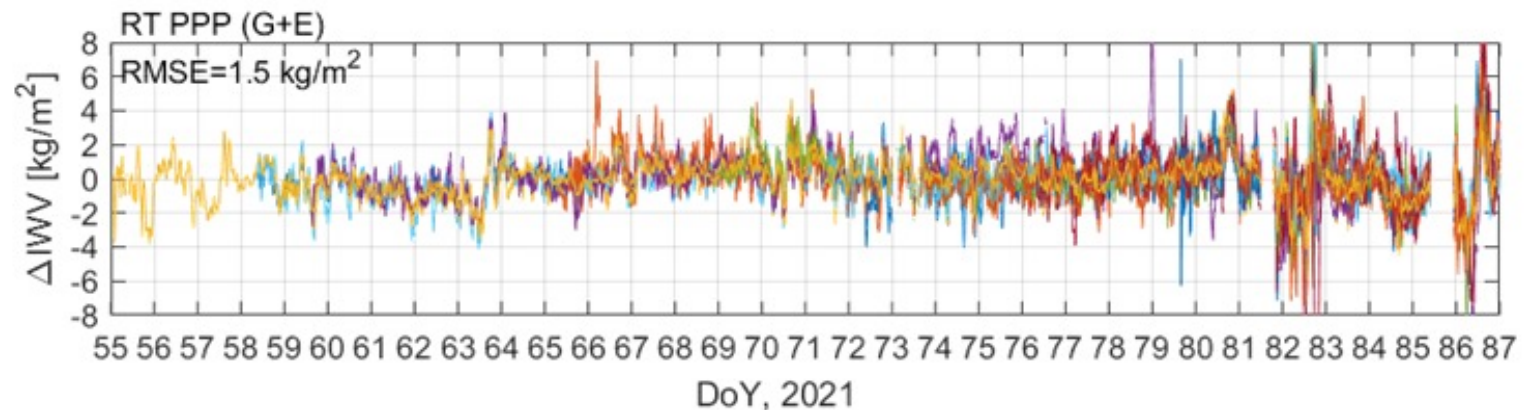
- WRF grid point
- low-cost station

- 17 low-cost stations
- c.a. 300 km² (3 – 8 km)
- ≥13 receivers for 15 days
(March, 2021)

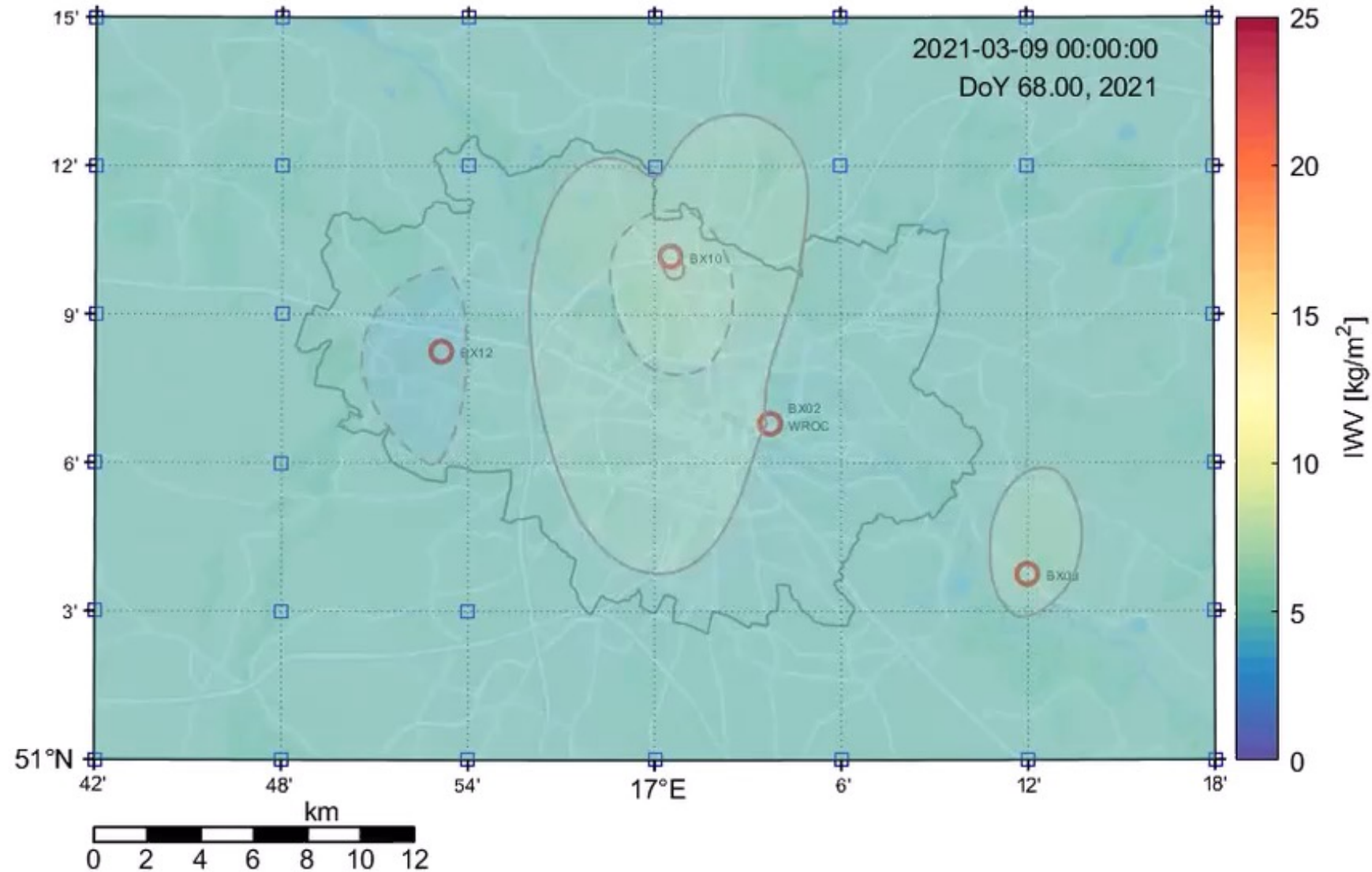
real-time IWV time series (42 days)



real-time IWV vs WRF



ZTD/IWV DYNAMICS AT A LOCAL SCALE



DIFFERENCES:

1) RT IWV vs WRF:

- 60% smaller than 1kg/m²
- min: -10.7 kg/m²
- max: +12.2 kg/m²

2) inter-station IWV:

- max: 16.6 kg/m²

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Thank you!



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IGS 2022 Virtual Workshop
„Science from Earth to Space”