



Real-time coseismic fault model estimation based on RTK-GNSS analysis in Japan

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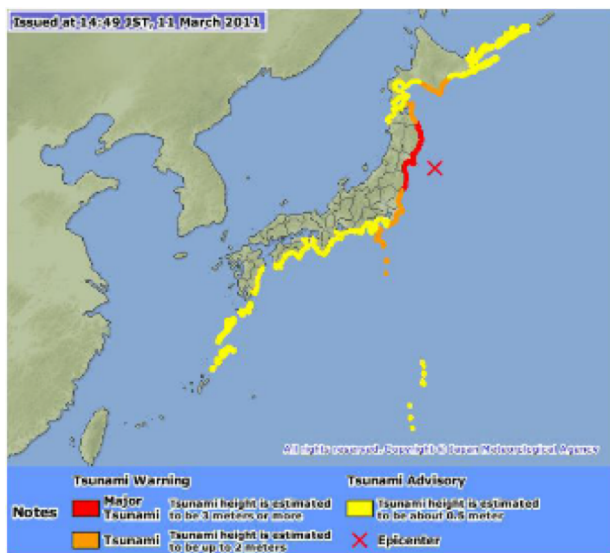
③ Tests for past earthquakes

④ 2016 Kumamoto earthquake

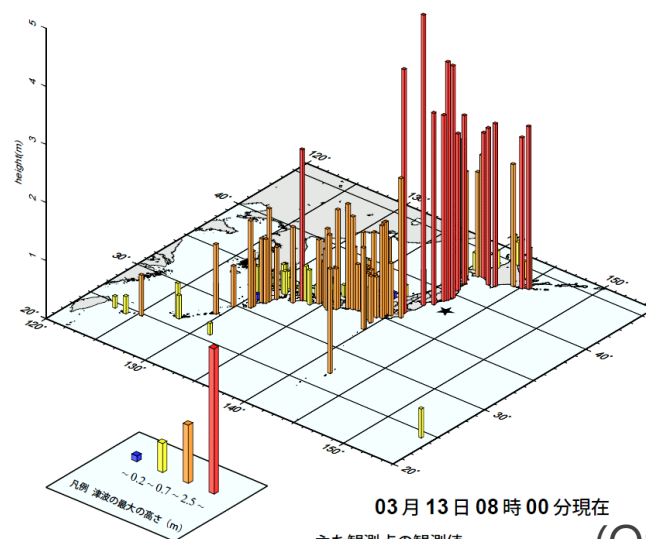
⑤ Summary

Underestimation of Tsunami warning for the 2011 Tohoku Earthquake (Mw 9.0)

Warning at 3 minutes



Observed

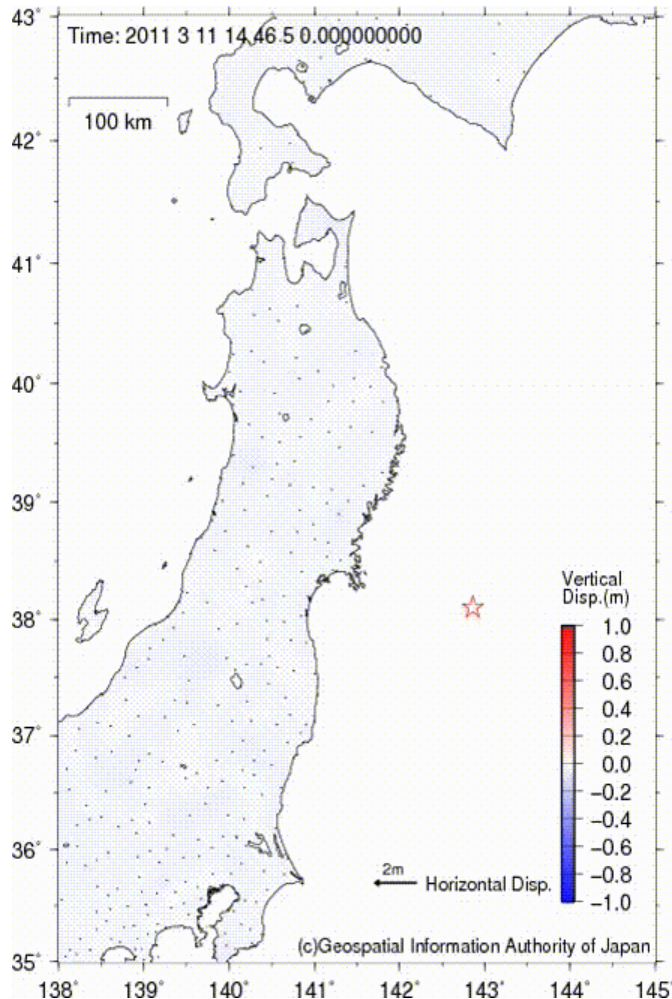


Reasons:

- tsunami warning depended on magnitude based on **short period seismometers**
- Used a saturated magnitude (**M7.9**)

How to prevent the saturation problem?

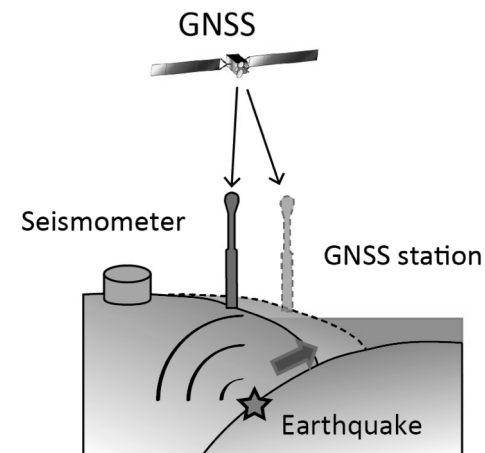
Prevention of the Magnitude Saturation



(www.gsi.go.jp/cais/chikakuhendo40010.html)

Real-time Kinematic GNSS provides:

- Real-time displacement
- Finite fault model
- Mw **free from saturation problem**



Japan's official CORS (GNSS) network



- 1,318 stations
- Distributed at 20 km intervals
- Continuous observation
- Real-time communication

Enables **real-time finite fault estimations** based on GNSS data

GOAL

Provision of
finite fault model within 3 minutes
to improve tsunami warning

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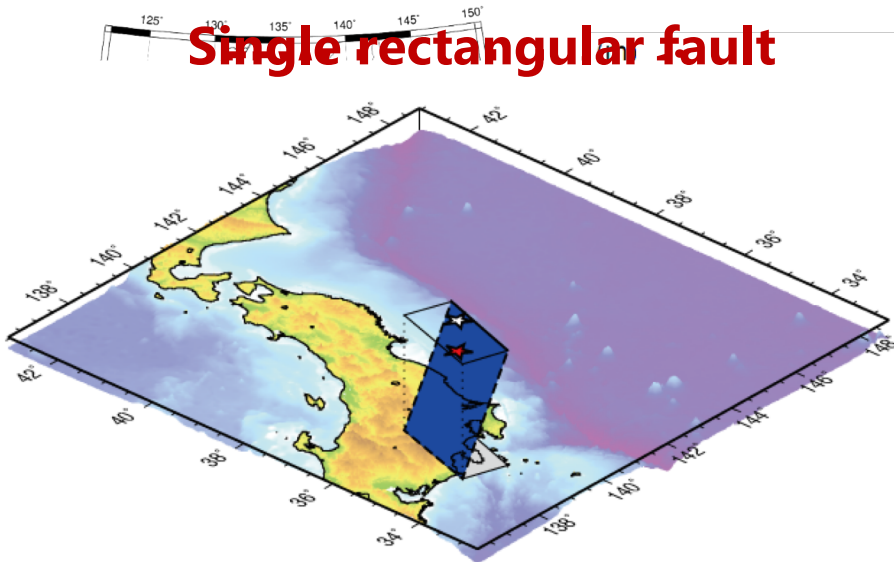
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Development of REGARD system

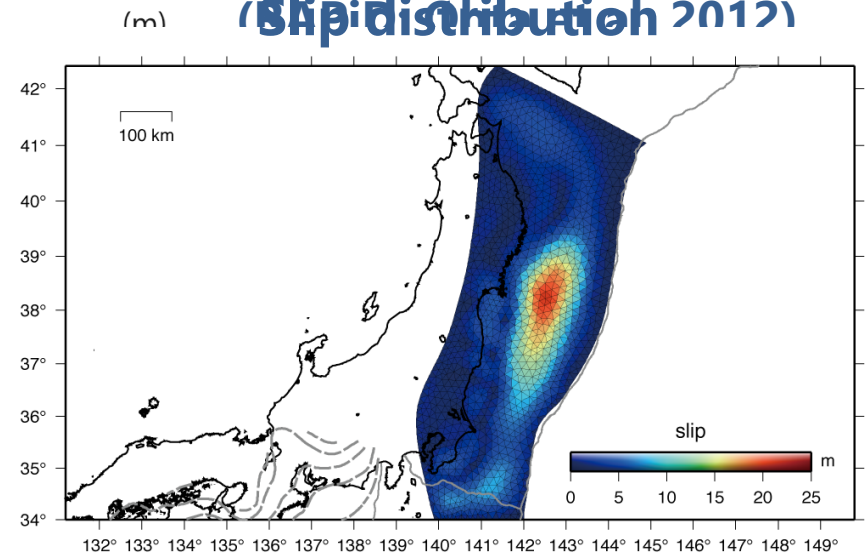
Provides Mw within 3 minutes

- Calculates 1Hz displacement by RTK
- Detects earthquake events
- Estimates fault model automatically

Single rectangular fault



GNSS-based detection
(Slip distribution 2012)



Threshold: 10 cm

Basic concept of the system

Continuously

RTK-GNSS analysis

30 – 40 sec

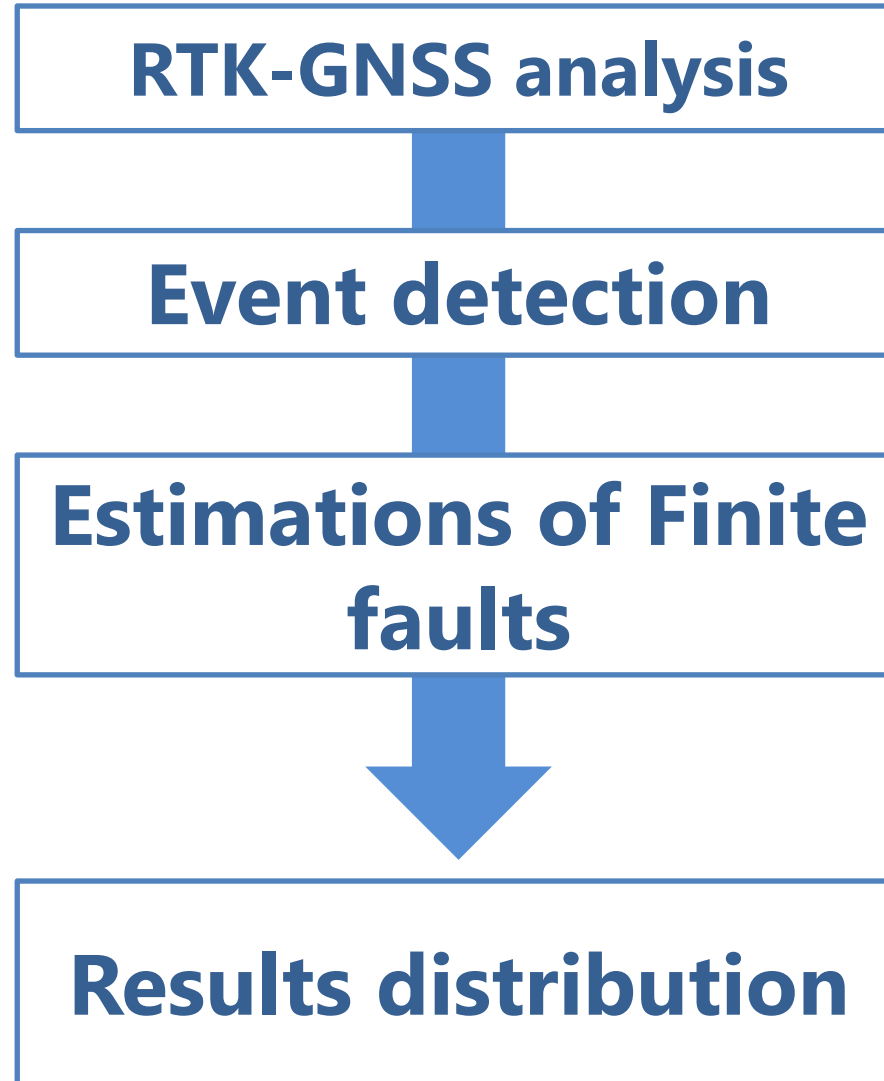
Event detection

1 – 3 min

**Estimations of Finite
faults**

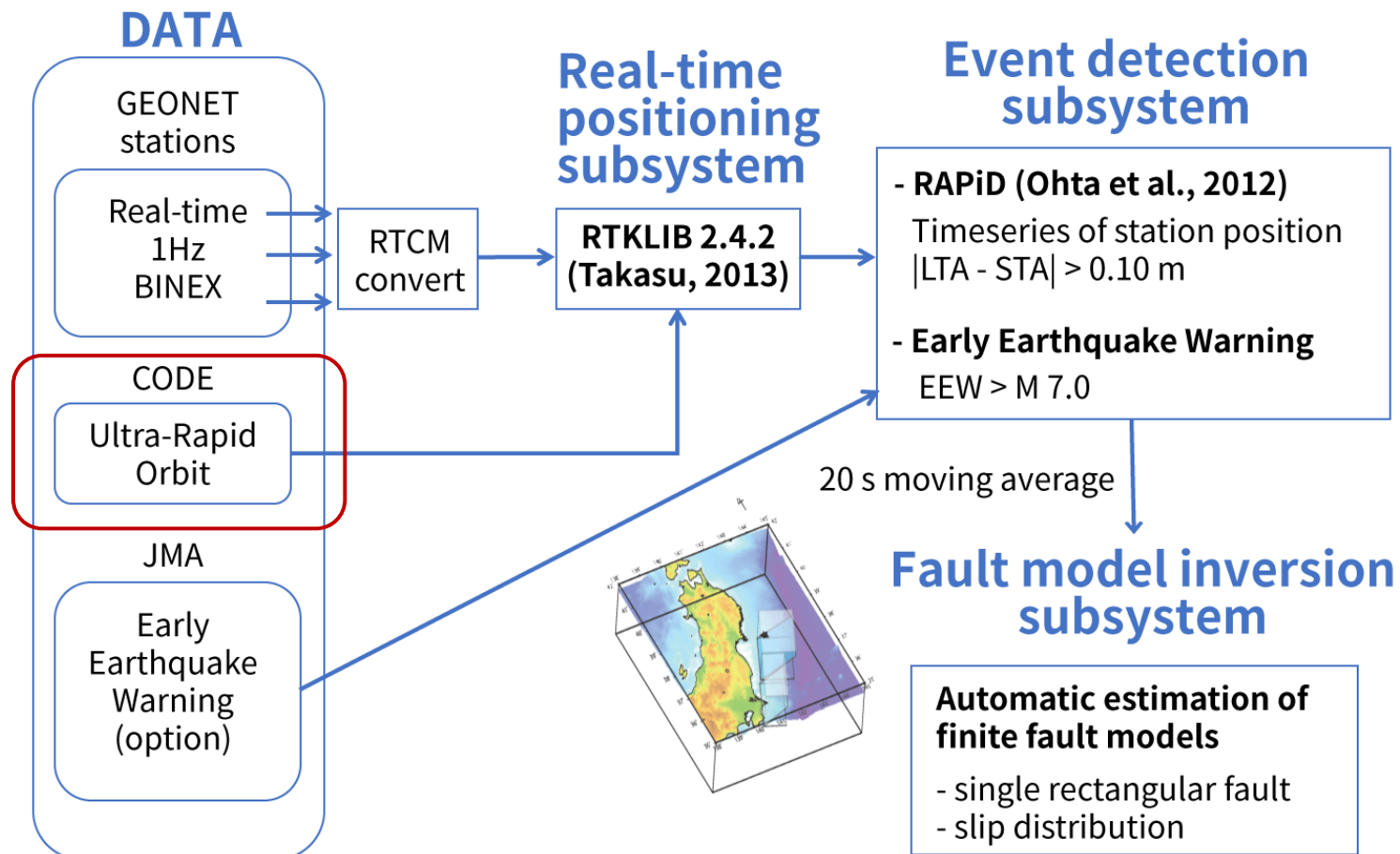
3 min ~

Results distribution

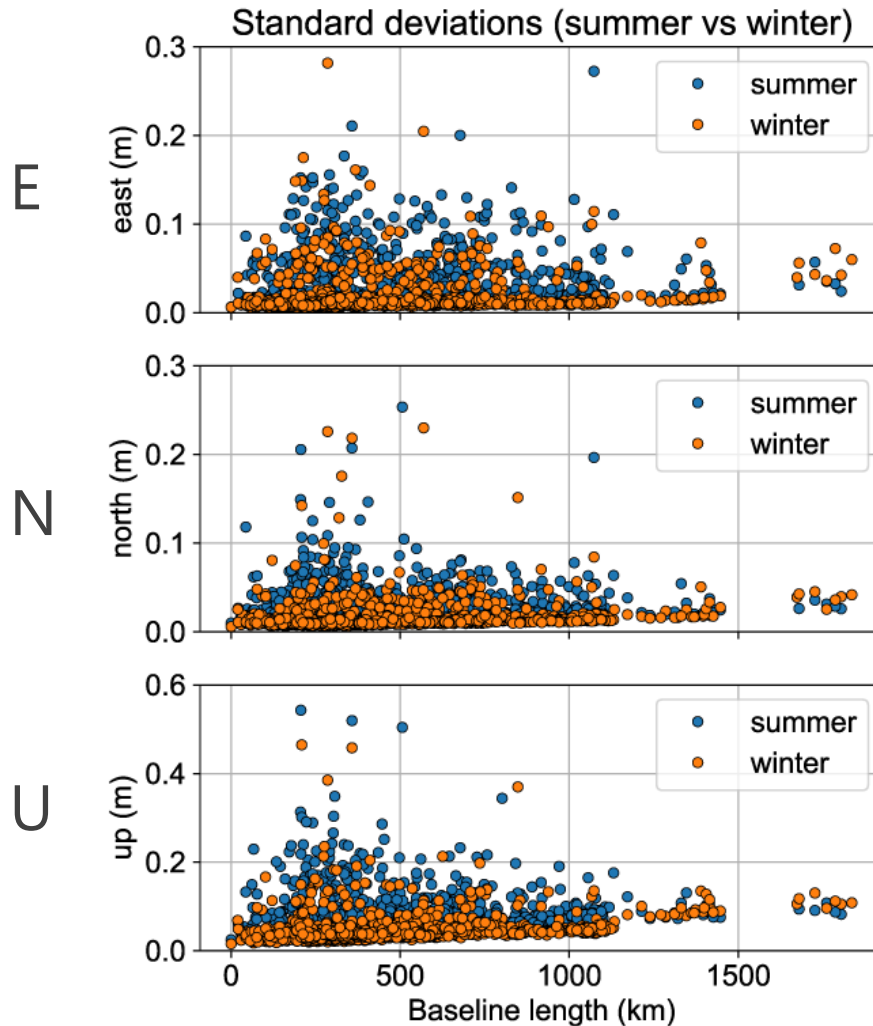


Importance of ultra-rapid orbit

REGARD system depends on **ultra-rapid orbit (predicted part)** for precise positioning



Positioning precision of REGARD



Mean Std: 2.4cm

Mean Std: 2.2cm

Mean Std: 6.1cm

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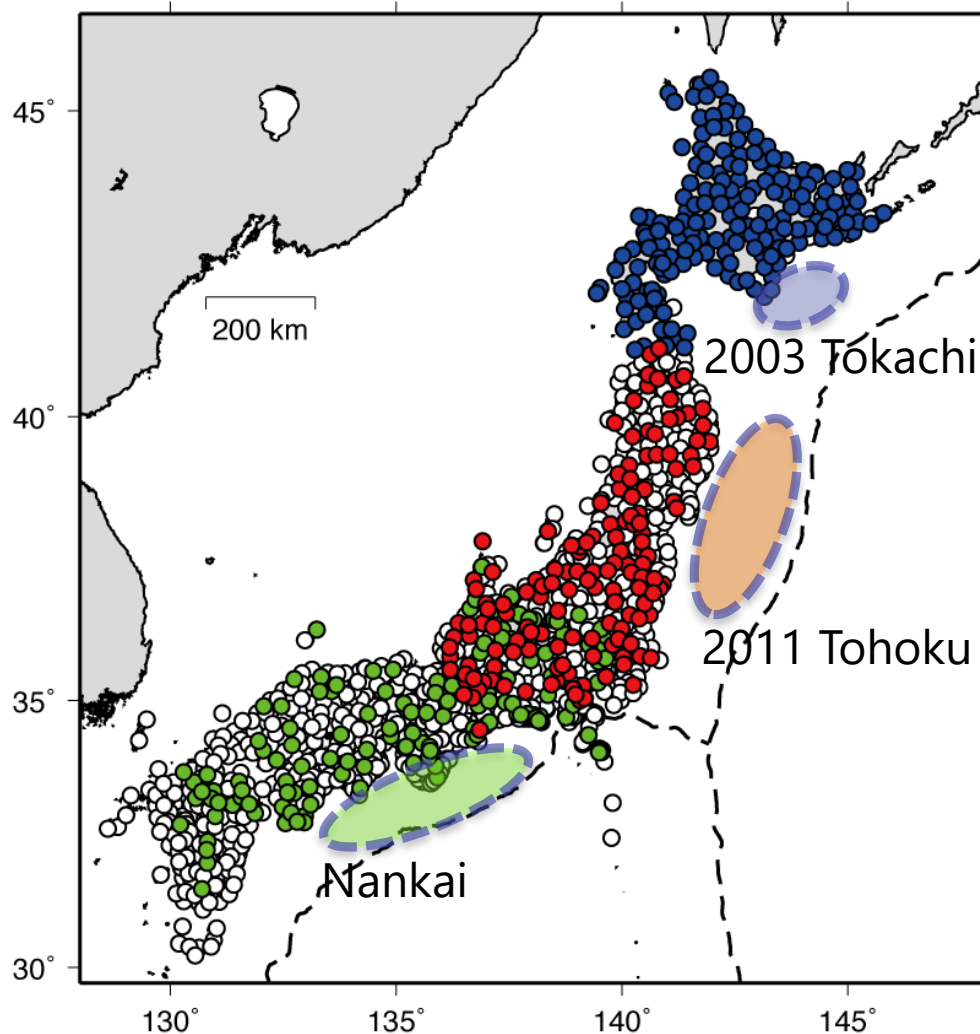
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Tests for past large earthquakes

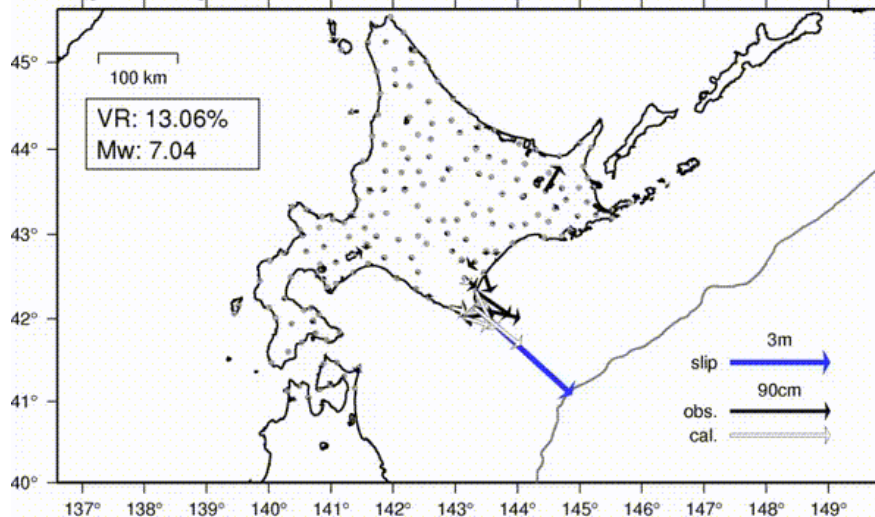


- 2003 Tokachi-oki earthquake (Mw 8.3)
- 2011 Tohoku earthquake (Mw 9.0)
- Nankai Trough earthquake (Mw 8.7; simulation data)

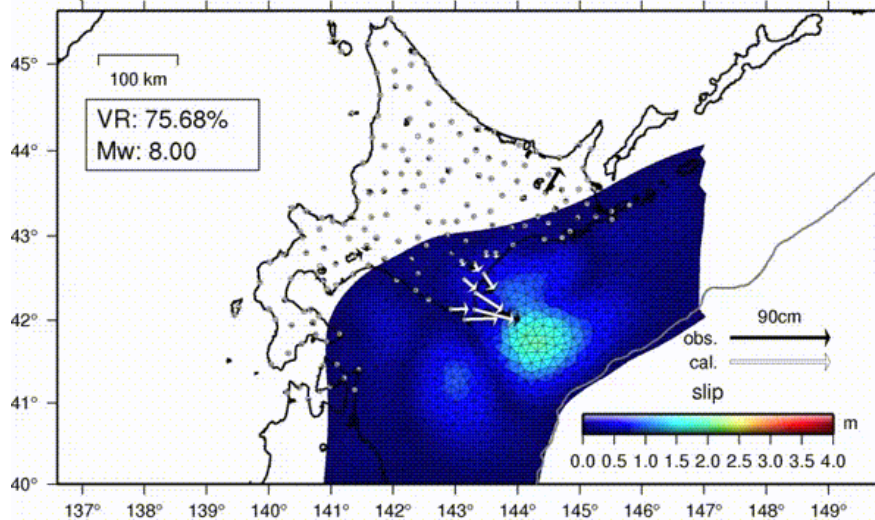
2003 Tokachi-oki earthquake (Mw 8.3)

sec = 33

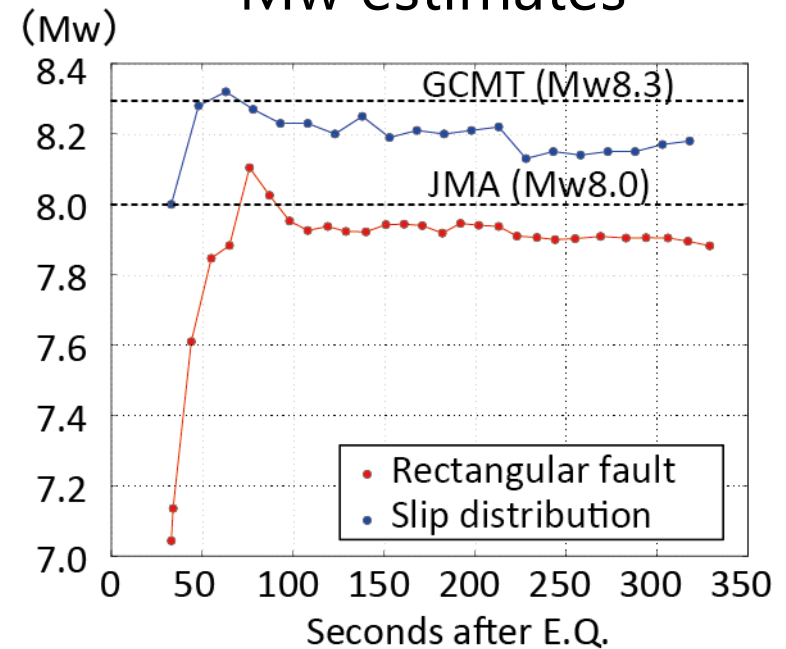
single rectangular fault model



slip distribution model



Mw estimates

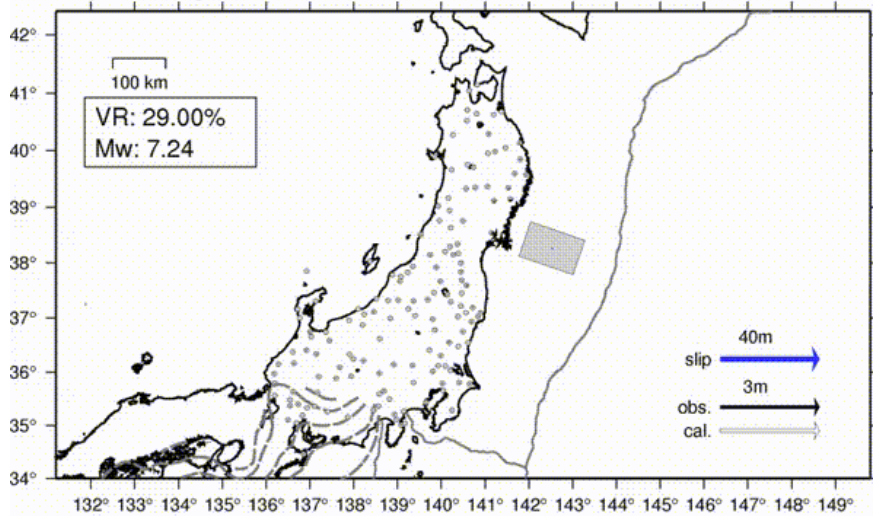


- **Both models were stable** with high VRs
- Single rectangular fault was smaller because it converged to a shallower depth

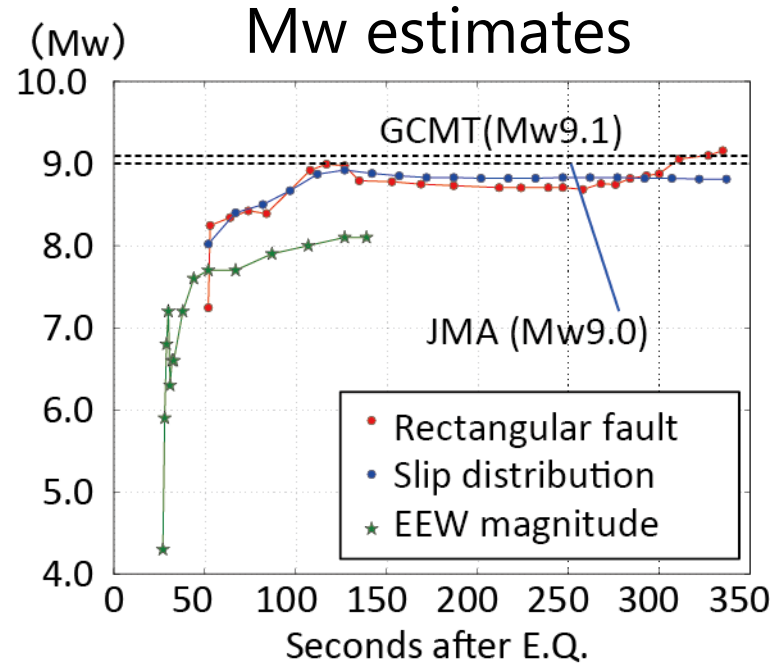
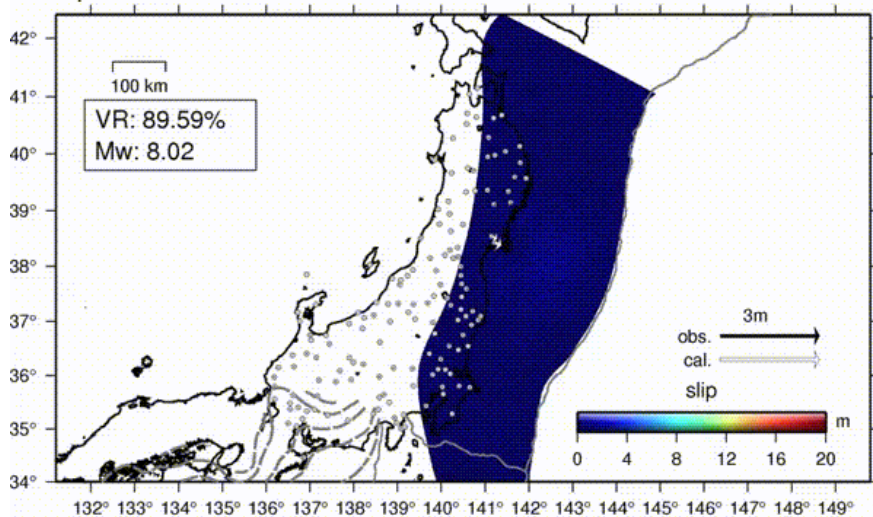
2011 Tohoku earthquake (Mw 9.0)

sec = 52

single rectangular fault model



slip distribution model



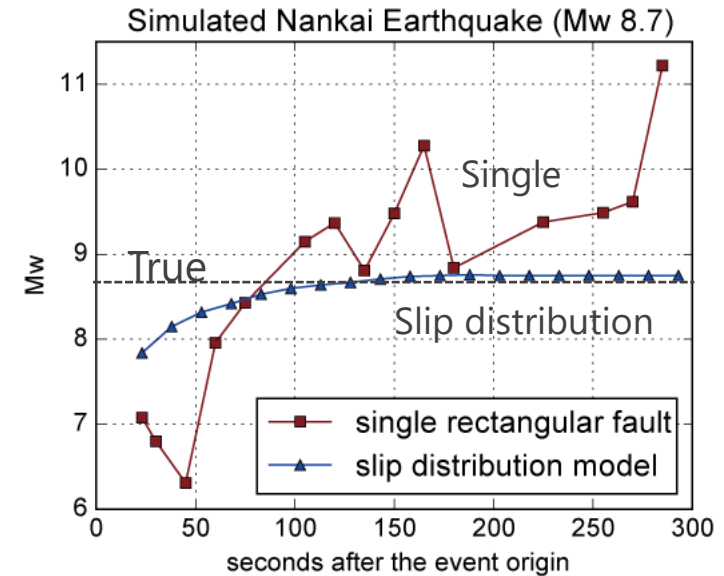
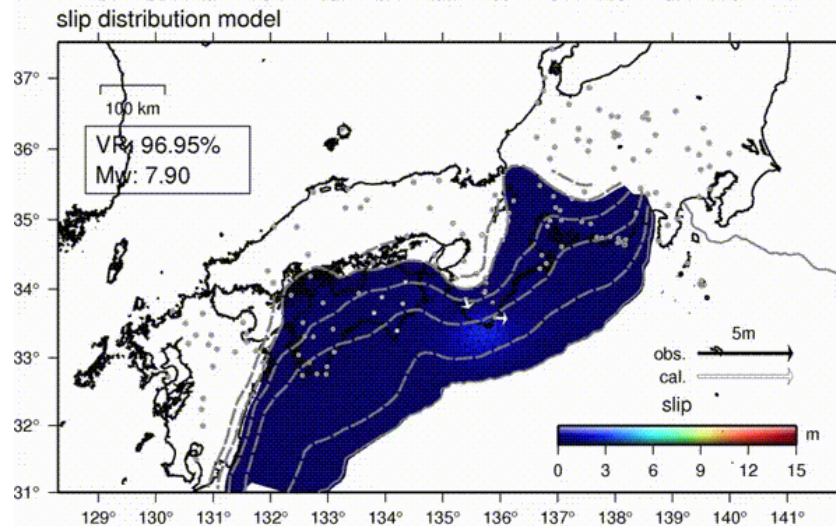
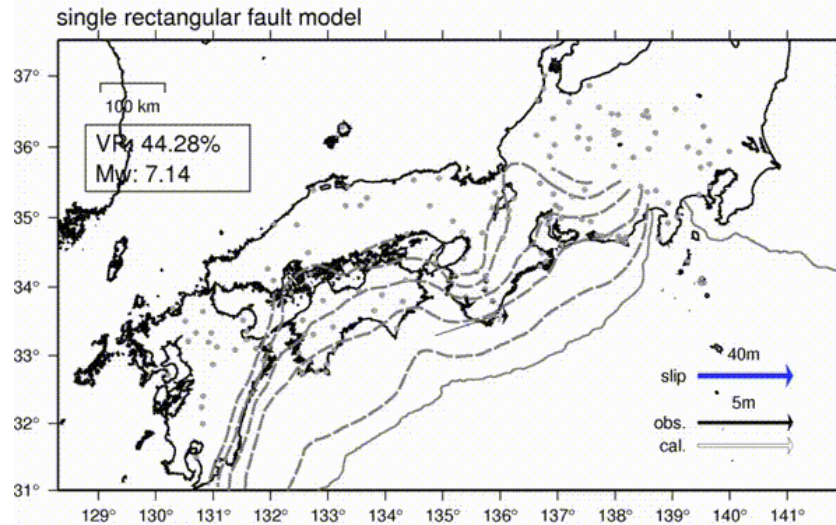
- **Stable after 120 seconds**

Single fault: Mw 9.03 (VR 96%)

Slip distribution: Mw 8.83 (VR 99%)

Nankai Trough earthquake (Mw8.7)

sec = 30



- **Slip distribution model provided accurate Mw**
- Single rectangular fault was unstable due to the complex plate boundary and slip

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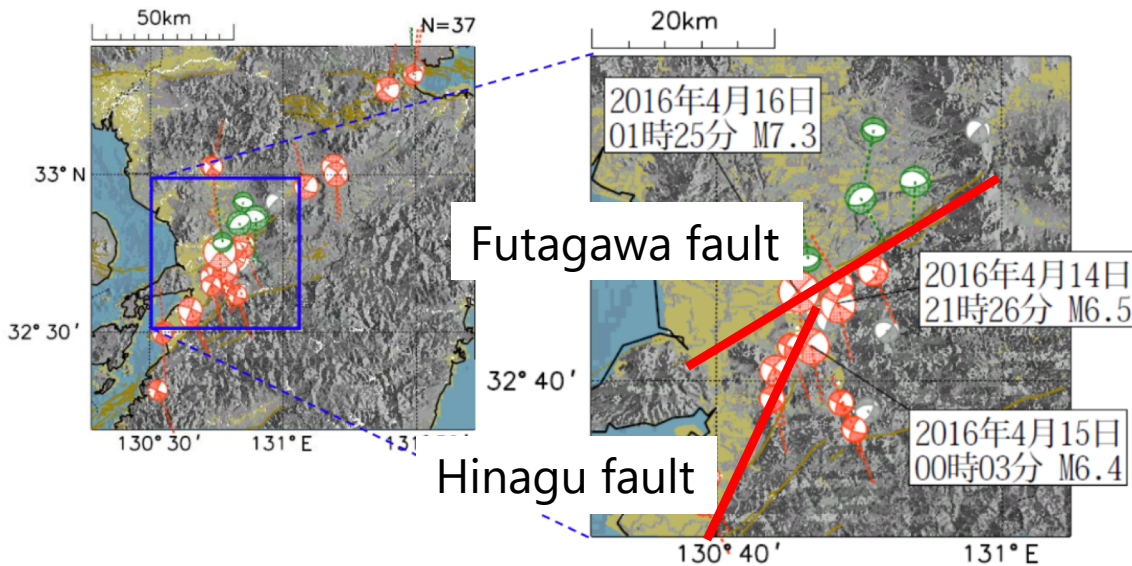
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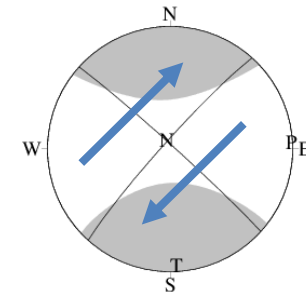
The 2016 Kumamoto earthquake (M7.3; Mw7.0)



(Japan Meteorological Agency)

図2-4 発震機構 (CMT 解) 分布図
(1997年10月1日~2016年4月30日、
深さ0~30km、 $M \geq 4.0$)
シンボルから伸びる点線は張力軸の方位を示す。
橙色は横ずれ断層型、緑色は正断層型の発震機構を示す。
震央分布図中の細線は、地震調査研究推進本部の長期評価による活断層を示す。

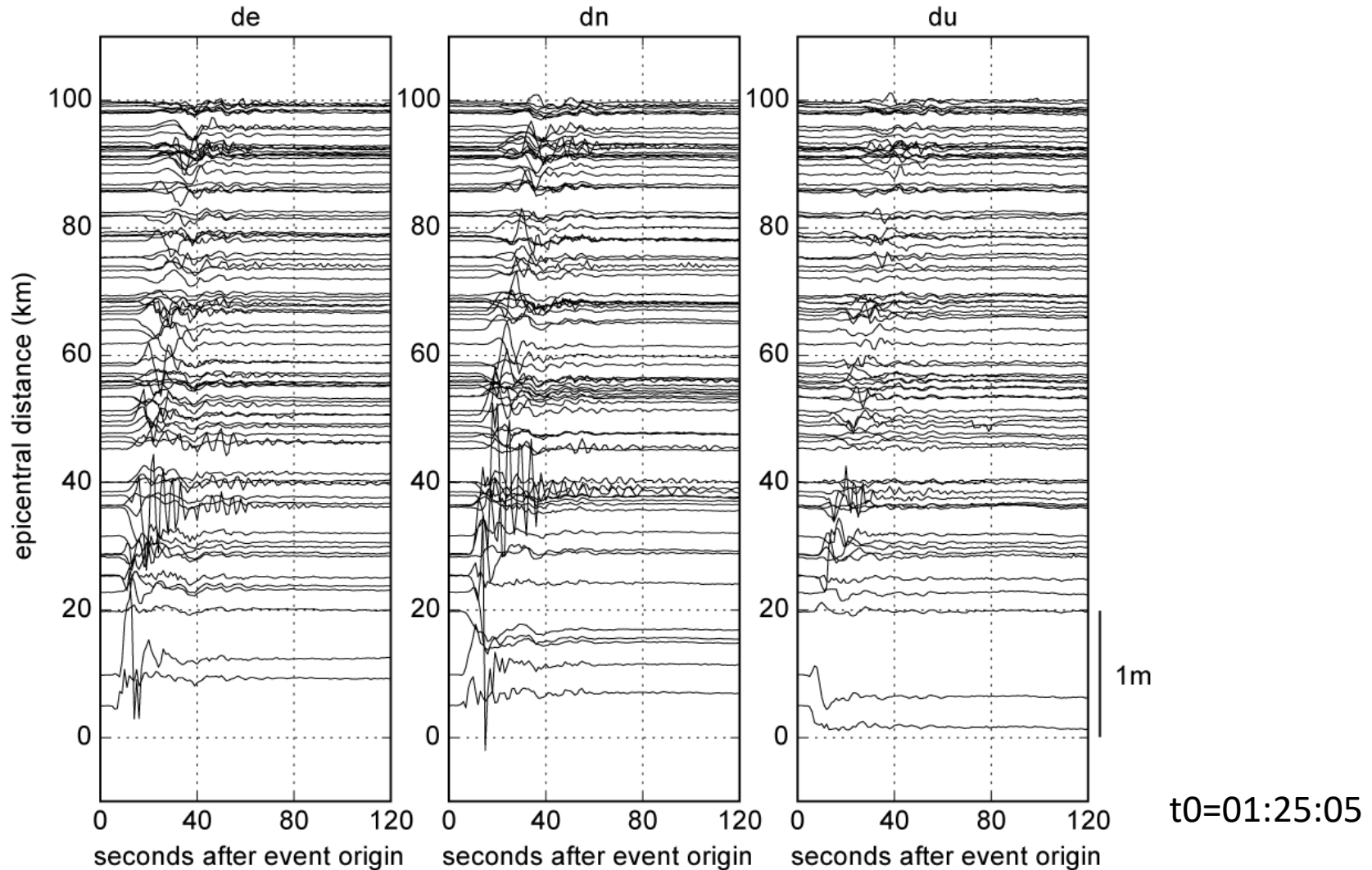
Massive landslide



4/16 Mw7.0

- Two large foreshocks (M6.5 on April 14, M6.4 on April 15)
- **The mainshock (M7.3)** caused significant damage
- NE-SW right lateral strike slip along the Futagawa-Hinagu fault zone

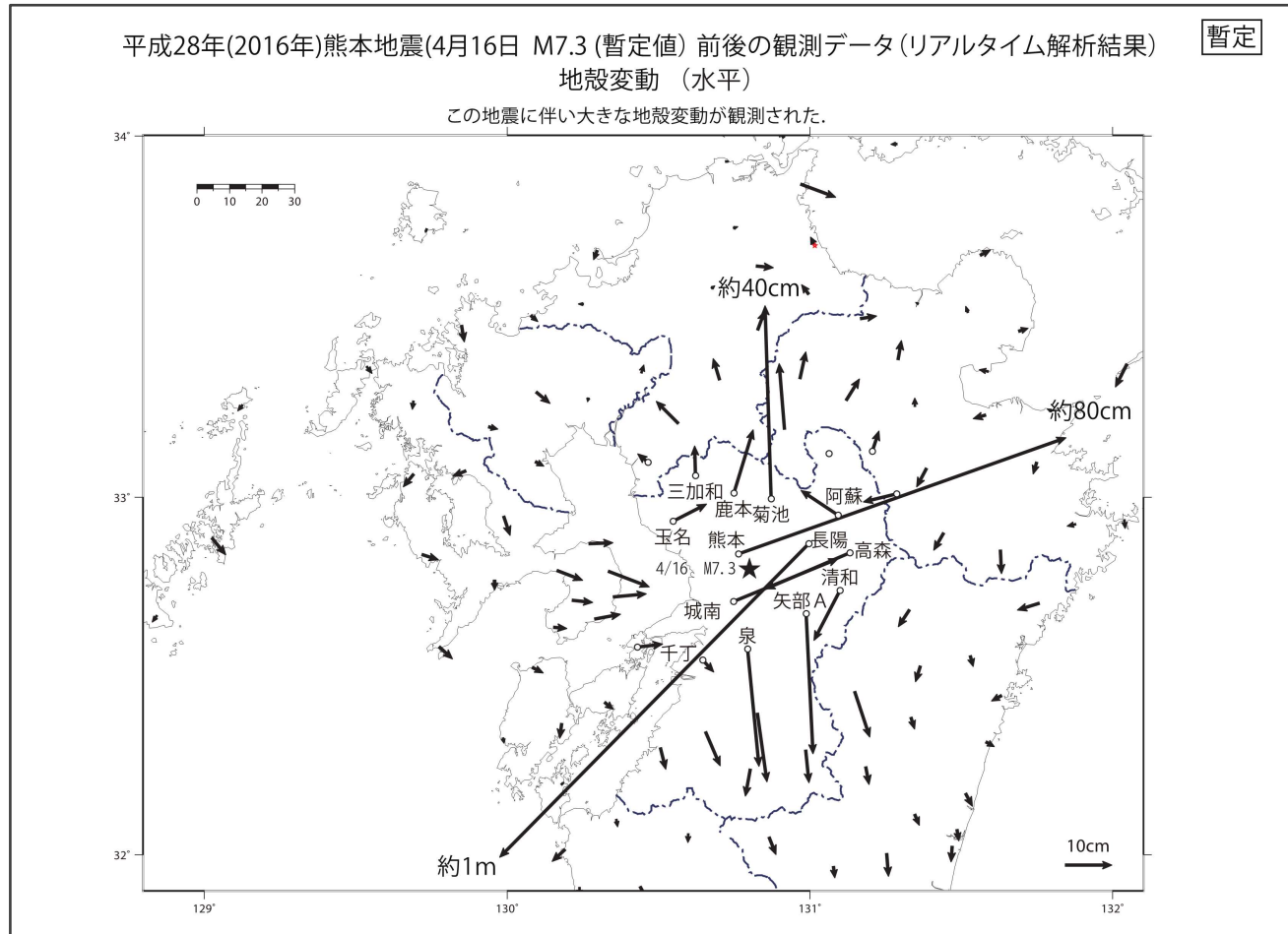
Coseismic displacements by GNSS



Coseismic displacements due to the mainshock

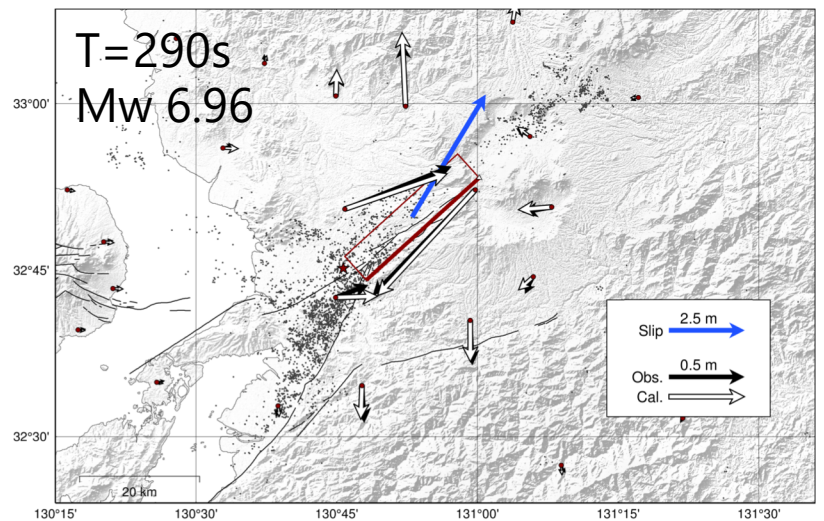
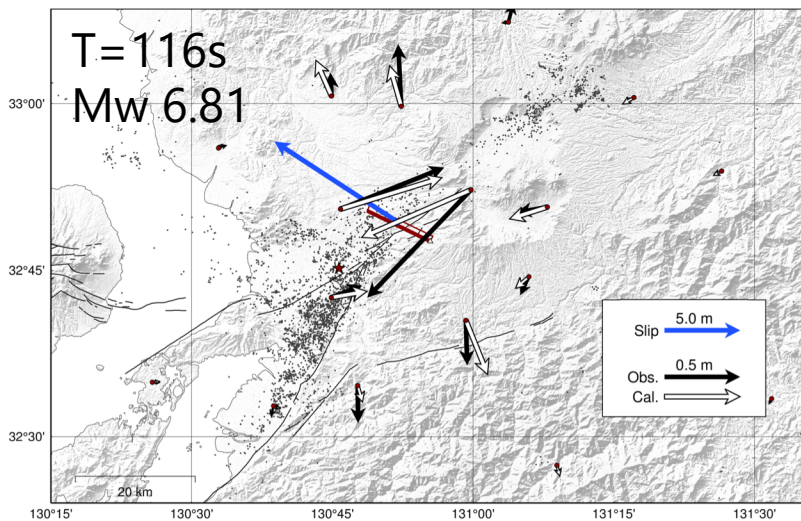
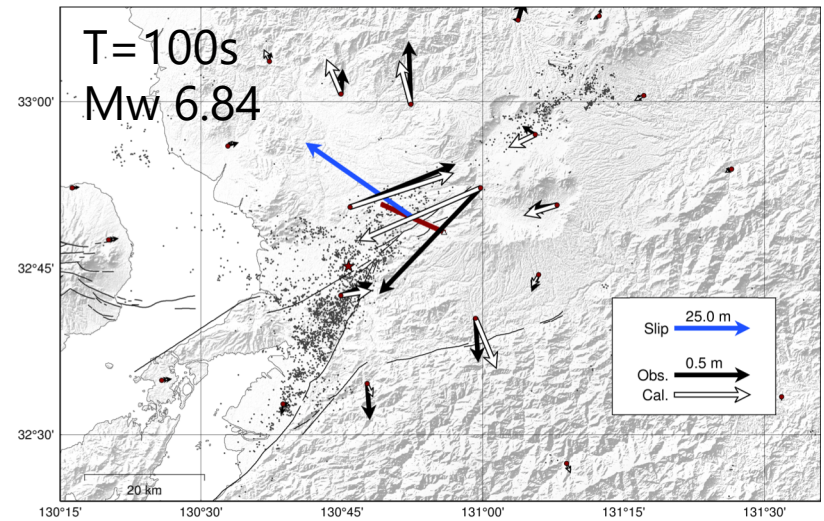
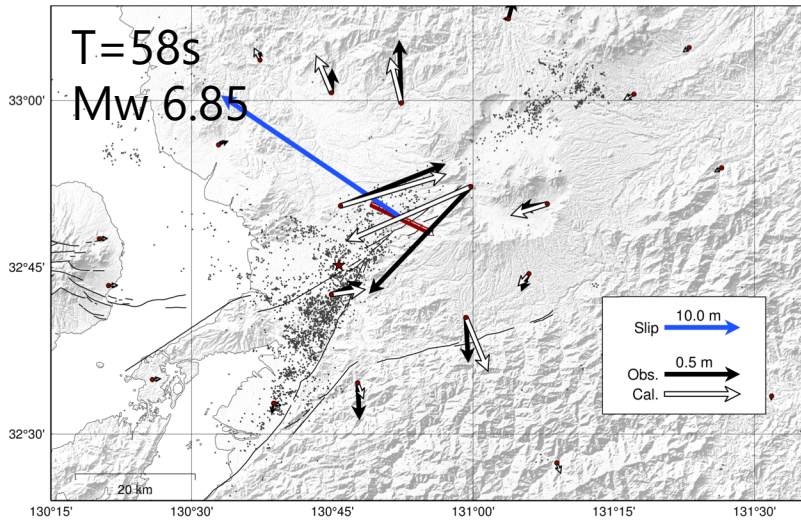
20

Significant horizontal displacements of up to 1m

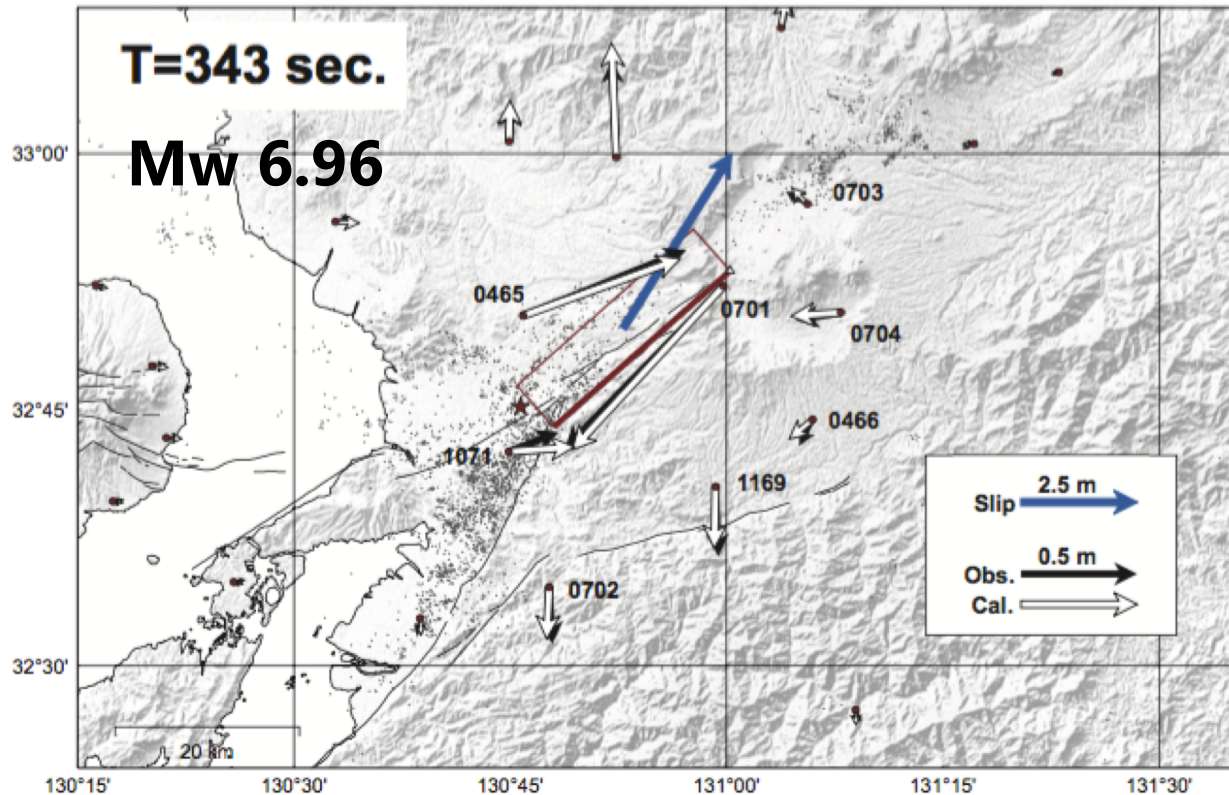


Observed displacements published on the GSI website

Real-time inversion results

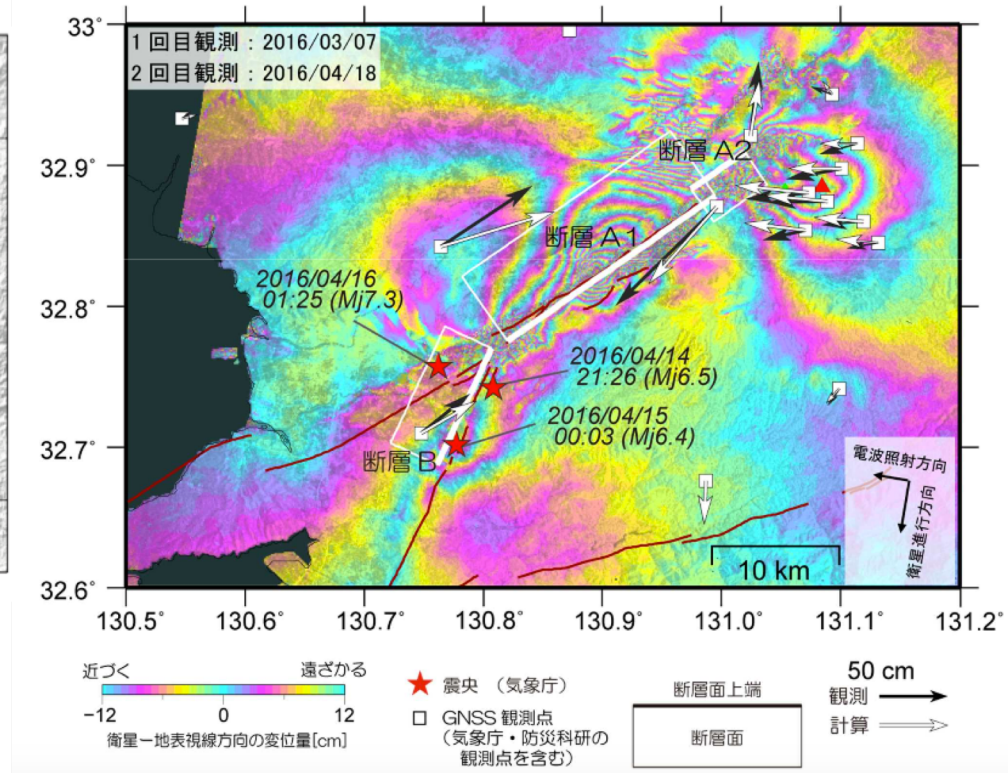
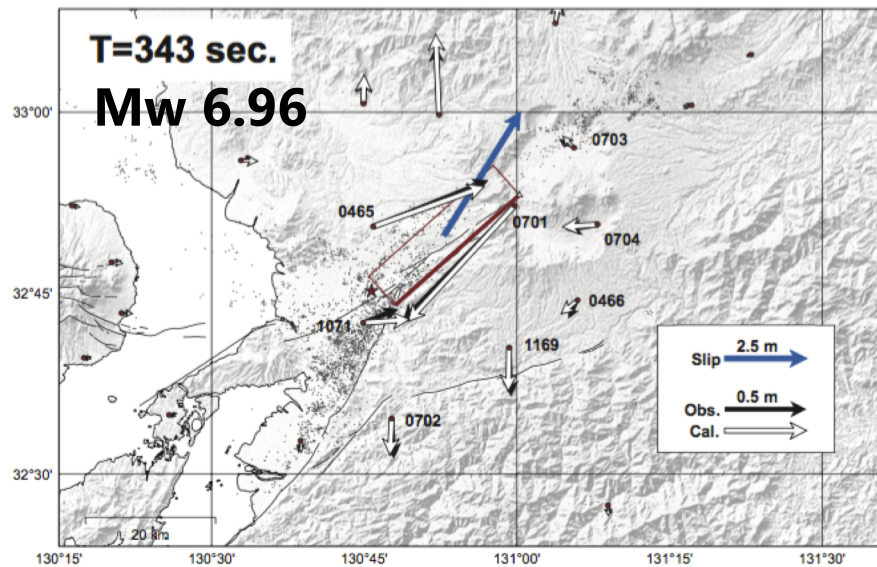


Final model for Kumamoto EQ (Mw 7.0)



Provided right-lateral slip fault model along the Futagawa fault segment **within ~5 minutes**

Final model vs post-processed model



<http://www.gsi.go.jp/common/000140781.pdf>

Consistent with the post-processed fault model inferred from GNSS and InSAR data

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Conclusion

Development of REGARD system

- Implements RTK-GNSS at 1,200+ sites
- Provides finite fault estimates within **3 minutes**
- successfully **provided accurate fault model for the 2016 Kumamoto earthquake in real-time**

For more robust system...

- **Multi-GNSS products** (ultra-rapid or real-time orbit) are important for more accurate positioning
- Implementation of PPP for redundancy

Related works:

- Ohta et al. (2012), Quasi real-time fault model estimation for near-field tsunami forecasting based on RTK-GPS analysis: Application to the 2011 Tohoku-Oki earthquake (Mw9.0), JGR.
- Kawamoto et al. (2016), First result from the GEONET real-time analysis system (REGARD): the case of the 2016 Kumamoto Earthquake, Earth, Planets and Space.
- Kawamoto et al. (2017), REGARD: A new GNSS-based real-time finite fault modeling system for GEONET, JGR.