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Real-time orbit and clock products at Wuhan University to support Multi-GNSS applications

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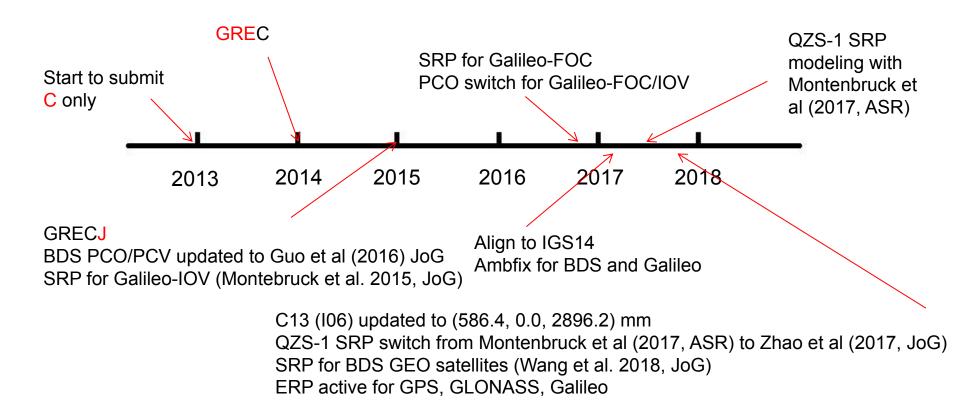
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Collaborative Innovation Center of Geospatial Technology, Wuhan University, China
School of Geodesy and Geomatics, Wuhan University, China





• IGS MGEX Multi-GNSS products of Wuhan University (WUM)







- iGMAS Multi-GNSS products of Wuhan University
 - ultra-rapid, rapid, and final orbits, clocks, and ERP
 - the products are available at ftp://igs.gnsswhu.cn/pub/whu/MGEX/

Project

Multi-GNSS analysis at Wuhan University: attitude, solar radiation pressure, phase center, and more

🔮 Jing Guo · 🛞 Qile Zhao · 🌒 Chen Wang · <u>Show all 6 collaborators</u>

Goal: We aim to obtain and broaden our knowledge about the characteristics of GPS, GLONASS, and the newly developing GNSS systems, e.g., Galileo, BeiDou, QZSS, and NAVIC. Yaw attitude, solar radiation pressure, and phase center correction are those we focus on in order to provide...

Show details





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 - ultra-rapid, rapid, and final orbits, clocks, and ERP
 - the products are avaliable at ftp://igs.gnsswhu.cn/pub/whu/MGEX/
- WHU already provide the real-time orbit and clock for GPS only

STR; CLK15; BRDC_CoM_ITRF; RTCM 3.1; 1059(5), 1060(5); 0; GPS; MISC; CHN; 30.52; 114.35; 0; 1; PANDA; none; B; N; 1800; WUHAN STR; CLK16; BRDC_APC_ITRF; RTCM 3.1; 1059(5), 1060(5); 0; GPS; MISC; CHN; 30.52; 114.35; 0; 1; PANDA; none; B; N; 1800; WUHAN

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 Motivated by iGMAS and Multi-GNSS applications to generate the real-time orbit and clock

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Ultra-rapid orbits

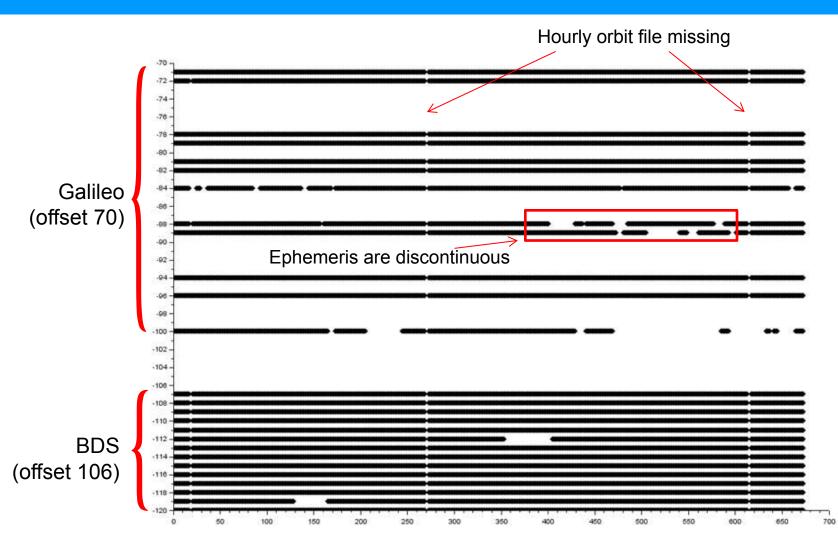
PATHWAYS TO IMPROVED PRECISION

- 6-hour (whu): gweek 1904 to gweek 1909
- 3-hour (whu): gweek 1910 to gweek 1948, and gweek 1975 to now
- 1-hour (whu): gweek 1949 to gweek 1974
- 1-hour (hour): gweek 1975 to gweek 2015
- 1-hour (hour): since gweek 2016



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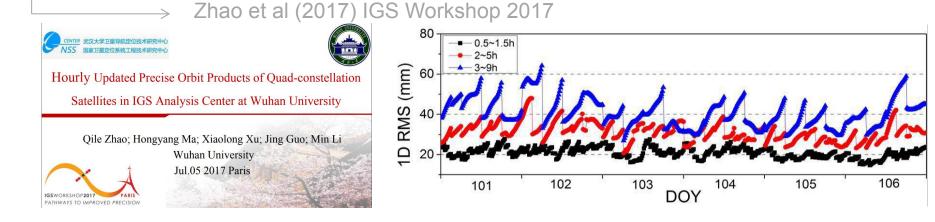




gweek, 1991; Courtesy by Blot Alixis @ CNES



- Ultra-rapid orbits avaliable
 - 6-hour (whu): gweek 1904 to gweek 1909
 - 3-hour (whu): gweek 1910 to gweek 1948, and gweek 1975 to now
 - 1-hour (whu): gweek 1949 to gweek 1974
 - 1-hour (hour): gweek 1975 to 2015
 - 1-hour (hour): since gweek 2016





- Hourly ultra-rapid Multi-GNSS orbits
 - Huge computational burden and time consuming
 - For computation efficiency, Task Parallel mode used
 - ✓ SHAO (Chen et al. 2017): GPS+R/E/C
 - ✓ SGG of WHU (Li et al. 2018): 300s -> 600s, multi-thread for QC, OI, etc.
 - ✓ Other approach?
- Review of the parameter estimation algorithem used in PANDA
 - The efficient data processing strategy proposed by Ge et al. (2006) used in PANDA
 - The iead is to eliminate the non-active parameters in the normal equations to reduce the size
 - "one-by-one" elimination of parameters used



+		 +	++	++
a11	a12	 aln	x1	L1
	a22	 a2n	x2	L2
1		.	. =	1.1
1		• 1	1.1	1.1
1		.	1.1	1.1
1		1	1.1	1.1
1		ann	xn	Ln
+		 +	++	++

Origin Normal Equation

Using block elimination and recovery to instead of "one-by-one" elimination and recovery

Using Cholesky factorization for Matrix inversion

+				+	++	++
a11 .	alj	•	alk	. aln	x1	L1
1				L	x2	L2
			•	. a2n		
		•		.	xj =	= Lj
			•	.	xk	Lk
1				1	.	.
1				ann	xn	Ln
+				+	++	++

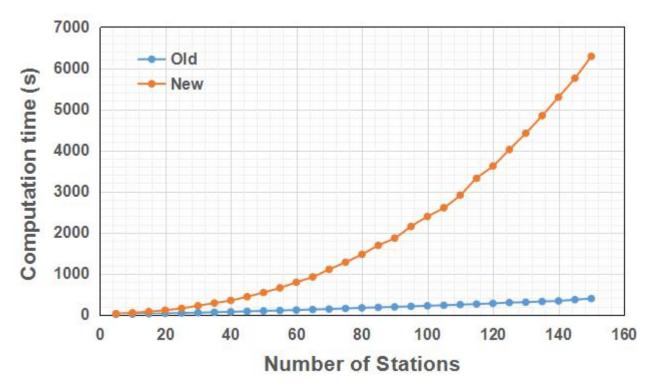
Deactivated parameters elimination

+ a11 	a1j	alk		+ aln 	++ x1	++
	a2j	a2k •	••••	a2n •	xj xk =	Lj Lk
1		•		• 1	1.1	1.
1			•	·	•	·
1				1	1 • 1	•
 				ann	xn	Ln

Deactivated parameters blocked and eliminated

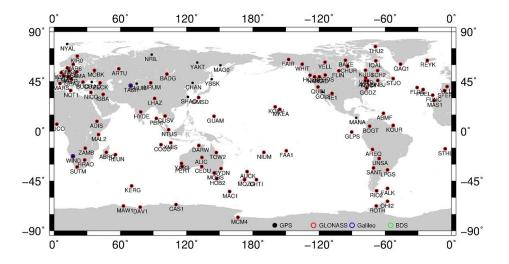


- Computation time (Intel Xeon 16 cores @ 2.9 GHz)
 - GPS+GLONASS





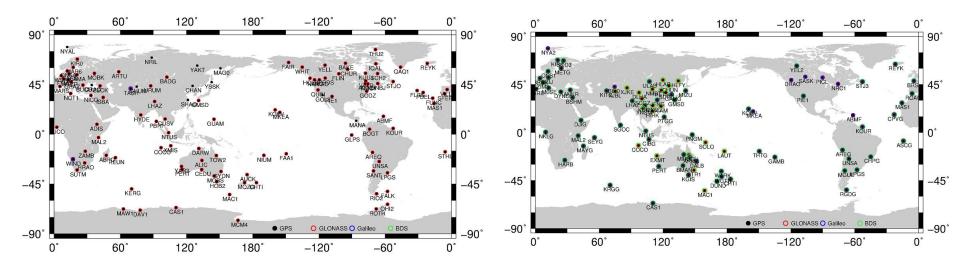
- Strategy
 - 120 stations used for GPS+GLONASS





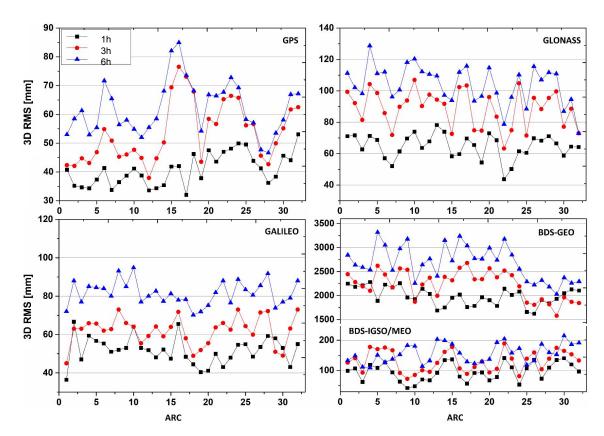
Strategy

- 120 stations used for GPS+GLONASS
- 90 stations used for GPS+BDS+Galileo
- ~30 min for generation of ultra-orbits





- Orbit accuracy
 - GPS/GLONASS (IGS final), Galileo/BDS (GBM)

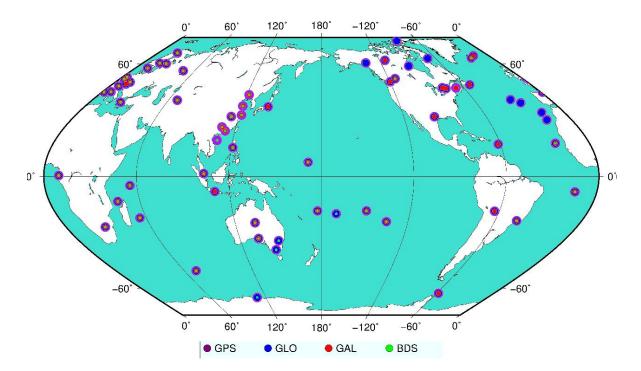


Latency (h)	Ava. Part(h)	Update Freque ncy
1	1-2	1 h
2	2-5	3 h
2	2-8	6 h

		3D	RMS (n	nm)
		1h	3h	6h
GPS		40	53	59
GLS		65	89	104
	G	1987	2224	2678
BDS	I/ M	95	133	157
GAL		51	65	82

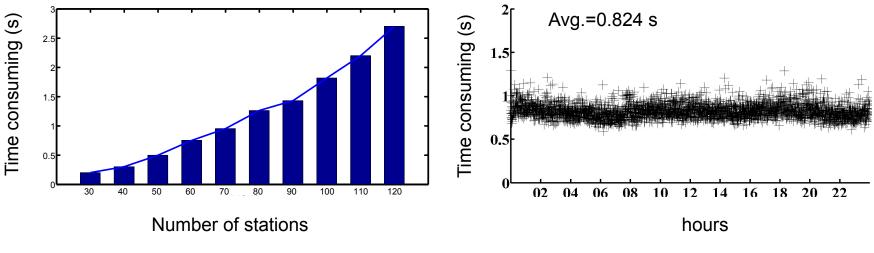


- Squre-root Information Filter (SRIF)
- Using lonosphere-Free (IF) observables
- 70 stations, 5s sampling
- GPS (32)/GLONASS (24)/Galileo (12)/BDS-2 MEO and IGSO (9)





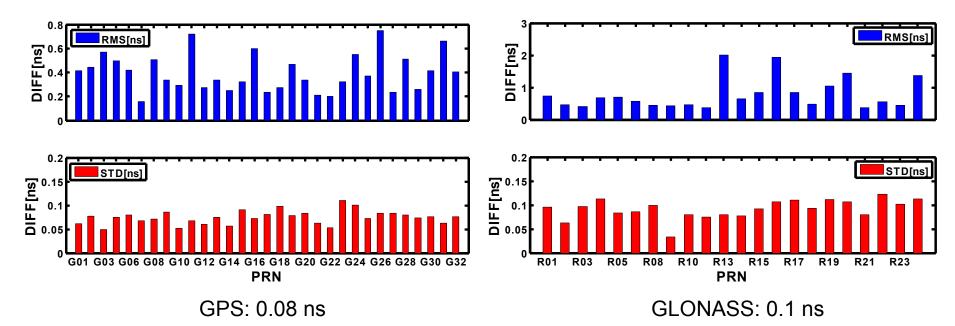
- An efficient algorithm for SRIF
 - Blocked QR factorization (Gong et al. 2017)
 - LAPACK Library for matrix operations



⁽Intel Xeon 4 cores @ 3.5 GHz)

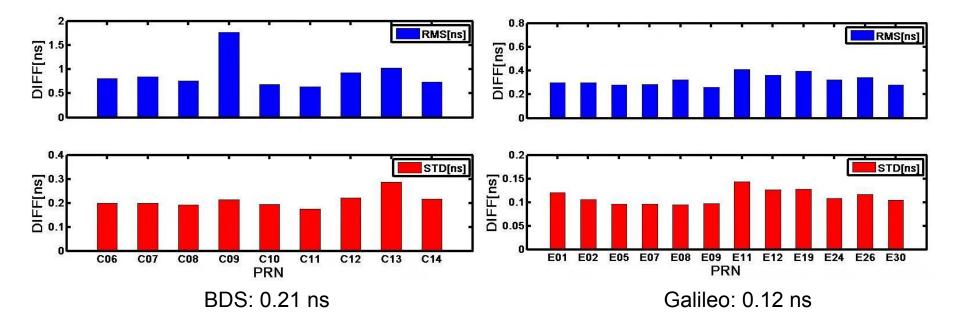


- Accuracy (DOY281 to 298, 2018)
 - WUM clocks used as the reference





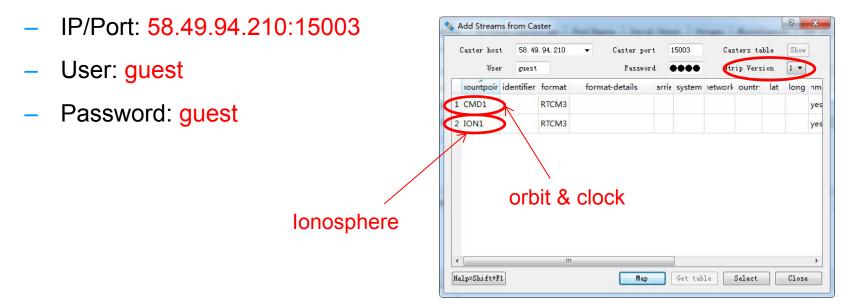
- Accuracy (DOY281 to 298, 2018)
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Real-time products



SSR corrections (APC) for orbit and clock is broadcasted vis



Real-time products



- SSR corrections (APC) for orbit and clock is broadcasted vis
 - IP/Port: 58.49.94.210:15003
 - User: guest
 - Password: guest
- IOD (Issue of Data) calculation
 - GPS: IODE
 - GLONASS: NINT(SOD/900)+1
 - Galileo: NINT(SOD/600)+1
 - BDS: NINT(SOD/1800)+1

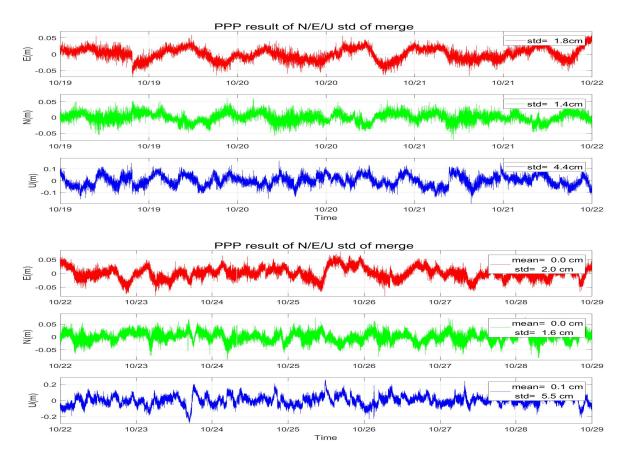
Second of Day (SOD) is in GPS Time

0	Caster hos	t 58.49	9.94.210	•	Caster por	t 1	15003	Cas	ters tal	ble	Show	
	Vsei	r guest			Passwor	a (Ntr	ip Vers	ion	1 🔻	
	ountpoir	identifier	format	format	-details	arrie	system	network	ountr	lat	long	n
1	CMD1		RTCM3									y
2	ION1		RTCM3									y

Validation



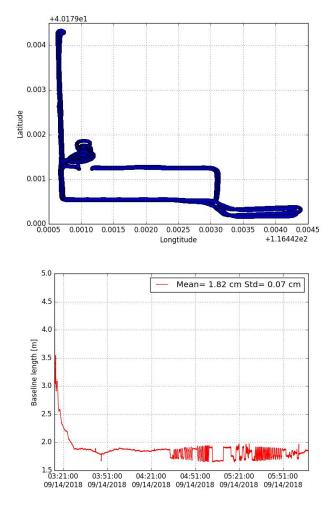
Static station in Wuhan



Validation







Summary and outlook



- WUM product keep to incorporate the new satellites, models or algorithem
 - BDS-3 and QZSS will be supported
 - Yaw attitude model for Galileo, BDS-2/BDS-3
- New hourly ultra-rapid orbits has been released with better quality (stability, accuracy), thanks to the improved computation efficiency by using block elimination
- With blocked QR factorization for SRIF, real-time clock with good performance by using IF observations is determined within limted time
- The real-time products are ready for evaluation and use



Thanks for your attentain!