

Improved Precise Orbit Determination by use of highly accurate clocks

I. Selmke¹, U. Hugentobler¹, E. Schönemann², W. Enderle²

¹ *Institute for Astronomical and Physical Geodesy, Technische Universität München, Munich, Germany*

² *European Space Operations Centre, Navigation Support Office, Darmstadt, Germany*

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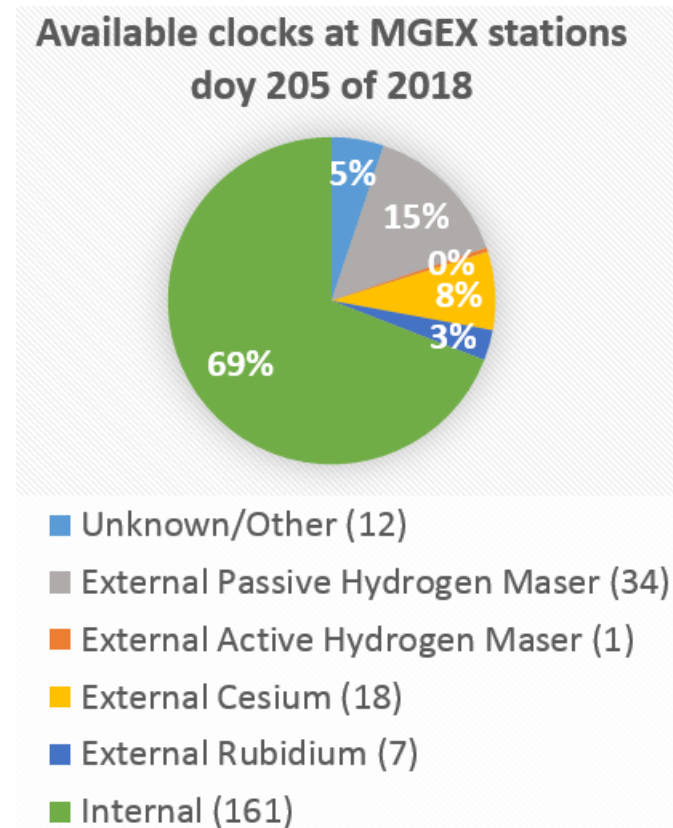
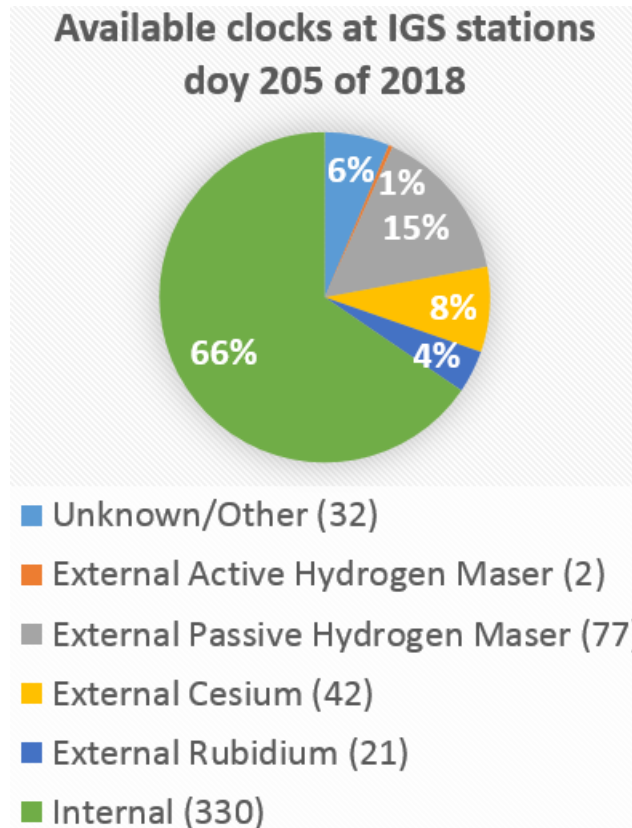
Introduction

- Measurement principle: One-way travel time of the respective signals from satellite to receiver
- High-quality satellite atomic clocks and their predictability are key to achieve highest accuracy for precise real-time applications of GNSS
- State-of-the-art precise GNSS applications:
 - Epoch-wise clock correction estimation
 - High Degree of Freedom
 - Possible weakening of parameter estimation

Introduction

- More and more highly accurate clocks available (eg. Passive Hydrogen Masers on Galileo satellites)
 - ⇒ Model clocks in a physical meaningful way
 - ⇒ Constrain epoch-wise estimated clock parameters to an a priori clock model
- Better estimates of global parameters (orbits, ERPs)
- Better decorrelation and estimates of high-sampled parameters
- Better orbit prediction

Receiver clocks



⇒ Ca 15 % Hydrogen Masers in IGS/IGS-MGEX network

Satellite clocks

GNSS	Block	Rb	Cs	PHM
GPS	I	3	0-1	-
	IIA	2	2	-
	IIR/IIR-M	3	-	-
	IIF	2	1	-
	III	3	-	-
GLONASS	I	v	-	-
	II	(v)	v	-
	M	-	3	-
	K1	v	v	-

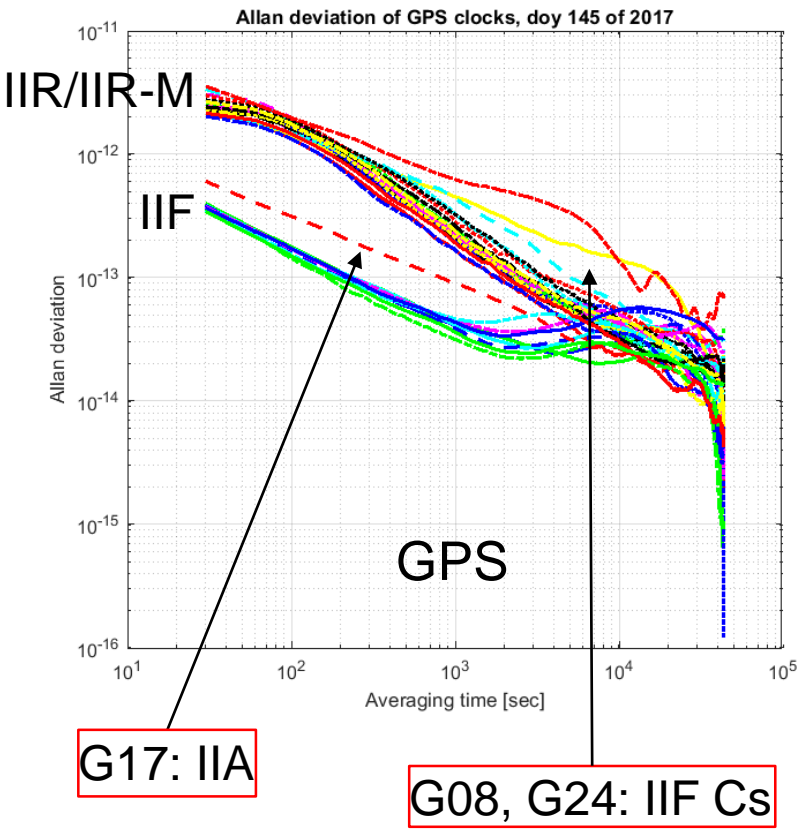
GNSS	Block	Rb	Cs	PHM
Galileo	GIOVE-A	2	-	-
	GIOVE-B	2	-	1
	IOV/FOC	2	-	2
	III	v	-	v
BeiDou	C104/C105	v	-	v
	other	v	-	-
QZSS		2	-	-
IRNSS		v	-	-

Decommissioned

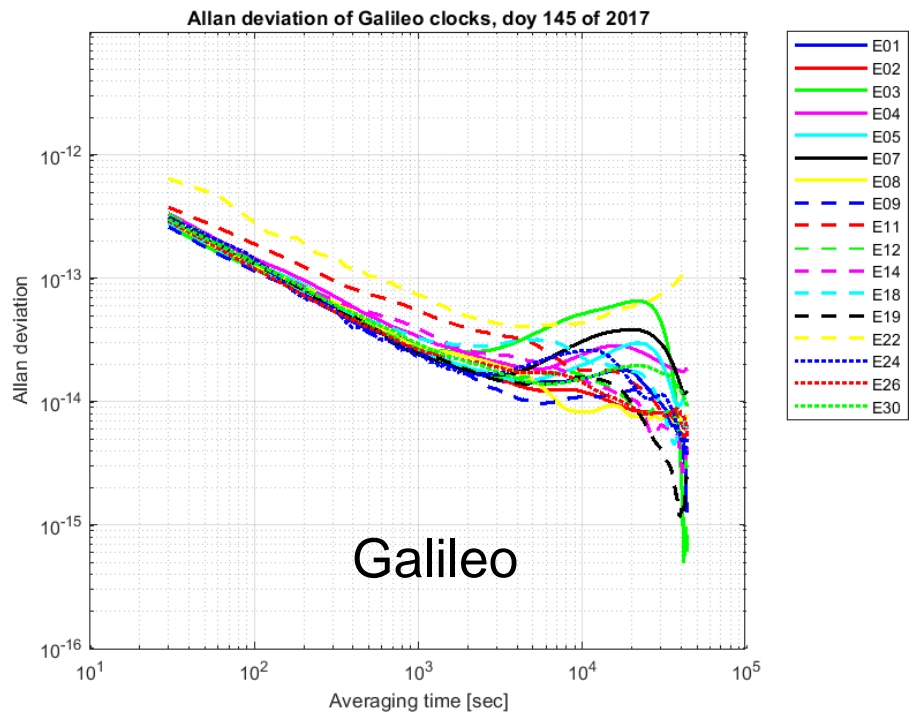
Operational/launched

Planned

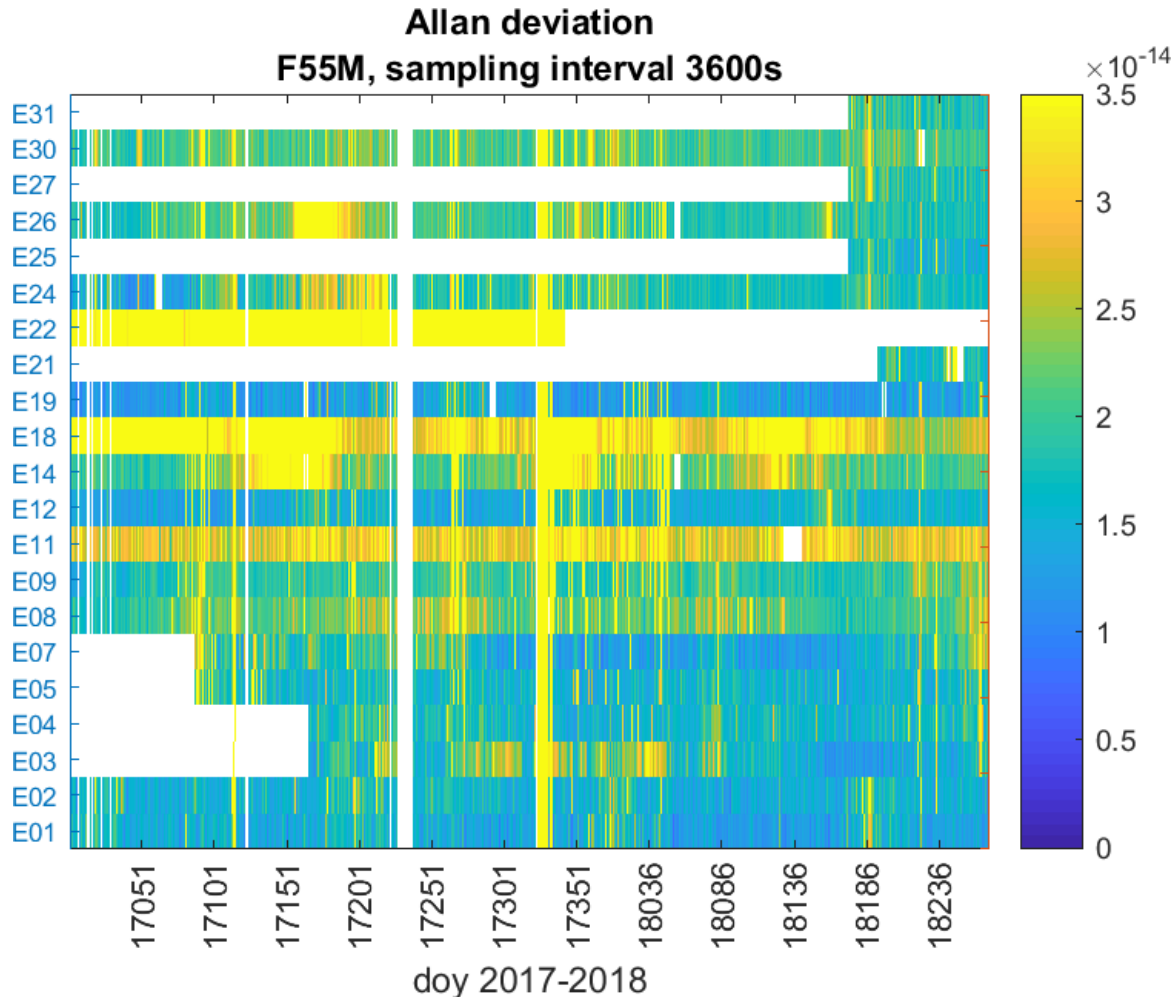
Allan deviation



- G01
- G02
- G03
- G05
- G06
- G07
- G08
- G09
- G10
- G11
- G12
- G13
- G14
- G15
- G16
- G17
- G18
- G19
- G20
- G21
- G22
- G23
- G24
- G25
- G26
- G27
- G28
- G29
- G30
- G31
- G32



Allan deviation



- ADEV sampling interval 3600 sec
- From TUM Galileo clocks
- Selection criteria for Galileo clock modelling

Clock modelling

- **Deterministic clock model:**

- „lin“: $\delta t(t) = a_0 + a_1(t - t_0)$

- „lin/quad“: $\delta t(t) = a_0 + a_1(t - t_0) + a_2(t - t_0)^2$

- „lin/2rev“: $\delta t(t) = a_0 + a_1(t - t_0) + c_2 \cos 2nt + s_2 \sin 2nt$

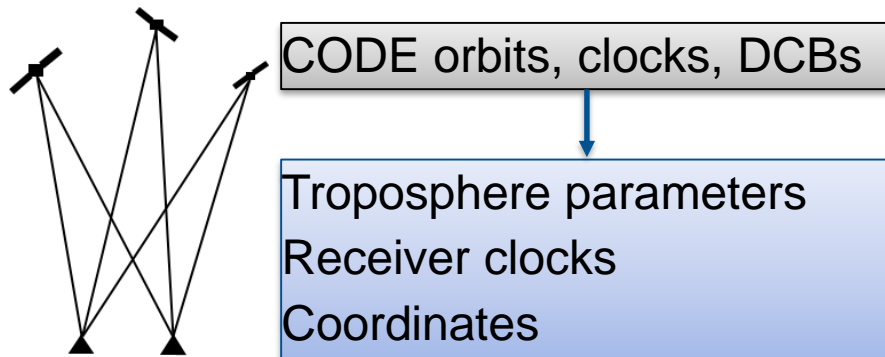
- **Stochastic clock model:**

- **Absolute constraining** of the epoch-wise estimated clock corrections to the selected deterministic a priori clock model

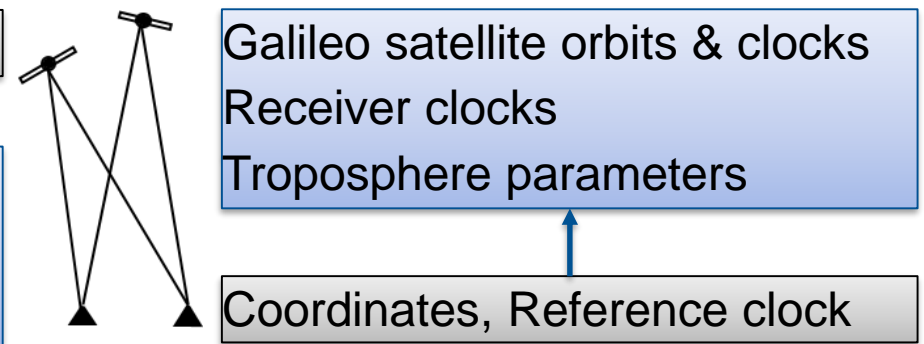
- The clock constraints are tested between 10ns and 1ps

Scenarios

1): GPS-only PPP



2): Network solution

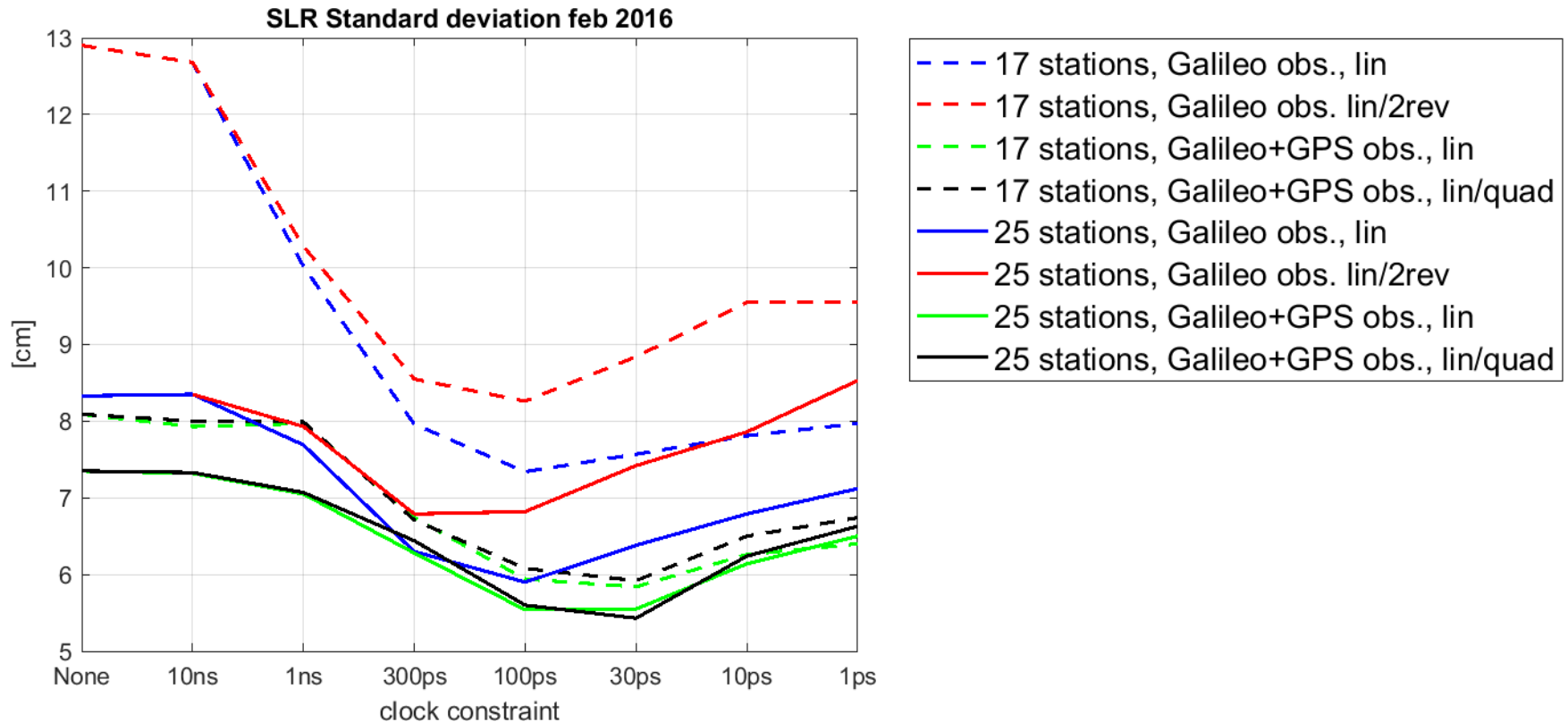


Test Scenarios covering different

- Clock models and clock constraints
- Radiation pressure models
- Network sizes
- GNSS observations

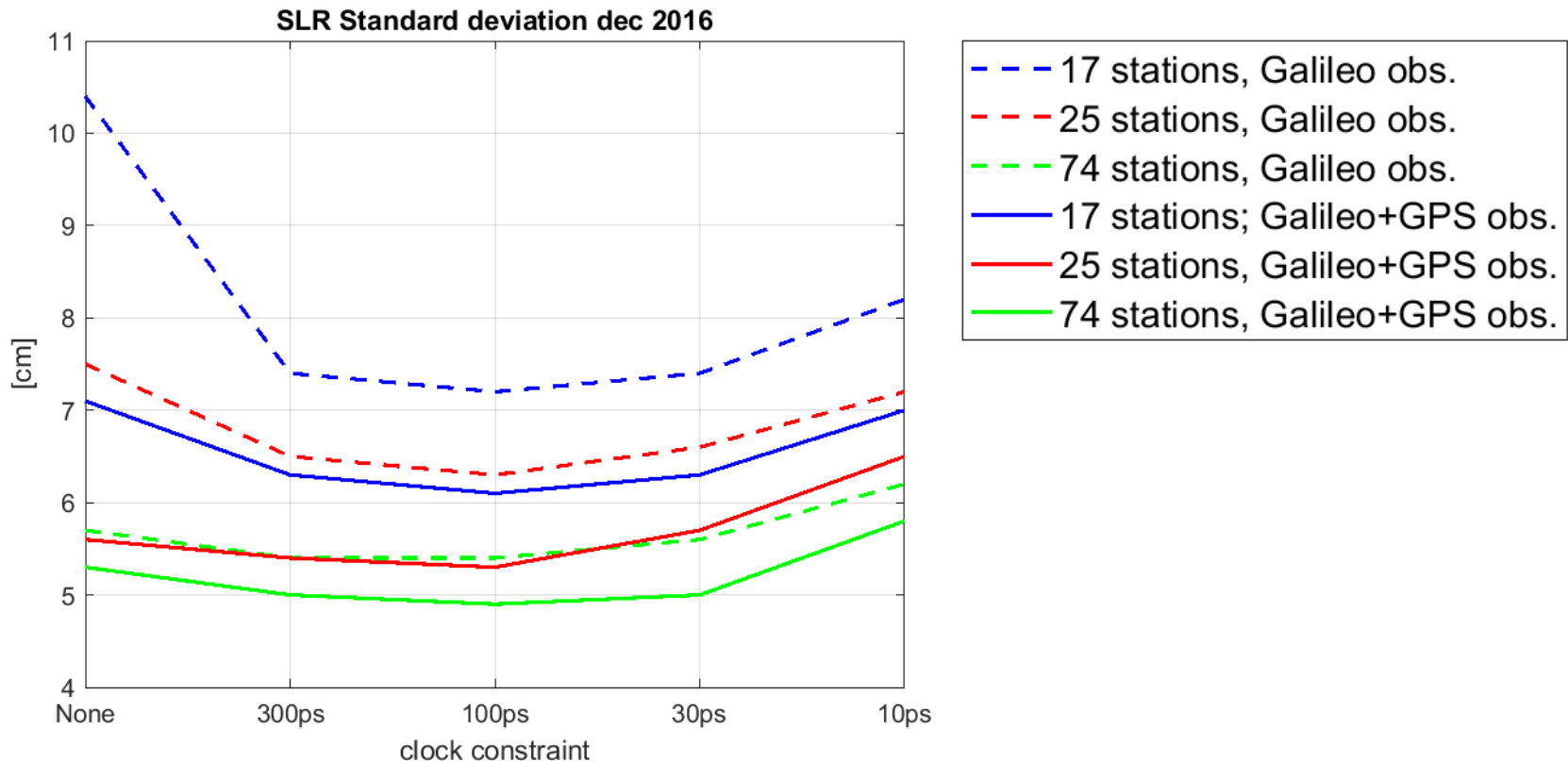
SLR: Clock model

Standard deviation for different clock models:



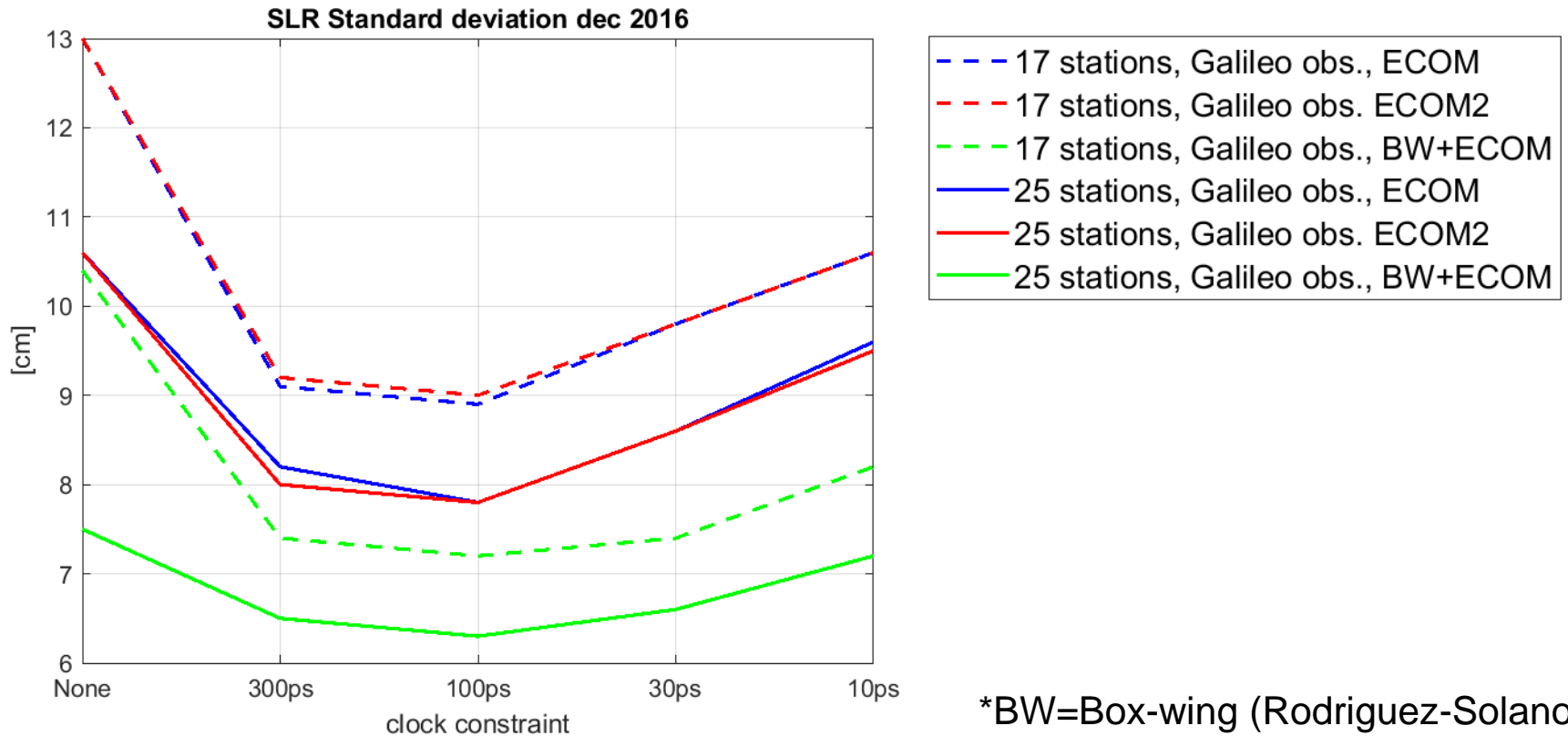
SLR: Network size

Standard deviation for different network sizes



SLR: Radiation pressure models

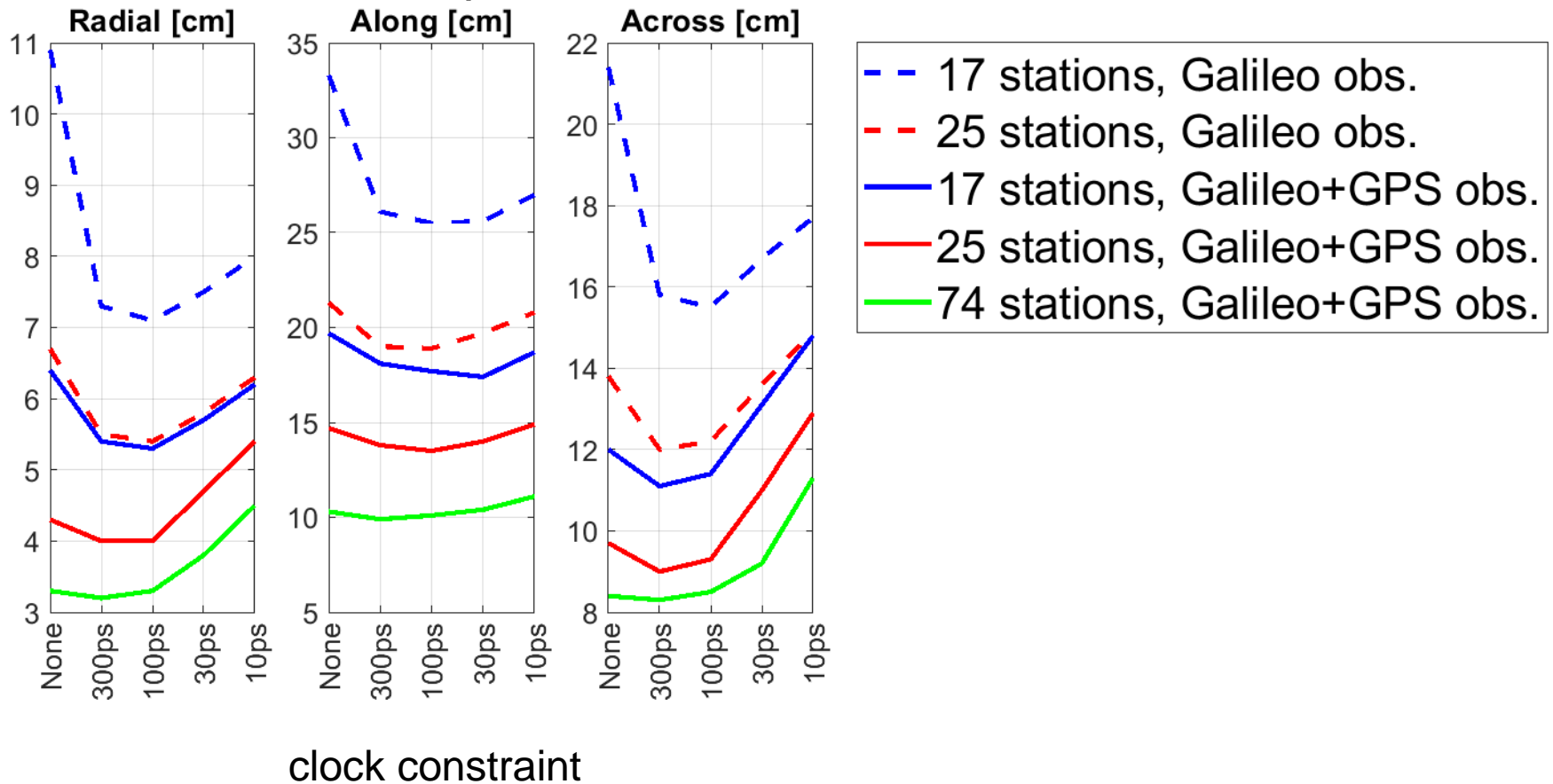
Standard deviation for different radiation pressure models



*BW=Box-wing (Rodriguez-Solano et al., 2012)

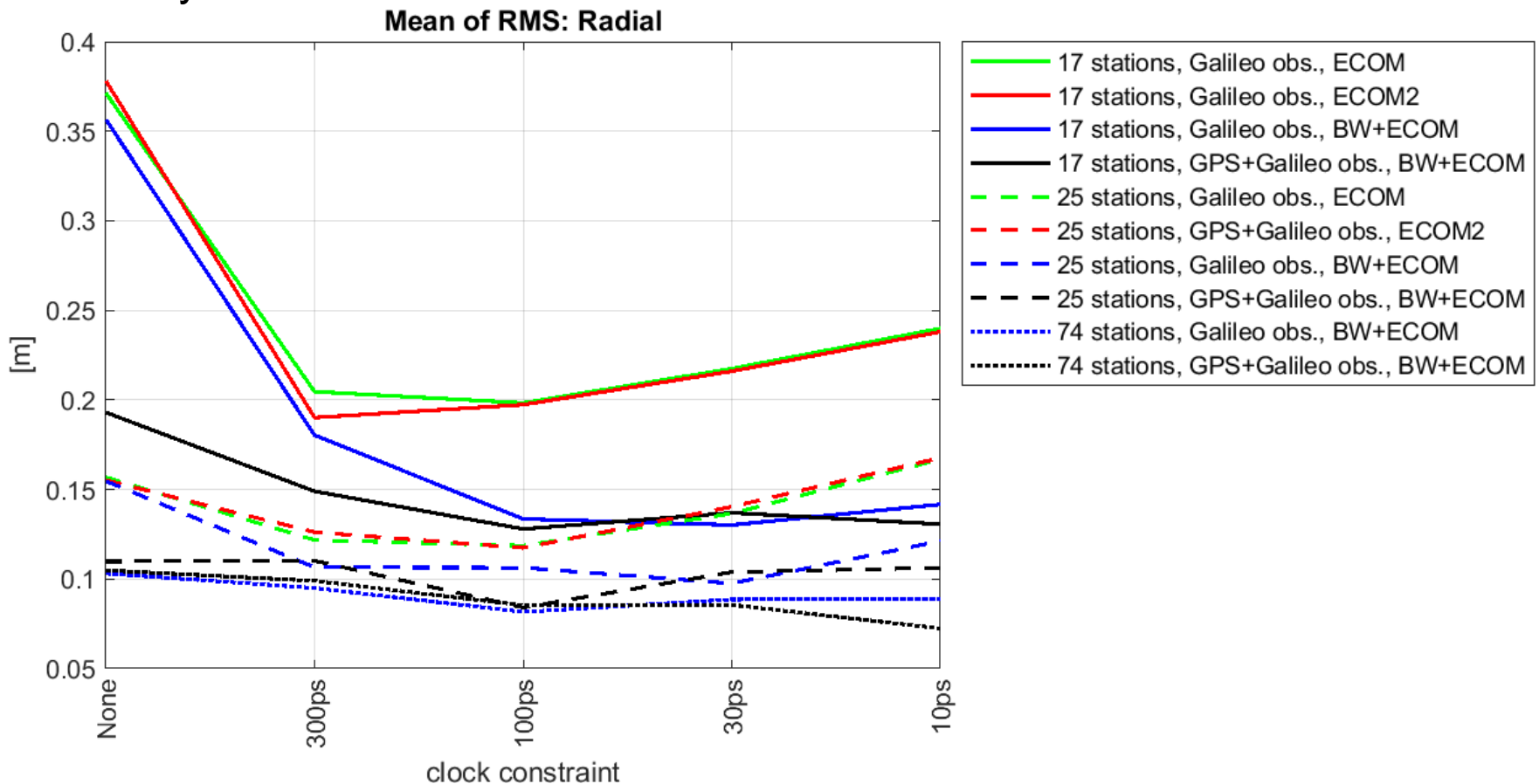
Orbit comparison

Standard deviation of orbit comparison with esoc - 2016dec



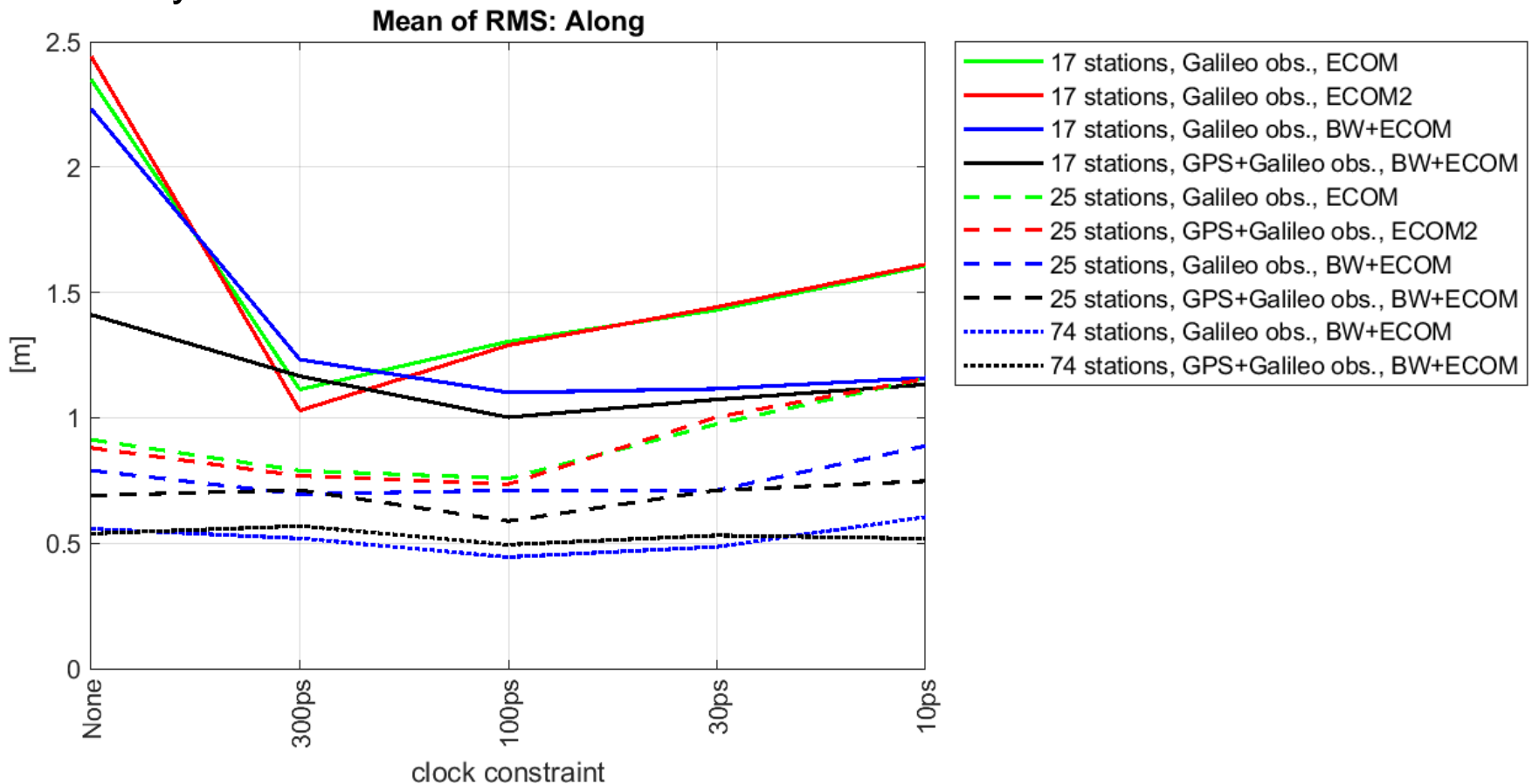
Orbit prediction: Radial

Mean of all satellites of RMS of orbit prediction vs. fitted orbit of next day over one month:



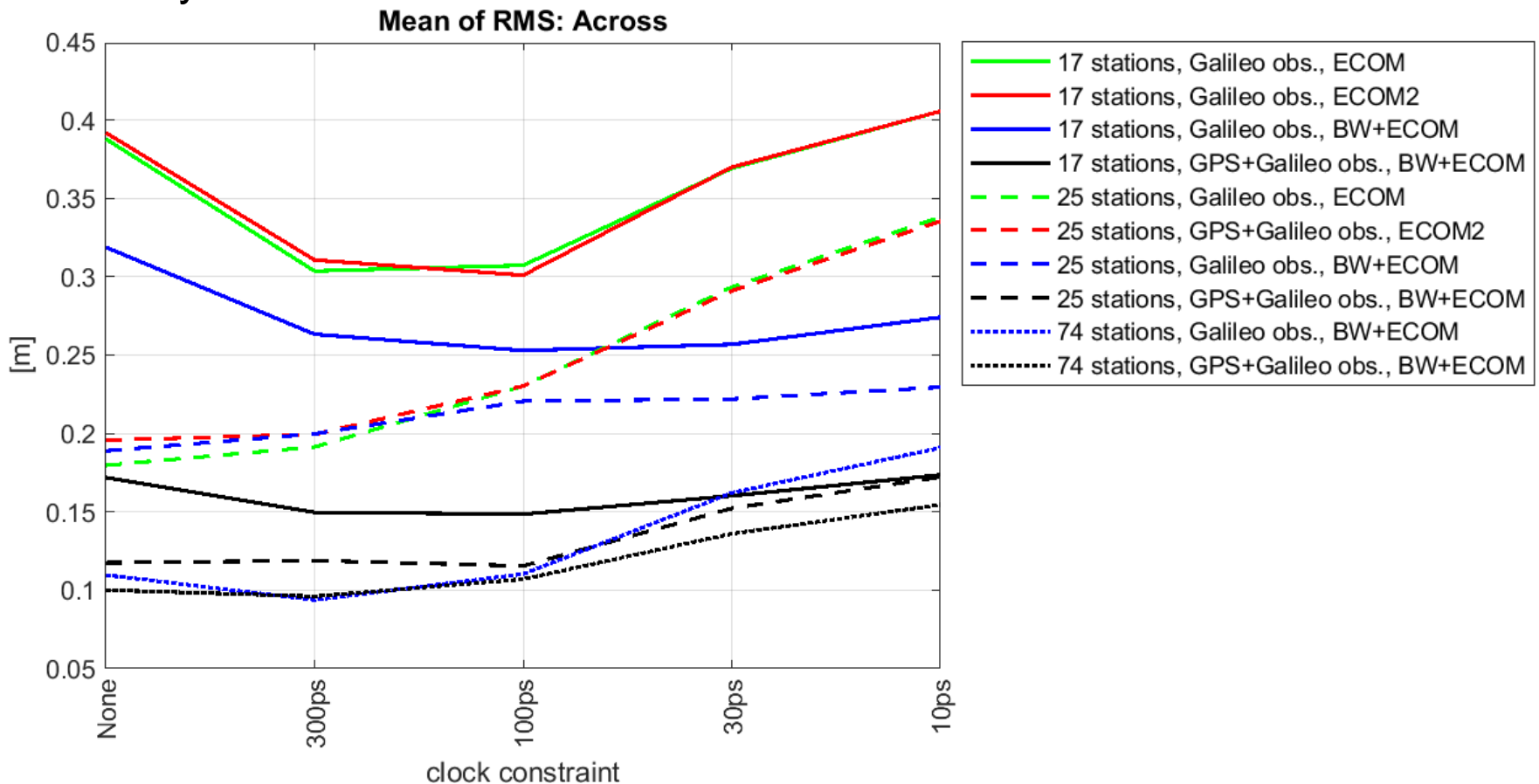
Orbit prediction: Along-Track

Mean of all satellites of RMS of orbit prediction vs. fitted orbit of next day over one month:



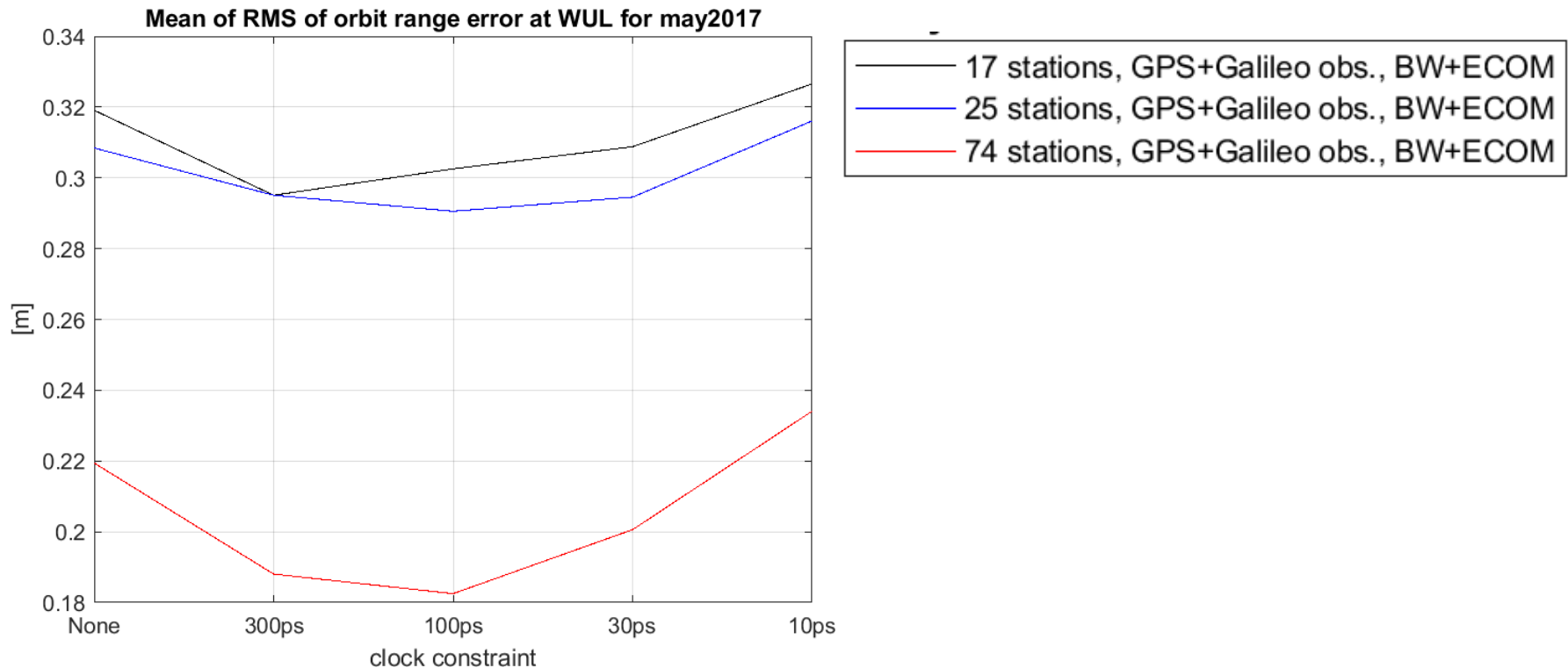
Orbit prediction: Across-Track

Mean of all satellites of RMS of orbit prediction vs. fitted orbit of next day over one month:



Orbit prediction: WUL

Mean of RMS of orbit range error at **Worst User Location** for different networks sizes and clock constraints



Summary

- All conducted test scenarios show improvements with absolute clock modelling constraints for Galileo PHMs applied
- Simple linear clock model already sufficient
- Optimal constraints between 30-300 ps depending on the solution
- Clock modelling especially beneficial for small networks
- Orbit prediction improves similarly

Thank you for your attention!
