

NATURAL RESOURCES CANADA - INVENTIVE BY NATURE

High rate GPS and GLONASS observations of RT-IGS network to monitor ionospheric irregularities and TEC mapping

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Outline

- Ionospheric monitoring using RT-IGS network at NRCan
- Monitoring ionospheric irregularities using dual frequency GPS and GLONASS phase measurements
- Receiver and constellation dependent background phase noise
- NRT global TEC mapping and forecast
- Summary and conclusions





Ionospheric monitoring using RT-IGS network at NRCan



Monitoring ionospheric irregularities using dual frequency GPS and GLONASS phase measurements

At the Canadian Geodetic Survey of NRCan, 1 Hz phase measurements are used to derive indices over 30 sec intervals as follow:

$$sDPR = \frac{\sqrt{\left|\left(\frac{d(l_g(L_1, L_2))}{dt}\right)^2\right| - \left(\frac{d(l_g(L_1, L_2))}{dt}\right)^2}{m(e)}}$$

$$I_g: \text{ Geometry-free combination}$$

$$m(e): \text{ An elevation angle } (e) \text{ dependent mapping function}$$

$$GPS:$$

$$L_1: L1C$$

$$L_2: L2W$$

$$GLONASS:$$

$$L_1: L1C$$

$$L_2: L2P$$

Experiments at collocated stations to study the impacts of:

- Constellation (GPS vs. GLONASS)
- Receiver type

Station and constellation specific de-trending of sDPR





Real-time IGS network station specific background inter-frequency GPS phase rate noise by means of daily mean sDPR during March 16 (quiet day) and March 17 (stormy day), 2015

b)

b



| Representative name used in figures (a and b) | Receiver types | Number of receivers contributed in Mar 17, 2015 |
|--|-------------------|---|
| JAVAD | TRE_G3TH DELTA | 15 |
| ACT | AOA BENCHMARK ACT | 11 |
| | AOA SNR-12 ACT | 1 |
| LEICA | GRX1200GGPRO | 15 |
| | GRX1200+GNSS | 2 |
| | GRX1200 | 1 |
| | GR25 | 4 |
| | GR10 | 4 |
| TPS | NET-G3A | 21 |
| | NETG3 | 1 |
| | E-GGD | 1 |
| TRIMBLE | NETR5 | 6 |
| | NETR8 | 5 |
| | NETR9 | 25 |
| | NETRS | 26 |
| SEPT | POLARX2 | 1 |
| | POLARX4 | 5 |
| | POLARX4TR | 1 |
| ASHTECH | UZ-12 | 1 |
| | Z-X | 1 |
| | Z-XII3 | 2 |
| | Z-XII3T | 2 |



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Receiver and constellation dependent background phase noise



| (Lat: 62.481 Lon: -114.481) | | | | |
|-----------------------------|-------------------------|----------------|--|--|
| Station | Receiver type | Antenna type | | |
| YE2L | JAVAD TRE_G3TH SIGMA | AOAD/M_T | | |
| YEL3 | TPS NET-G3A | TWIVP6050_CONE | | |
| YELL | JAVAD TRE_3N DELTA | AOAD/M_T | | |

Co-located GNSS stations at Yellowknife, Canada

Daily min and max diff from mean (58271.5 nT) of the intensity of magnetic field at Yellowknife



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Receiver and constellation dependent background phase noise: RT-IGS stations



Receiver types contributed both GPS and GLONASS in studies presented here

| Representative name used in this presentation | Receiver types | Number of receivers |
|--|----------------|------------------------|
| JAVAD | TRE_G3TH DELTA | 20 |
| | TRE_G3TH SIGMA | 2 |
| | TRE_3 DELTA | 2 |
| | TRE_3N DELTA | 1 |
| LEICA | GRX1200GGPRO | 8 |
| | GRX1200+GNSS | 3 |
| | GR25 | 9 |
| | GR10 | 2 |
| SEPT | POLARX4 | 8 |
| | POLARX5 | 5 |
| | POLARX4TR | 6 |
| | POLARXS | 2 |
| TPS | NET-G3A | 24 |
| TRIMBLE | NETR3 | 1 |
| | NETR5 | 2 |
| | NETR8 | 4 |
| | NETR9 | 20 |



Receiver and constellation dependent background phase noise: RT-IGS stations







Detection of high latitude ionospheric irregularities using RT-IGS stations



GPS and GLONASS IPPs from RT-IGS stations with gmag lat > 55 deg during March 27, 2017 (DoY 86), a day with moderate geomagnetic disturbances.



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Auroral Electrojet Index

Percentage of occurrence of large (> 4 mm/sec) de-trended sDPR values in bins of 1 UT hour by 5 deg gmag lat; separately for GPS and GLONASS



UT hour of DoY 86, 2017

6

4

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GPS vs. GLONASS phase irregularities in response to geomagnetic field variations



NRT global TEC mapping and forecast



CGS near-real-time global TEC maps use high rate realtime IGS stations every 15 minutes. Forecast for up to 24 hours ahead... Grid forecast model:

$$\hat{g}_{d}^{t_{n}} = g_{d-1}^{t_{n}} + \left[g_{d}^{t_{m}} - g_{d-1}^{t_{m}}\right]_{m=0,\dots,n-1}$$





15 minutes to 24 hours TEC forecast: performance against IGSG and other ACs March 27, 2017





15 minutes to 24 hours TEC forecast: performance against emug (NRCan NRT TEC) March 21 – May 10, 2017



Daily sum of 3-hourly Kp index

15 min to 24 hours forecast vs emug - mean (red) and std (grey) of diff over global grid

DoY 2017





 130

15 minutes to 24 hours TEC forecast: global RMS of difference from emug (NRCan NRT TEC) March 21 – May 10, 2017



During the studied period global RMS (NRT vs. forecast) was below 2 TECU for forecasts up to 45 minutes.



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Summary and conclusions (1)

- At the Canadian Geodetic Survey of NRCan 1 Hz GPS and GLONASS observations from RT-IGS network are used for monitoring ionospheric irregularities and TEC mapping in near-real-time.
- Impact of receiver type and constellation (GPS and GLONASS) on GNSS-derived indices is quantified at stations of RT-IGS network. Inter constellation biases in GNSS derived indices are presented for different receiver categories operating within RT-IGS network using ratio of GPS to GLONASS daily mean sDPR. Even though such a ratio can be dependent on the spatial and temporal distribution of IPPs between two constellations, a clear receiver dependency among all regions and studied periods is observed.
- When GPS and GLONASS phase measurement are used together for detection of ionospheric irregularities, the station specific systematic bias between the two constellations needs to be evaluated and applied before interpretation of results.



Summary and conclusions (2)

- Overall, both GPS and GLONASS responded rather similarly to periods of ionospheric irregularities. Detection of irregularities with small spatiotemporal scales can benefit from multiple constellation due to increased coverage of measurements.
- NRCan's NRT TEC maps are generated from RT-IGS stations every 15 minutes and represented using spherical harmonics.
- A grid forecast method to generate global maps of 15 minute to 24 hours ahead is also implemented and evaluated.



17



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Thank you!

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