Enhancing global PPP with Local Ionospheric Corrections

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Real-time Precise Point Positioning (PPP)

- Autonomous positioning with centimetre-level accuracy
- Relies on products with global validity: satellite orbit and clock corrections and signal biases.
- IGS post-process and real-time products have demonstrated PPP capability
- With ambiguity resolution, can achieve accuracies comparable with RTK



Horizontal accuracy of PPP with floating (blue) and integer (green) ambiguities.

Long convergence times still an issue

Satellite delivered real-time PPP

- Satellite delivery is a natural fit for PPP
- Example using QZSS in Australia
 - Real-time products: Multi-GNSS Advanced Demonstration tool for Orbit and Clock Analysis (MADOCA)
 - RTCM messages for orbit, clock, code bias and accuracy estimates broadcasted using QZSS LEX signal
 - Centimetre level accuracy was verified in both fixed point and kinematic tests
- QZSS coverage includes most of East-Asia and Oceania
- MADOCA products delivered through QZSS L6 has great potential as an infrastructure for the region
- Similar systems can be expected to be developed in the future



Satellite PPP in Precision Agriculture

- IGS real-time orbits
- Clock corrections adjusted using local network
- Signal biases generated using local network
- No lonospheric corrections was transmitted (up to a few hour of convergence time)
- Integrated GNSS PNT and INS was used to guide an autonomous tractor
- Performance similar to short baseline RTK (2 cm horizontal RMS)
- Operated at about 291Km from the network



Local enhancements to PPP

- Challenge: precise lonospheric delay estimation required for rapid convergence
- Global precise lonospheric delay estimations are yet unavailable
- They are impractical for satellite transmission
- Using CORS networks to generate a local supplement to global PPP products:
 - -RTK-like convergence times inside or near network
 - -PPP performance over the wider coverage area
 - Improved accuracy and reliability using adjusted clock corrections and signal bias
- Joint CRCSI (Aus.) and JAXA (Jap.) project is studying Australian enhancement of MADOCA products



Local enhancements to PPP: product calculation

- Ionospheric corrections only (>1 ref. station) $P_{i,st}^{S} - \rho - dt^{S} - B_{i}^{S} = m_{st}^{S}T_{st} + \mu_{i}I_{1,st}^{S} + \epsilon_{i}$ $L_{i,st}^{S} - \rho - dt^{S} - b_{i}^{S} = m_{st}^{S}T_{st} - \mu_{i}I_{1,st}^{S} + \lambda_{i}N_{i,st}^{S} + \epsilon_{i}$
- Phase bias adjustment (≥ 3 ref. stations)

$$P_{i,st}^{S} - \rho - dt^{S} - B_{i}^{S} = m_{st}^{S}T_{st} + \mu_{i}I_{1,st}^{S} + \epsilon_{i}$$
$$L_{i,st}^{S} - \rho - dt^{S} = m_{st}^{S}T_{st} - \mu_{i}I_{1,st}^{S} + b_{i}^{S} + \lambda_{i}N_{i,st}^{S} + \epsilon_{i}$$

• Phase bias and clock adjustment ($\geq 4 \text{ ref. stations}$) $P_{i,st}^{S} - \rho - B_{i}^{S} = dt^{S} + m_{st}^{S}T_{st} + \mu_{i}I_{1,st}^{S} + \epsilon_{i}$ $L_{i,st}^{S} - \rho = dt^{S} + m_{st}^{S}T_{st} - \mu_{i}I_{1,st}^{S} + b_{i}^{S} + \lambda_{i}N_{i,st}^{S} + \epsilon_{i}$

Slant TEC from loose network: a test in Victoria

CNES real-time stream CLK91 used to solve phase ambiguities



STEC estimation at monitor station

- Tests performed between 25th and 26th of November 2015
- Slant TEC was calculated on each station using ambiguity resolved PPP technique
- Slant TEC on 5 monitoring stations were compared with values interpolated/extrapolated from nearby stations
 - -Stations within 200Km were selected
 - Slant TEC was estimated as a linear regression from values on selected stations

$$I_{rc} = I_{st} + dI_{lat}(lat_{st} - lat_{rc}) + dI_{lon}(lon_{st} - lon_{rc})$$

-Using weighted least squares

$$H^T W H \mathbf{I}_{rc} = H^T W \mathbf{I}_{st} \qquad W_{st,st} = (1/dist_{st-rc})^2$$

Estimated STEC accuracy

- RMS of Ionospheric correction errors was 30.5 cm
- Ionosphere errors were dominated by a handful of satellite/station combinations with very large errors.
- 80% of Slant TEC values had less than 10 cm of RMS errors
- RMS discarding the satellite with large errors was 13.0 cm

RNBO

- -#stations used: 9
- –Dist. to stations(Km): 82.1, 82.3, 83.5
- -Ion. Error(cm RMS): 2.32
- -<5cm error: 11/12



Estimated STEC accuracy (cont.)

BALL

- -#stations used: 14
- Dist. to stations(Km): 62.0, 80.5, 90.2
- -Ion. Error(cm RMS): 6.10*
- -<5cm error: 6/9

RUTH

- -#stations used: 7
- Dist. to stations(Km): 54.4, 56.4,79.7
- -Ion. Error(cm RMS): 6.50*
- -<5cm error: 6/10



Estimated STEC accuracy (cont.)

BUCH

- -#stations used: 7
- –Dist. to stations(Km): 54.0, 66.9, 117.7
- -Ion. Error(cm RMS): 15.76
- -<5cm error: 0/12

STRH

- -#stations used: 6
- Dist. to stations(Km): 36.7, 82.9, 95.7
- -Ion. Error(cm RMS): 25.20*
- -<5cm error: 2/9



Slant TEC maps for PPP

- PPP using STEC maps
 - Ionospheric corrections calculated in 117 stations from GPSnet in Victoria
 - Mapped into a 1° lat. × 2° lat. Slant TEC maps
 - 10cm accuracy in a few minutes
 - Significantly reduced ambiguity resolution



Summary and future work

- PPP, specially satellite delivered PPP has potential as positioning infrastructure
- Precise estimate of lonospheric delays is required for instantaneous convergence
- Ionospheric corrections from local networks could be used to enhance global PPP products where infrastructure is available
- Preliminary studies conducted are being conducted using CORS stations in Australia
 - Products from CNES CLK91 were used to calculate PPP solutions for reference stations in Victoria
 - Resulting Ionospheric delay estimates were used to calculate Slant TEC in monitoring stations (average distance to three stations 75Km)
 - -80% of satellites showed less than 10 cm RMS errors
 - -Few satellites show large errors
- Short term objective is the enhancement of real-time MADOCA streams
- Real-time testing to be conducted by September this year

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