



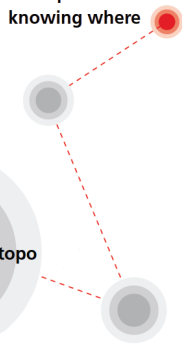
Schweizerische Eidgenossenschaft
Confédération suisse
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Swiss Federal Office of Topography (swisstopo)

AIUB



wissen wohin
savoir où
sapere dove
knowing where



Bias-SINEX Format and Implications for IGS Bias Products

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IGS Workshop on GNSS Biases

IGS INTERNATIONAL
GNSS SERVICE

Main

The next IGS Workshop on GNSS Biases will be organized from **5 to 6 November 2015**. It will be hosted by **AIUB**, the Astronomical Institute, at the University of Bern, Switzerland.

Program

Registration

This workshop is foreseen as a roundtable conference with a limited number of participants (about 40). We will consider this mostly an invitation-only meeting. Issues concerning handling/determination/calibration/consideration of (observable) biases of current GNSS and their signals shall be discussed.

List of participants

Supporting documents

It is our intention to open the IGS-BCWG discussion forum to a broader focused group of experts with experience and strong interests (including the RTCM/RINEX community and key experts from GNSS receiver manufacturers). Therefore, we propose that all interested persons (particularly interested in the "Bias Workshop 2015") are invited to register in addition to

Travel and accommodation

Presentations etc.

<http://igscb.jpl.nasa.gov/mailman/listinfo/igs-bcwg>

in order to follow the technical discussions (and further general announcements concerning the workshop).

Email contact

Please be also referred to the webpage from the first IGS Workshop on GNSS Biases (held in 2012):

<http://www.biasws2012.unibe.ch>





IGS Workshop on GNSS Biases 2015 (5 November 2015, with 31 participants)





IGS Bias WS 2016 Presentations

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Presentations

as held at the IGS Workshop on GNSS Biases at the University of Bern,
Switzerland on:

- 5 November 2015
- 6 November 2015

Please click on the title-author line of the presentation of interest to get the
desired pdf file.

Group photo of all workshop participants taken on 5 November 2015 in front of
the main building of the University of Bern.





Bias-SINEX V1.00: Three Format Blocks

The proposed format is based on the SINEX Format [SINEX 2.02]. A number of format blocks may be taken directly from [SINEX 2.02], in particular:

FILE/REFERENCE
SITE/ID
SITE/RECEIVER

Some other format blocks are defined within this document:

BIAS/DESCRIPTION	(Mandatory)
BIAS/RECEIVER_GROUPS	(Optional)
BIAS/SOLUTION	(Mandatory)





Bias-SINEX V1.00: Main Features

2.2. Main Features of SINEX_BIAS

The BIAS/SOLUTION format structure of SINEX_BIAS V1.00 does allow the following main features:

- biases are specified for a give time interval of validity, defined by start and end time;
- biases may be augmented by their slope parameters;
- support of biases responding to: (i) *system*, (ii) *satellite*, (iii) *receiver*, (iv) *satellite-receiver*, and even (v) biases attributed to (user-defined) *receiver groups*;
- *differential* (relative) or *observable-specific* (pseudo-absolute) bias parameters;
- consideration of bias parameters with respect to *code* and *phase* observations;
- the possibility to define *GNSS observable groups* (to be treated with one common bias parameter).





Bias-SINEX V1.00: Representation in Time

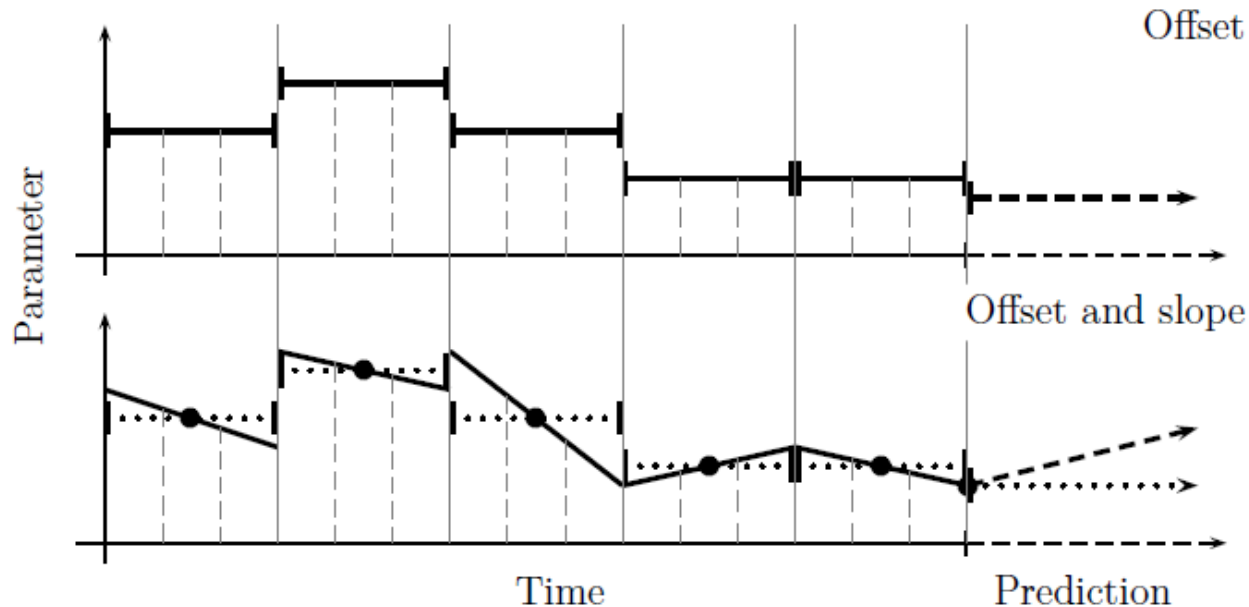


Figure 1: Bias parameter representation *without* (top) and *with* slopes (bottom), as supported by the Bias-SINEX V1.00.





Bias-SINEX V1.00: Three Types of Biases

6.3. Three Types of Signal Biases

We distinguish between three types of signal biases:

- **Observable-specific Signal Bias**, labeled with **OSB**, or $B_{O(\text{constellation,observable})}$;
- **Differential Signal Bias**, labeled with **DSB**, or $B_{D(\text{constellation,observable1,observable2})}$;
- **Ionosphere-free linear combination Signal Bias**, or simply **Ionosphere-free Signal Bias**, labeled with **ISB**, or $B_{I(\text{constellation,observable1,observable2})}$.

The terminology introduced here is based on the outcome of a dedicated e-mail discussion carried out after the Bias Workshop 2015. The (previously used) term “Code,” was replaced by “Signal,” as the SINEX_BIAS Format now also support biases with respect to GNSS phase observations.





Bias-SINEX V1.00: Bias Arithmetics

6.1. Sign Convention

The following sign convention is used for bias values:

$$\text{bias} = \text{observation} - \text{true (or unbiased) observation} \quad (3a)$$

$$\text{observation} = \text{true observation} + \text{bias} \quad (3b)$$

$$\text{true observation} = \text{observation} - \text{bias} \quad (3c)$$

Numerical example: ground truth 11, observed 7, bias (or error) -4 .

6.2.2. Satellite and Receiver Bias Components (and Total Bias)

The **total bias** (or overall bias), if a separation into a satellite component, $B_{\text{satellite}}$, and into a receiver component, B_{receiver} , is assumed, is defined as follows:

$$B_{\text{total}} = B_{\text{satellite}} + B_{\text{receiver}} \quad (5)$$

6.3.2. Ionosphere-free Signal Bias (ISB)

The Ionosphere-free Signal Bias (ISB) has to be interpreted as

$$B_{I(G,C1W,C2W)} = \kappa_1 B_{(G,C1W)} + \kappa_2 B_{(G,C2W)}, \quad (11)$$





Bias SINEX Format Version 1.00



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etc.

Supporting documents for the workshop

- **Bias SINEX 0.01:** Proposal for a format to exchange information on GNSS biases
Format description (draft only)
- **Bias SINEX 1.00:** Finalized draft version
Format description (Proposed DRAFT Nov. 4, 2015)
Format description (Finalized DRAFT Feb. 7, 2016, for IGWS2016)
Message concerning naming of biases (Dec. 4, 2015)
- **IONEX 1.0:** Format to exchange ionosphere maps
Format description
- **IONEX 1.1:** Format update (concerning multi-GNSS DCBs)
Format description (DRAFT)

www.biasws2015.unibe.ch





Implications for IGS Bias Products (1/2)

- IGS ACs should start to consider the bias format standards of *Bias-SINEX Format Version 1.00*.
- *CC2NONCC RINEX2 conversion utility* should no longer be used.
- *Classic GPS P1-C1 DCB corrections* should be made directly by the analysis software.
- In case of MGEX multi-GNSS analysis or GLONASS analysis, there seems to be a necessity that an AC is capable to determine “ISB” bias parameters as such bias parameters become crucial in a **clock analysis of two or more GNSS systems**.





Implications for IGS Bias Products (2/2)

- GPS (and GLONASS) P1-P2 DCB satellite and receiver estimates shall no longer be included in IGS IONEX files.
- A minor update (to V1.1) is proposed for the IONEX Format.
- At AIUB, implementation of (OCB) bias parameter handling into the development version of the Bernese GNSS Software (V5.3) is in progress:
 - multi-GNSS flexibility
 - GNSS observation selection according to given priority list
 - OSB-like bias parameter setup
 - with flexibility for parameter manipulations at NEQ level
- Content of current GPS/GLONASS DCB data archive will be converted into Bias-SINEX Format V1.00
- CODE ISB products are internally available for the IGS (GPS/GLONASS) and the MGEX analysis product (covering 5 GNSS).



AIUB



Bias and Calibration Splinter Meeting

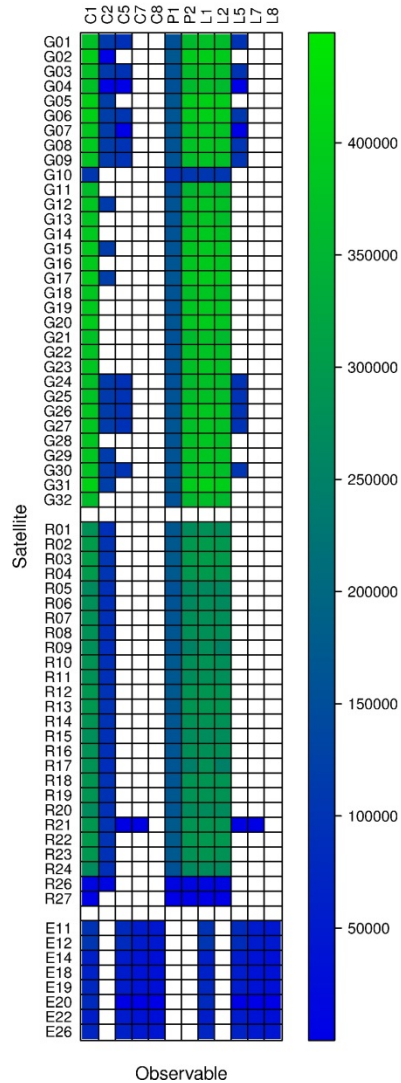
- Tuesday 9 February, 15:00-17:00
- Theatre A
- **Bias-SINEX Format** will be the primary topic for discussion.
- The format description is available at: www.biasws2015.unibe.ch
- Any input, or feedback is welcome.



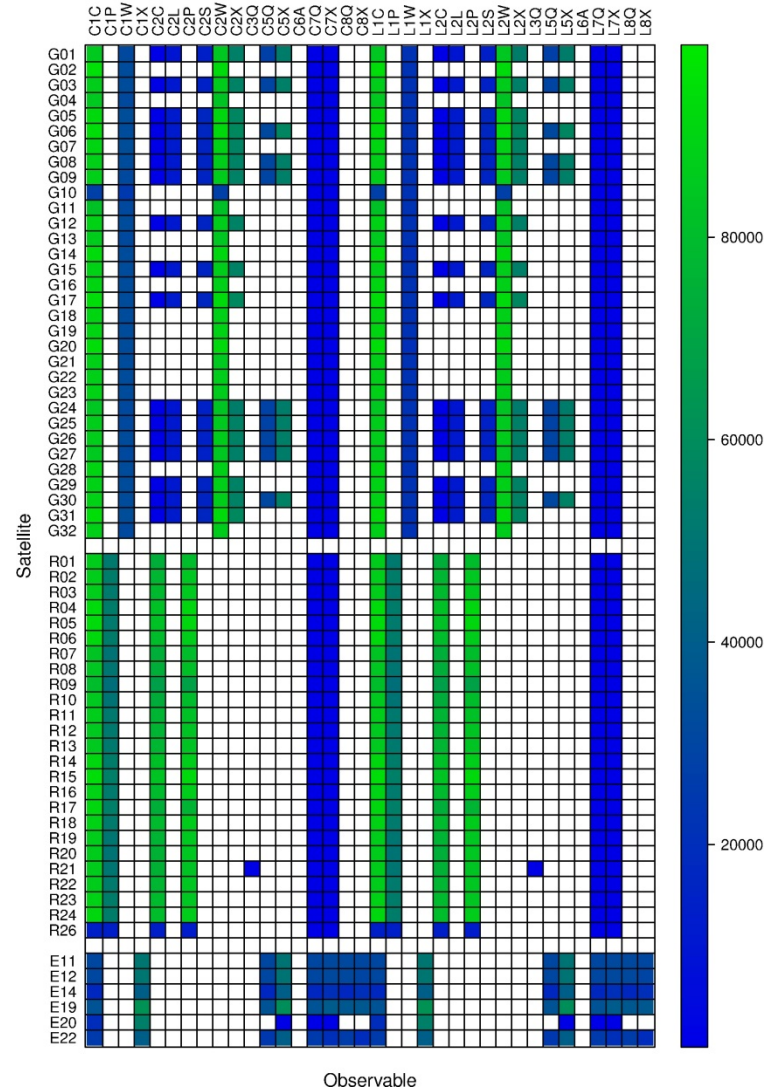


GNSS Observables in IGS RINEX2 & RINEX3

GPS / GLONASS / Galileo



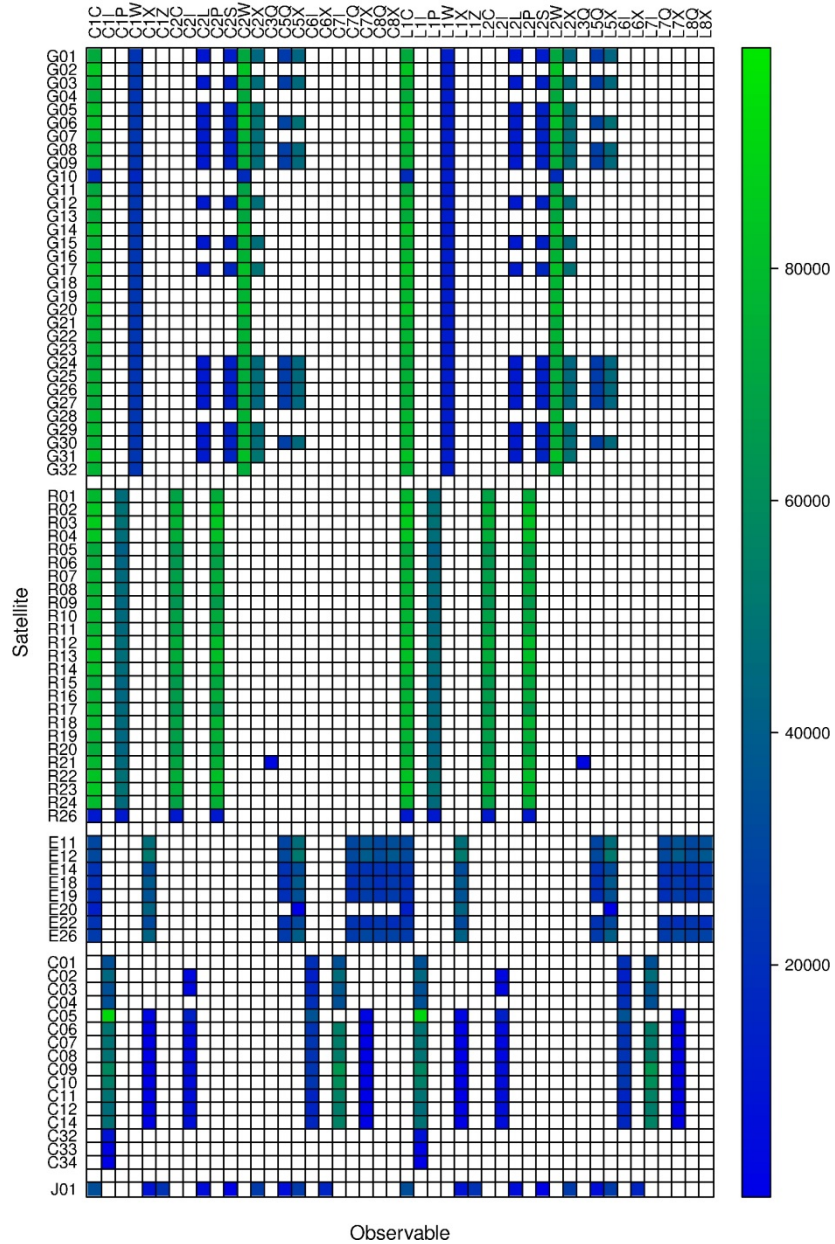
GPS / GLONASS / Galileo





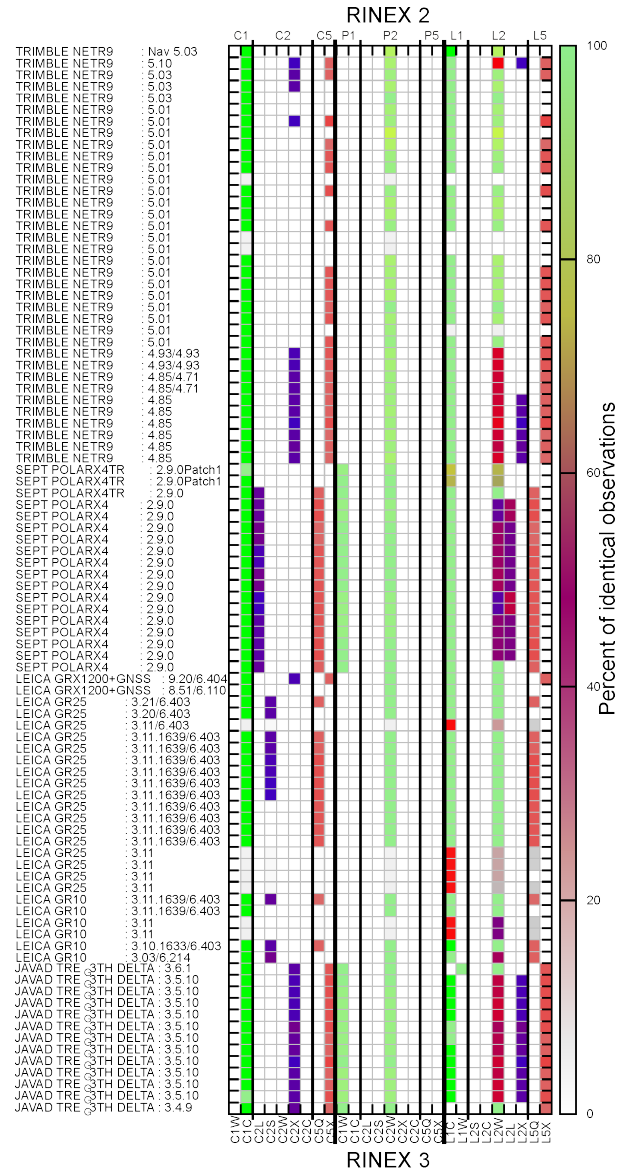
RINEX3 (for 5 GNSS)

GPS / GLONASS / Galileo / BeiDou / QZSS





Comparison of RINEX2/RINEX3 GPS Observations





SINEX_BIAS: Update from V0.01 to V1.00 ...

```
X-BIA 1.00 PF2 11:190:59736 PF2 11:113:86385 11:114:86385 P 04774 2 SINEX_BIA
-----
* Bias Solution INdependent EXchange Format (Bias-SINEX)
-----
+FILE/REFERENCE
REFERENCE FRAME      IGS08
DESCRIPTION          European Space Operation Center (ESOC)
INPUT                ESOC solutions in normal equation format
OUTPUT              ESOC solutions in Bias-SINEX format
CONTACT              Tin.Springer@esa.int.nospam
HARDWARE             Linux dgn12 2.6.27.19-5-default #1 SMP 2009-02-28 04:40:21
SOFTWARE             Napeos 3.6 TAS 07/06/2011
-FILE/REFERENCE
-----
+BIAS/DESCRIPTION
*KEYWORD----- VALUE(S)-----
OBSERVATION SAMPLING      300
PARAMETER SPACING         86400
DETERMINATION METHOD      CLOCK ANALYSIS
BIAS MODE                 DIFFERENTIAL
TIME SYSTEM               G
REFERENCE SYSTEM         G
REFERENCE OBSERVABLES    E C1C C7Q
REFERENCE OBSERVABLES    G C1W C2W
ZERO-MEAN CONDITIONS     G 0 0 0 0 0 0 0 0
ZERO-MEAN CONDITIONS     E 1 0 0 1 0 0 0 0
-BIAS/DESCRIPTION
-----
+BIAS/SOLUTION
*BIAS SVN_ PRN STATION_ OBS1 OBS2 BIAS_START_ BIAS_END_ UNIT ESTIMATED_VALUE STD_DEV ESTIMATED_SI
ISB G G GIEN C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GKIR C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GKOU C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GLPG C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GMAL C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GMIZ C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GNND C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GNOR C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GOUS C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GTHT C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GUSN C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB G G GVES C1W C2W 11:113:86385 11:115:00285 ns 0.000000000000000E+00 .000000E+00
ISB E E GIEN C1C C7Q 11:113:86385 11:115:00285 ns -.157174143960592E+03 .259286E+02
ISB E E GKIR C1C C7Q 11:113:86385 11:115:00285 ns -.153942459345551E+03 .259286E+02
ISB E E GKOU C1C C7Q 11:113:86385 11:115:00285 ns -.163243805130824E+03 .259285E+02
ISB E E GLPG C1C C7Q 11:113:86385 11:115:00285 ns -.151698143836368E+03 .259290E+02
ISB E E GMAL C1C C7Q 11:113:86385 11:115:00285 ns -.156472089904428E+03 .259285E+02
ISB E E GMIZ C1C C7Q 11:113:86385 11:115:00285 ns -.167156432084244E+03 .259321E+02
ISB E E GNND C1C C7Q 11:113:86385 11:115:00285 ns -.156922861008147E+03 .259665E+02
ISB E E GNOR C1C C7Q 11:113:86385 11:115:00285 ns -.153679440866705E+03 .259285E+02
ISB E E GOUS C1C C7Q 11:113:86385 11:115:00285 ns -.10159333722667E+03 .259439E+02
ISB E E GTHT C1C C7Q 11:113:86385 11:115:00285 ns -.159918985571303E+03 .259356E+02
ISB E E GUSN C1C C7Q 11:113:86385 11:115:00285 ns -.149146613879327E+03 .259279E+02
ISB E E GVES C1C C7Q 11:113:86385 11:115:00285 ns -.156221372596643E+03 .259288E+02
-BIAS/SOLUTION
-----
X-ENDBIA
```





Bias-SINEX V1.00: SVN/PRN/STATION Usage

5.2. Notes on SVN/PRN and STATION Usage in BIAS/SOLUTION Block

The fields SVN/PRN and STATION may be used for coding of biases with four different characteristics:

- **Satellite bias:** If a bias depends only on a satellite, SVN/PRN should be filled, STATION may be left empty.
- **Station bias:** If a bias depends only on a station and a particular GNSS, STATION should be filled and SVN/PRN should have the system code only (e.g. “G”, “R”, “E” for GPS, GLONASS, Galileo).
- **Satellite-station (satellite-receiver) bias:** If a bias depends on both satellite and station, all three fields, SVN/PRN/STATION, should be used.
- **System bias:** If a bias depends only on a particular GNSS, SVN/PRN should have the system code only (e.g. “G”, “R”, “E” for GPS, GLONASS, Galileo).





Bias-SINEX V1.00: Examples for Four Cases

Examples for the four cases (listed above) may look like:

```

-----
+BIAS / SOLUTION
*BIAS SVN_ PRN STATION__ OBS1 OBS2 BIAS_START__ BIAS_END____ UNIT __ESTIMATED_VALUE____ _STD_DEV___ __EST
DSB G063 G01 C1W C1C 15:276:00000 15:276:86399 ns 0.148022937908458E+01 .398201E-01
ISB C C ABMF C1I C7I 15:276:00000 15:276:86399 ns 0.240909461328850E+02 .835246E+00
ISB R730 R01 AUCK C1P C2P 15:276:00000 15:276:86399 ns 0.104868834341878E+02 .101419E+01
ISB G G C1W C2W 15:276:00000 15:276:86399 ns 0.000000000000000E+00 .000000E+00
-BIAS / SOLUTION
-----

```





Bias-SINEX V1.00: Receiver Groups

+BIAS/RECEIVER_GROUPS

*STATION__	C	GROUP_____	DATA_START__	DATA_END____	RECEIVER_TYPE_____	RECEIVER_FIRMWARE___
MA00	G	@MPO	15:276:00000	15:276:86399	JAVAD TRE-G3TH DELTA	3.6.4
SINO	G	@MPO	15:276:00000	15:276:86399	JAVAD TRE-G3TH DELTA	3.6.4
SIN1	G	@MP1TRI	15:276:00000	15:276:86399	TRIMBLE NETR9	5.10
STFU	G	@MP1JAV-1	15:276:00000	15:276:86399	JAVAD TRE-G3TH DELTA	3.6.4
TEST	G	@MP1JAV-2	15:276:00000	15:276:86399	JAVAD TR_VS	3.6.4
YXX	G	@MP1TRI	15:276:00000	15:276:86399	TRIMBLE NETR5	4.93
WTZZ	G	@MP_	15:276:00000	15:276:86399	JAVAD TRE-G3TH DELTA	3.6.4
MA00	E	@ALL	15:276:00000	15:276:86399	JAVAD TRE-G3TH DELTA	3.6.4
SINO	E	@ALL	15:276:00000	15:276:86399	JAVAD TRE-G3TH DELTA	3.6.4
SIN1	E	@ALL	15:276:00000	15:276:86399	TRIMBLE NETR9	5.10
STFU	E	@ALL	15:276:00000	15:276:86399	JAVAD TRE-G3TH DELTA	3.6.4
TEST	E	@ALL	15:276:00000	15:276:86399	JAVAD TR_VS	3.6.4
WTZZ	E	@ALL	15:276:00000	15:276:86399	JAVAD TRE-G3TH DELTA	3.6.4

- *LEGEND: G @MPO Receivers with disabled multipath (MP) mitigation.
- *LEGEND: G @MP1JAV-1 JAVAD TRE-G3TH receivers with MPNEW MP mitigation enabled.
- *LEGEND: G @MP1JAV-2 JAVAD TRIUMPH receivers with MPNEW MP mitigation enabled.
- *LEGEND: G @MP1TRI TRIMBLE receivers with Everest MP mitigation enabled.
- *LEGEND: G @MP_ Extra group with unknown MP mitigation mode.
- *LEGEND: E @ALL No grouping for the indicated system.

-BIAS/RECEIVER_GROUPS

+BIAS/SOLUTION

*BIAS	SVN_	PRN	STATION__	OBS1	OBS2	BIAS_START__	BIAS_END____	UNIT	ESTIMATED_VALUE_____	STD_DEV____	EST
DSB	G001	G01	@MPO	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	G001	G01	@MP1TRI	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	G001	G01	@MP1JAV-1	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	G001	G01	@MP1JAV-2	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	G001	G01	@MP_	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	G002	G02	@MPO	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	G002	G02	@MP1TRI	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	G002	G02	@MP1JAV-1	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	G002	G02	@MP1JAV-2	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	G002	G02	@MP_	C1W	C2W	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	E001	E01	@ALL	C1X	C5X	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	
DSB	E002	E02	@ALL	C1X	C5X	15:276:00000	15:276:86399	ns	0.0000000000000000E+00	.000000E+00	

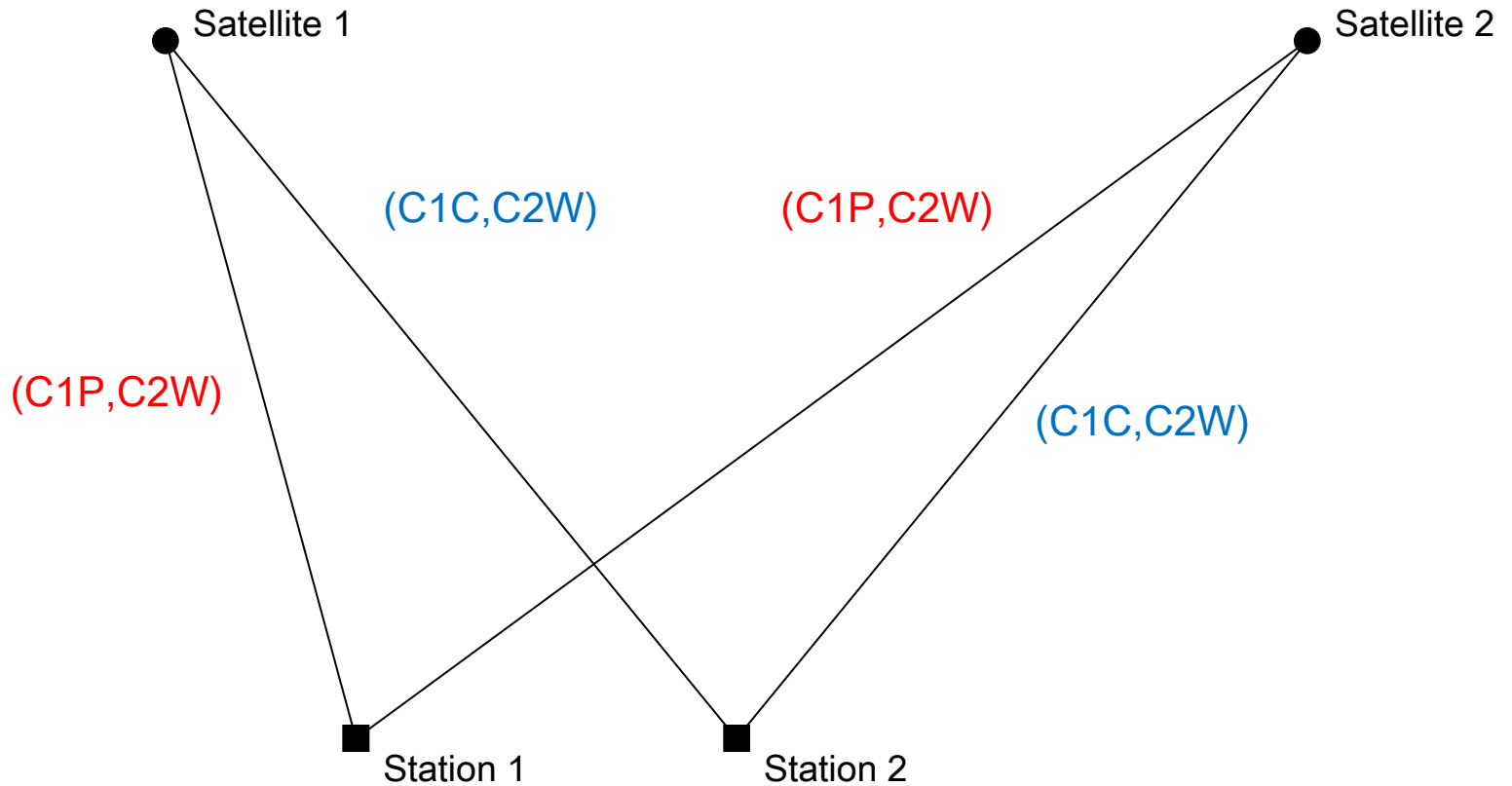
-BIAS/SOLUTION





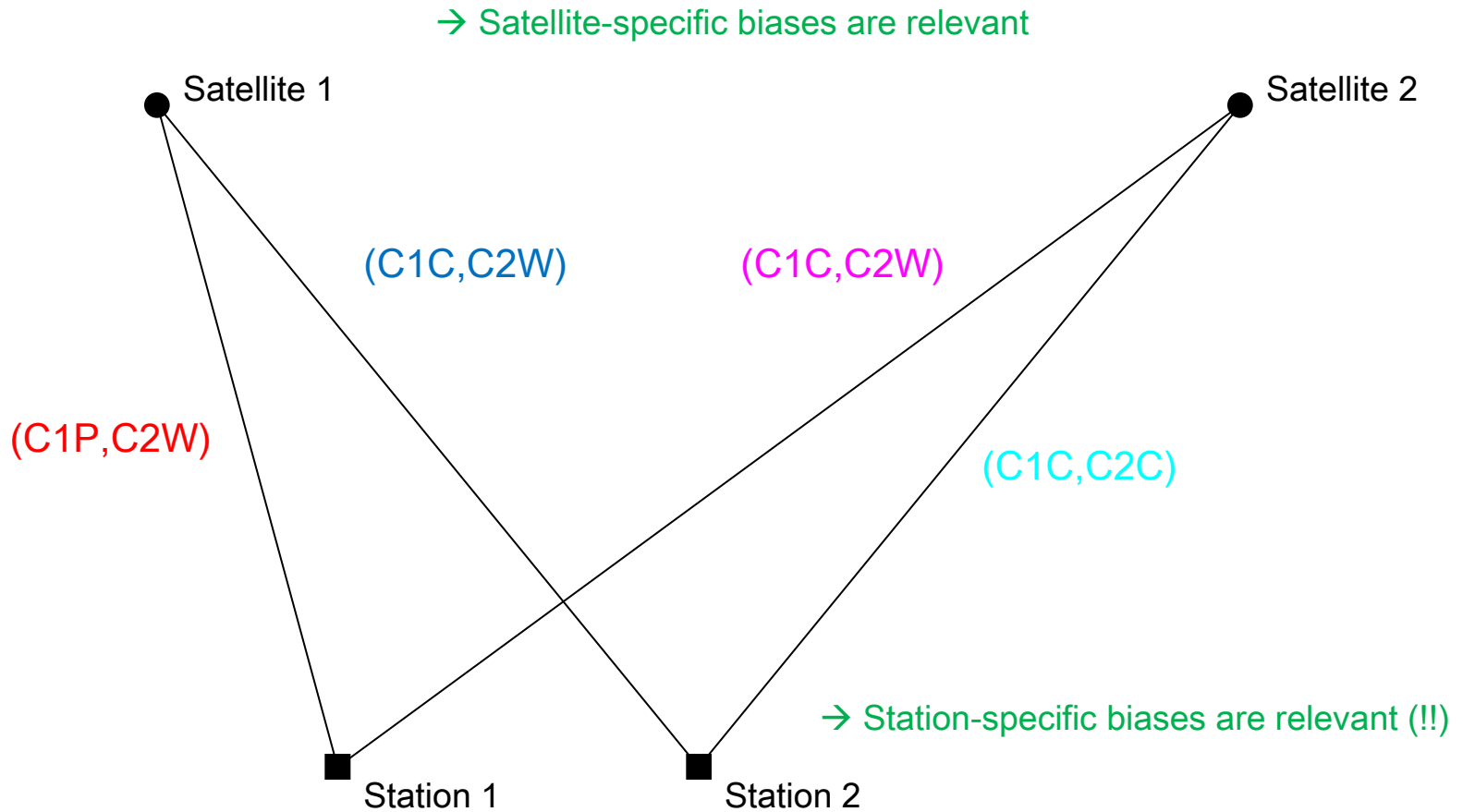
Mixture of different code observables (and biases!) is crucial for code-based widelane ambiguity resolution (1/2)

→ Satellite-specific biases are relevant



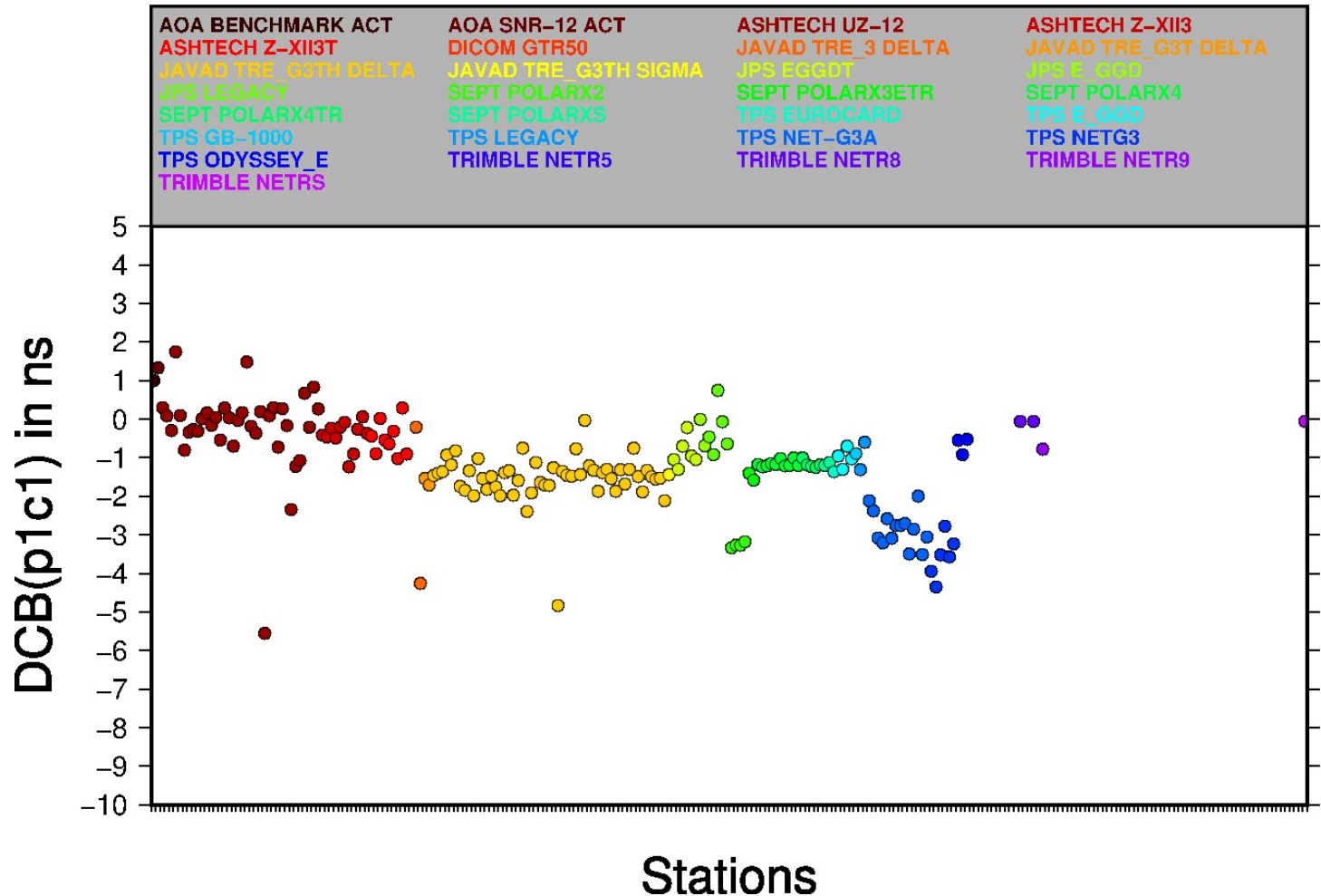


Mixture of different code observables (and biases!) is crucial for code-based widelane ambiguity resolution (2/2)



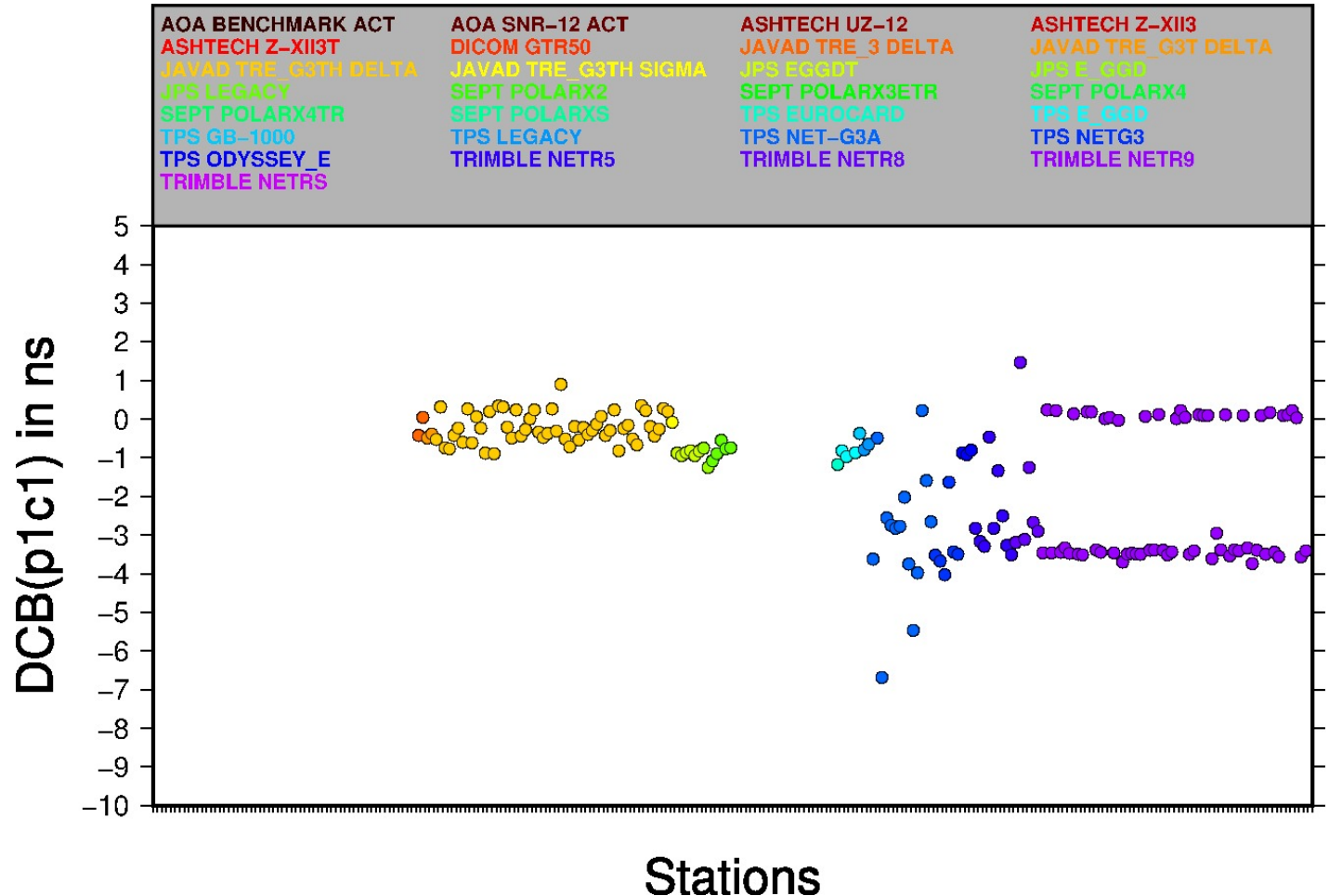


CODE's GPS P1-C1 DCB monthly solution, computed for September 2015 (directly from RINEX)



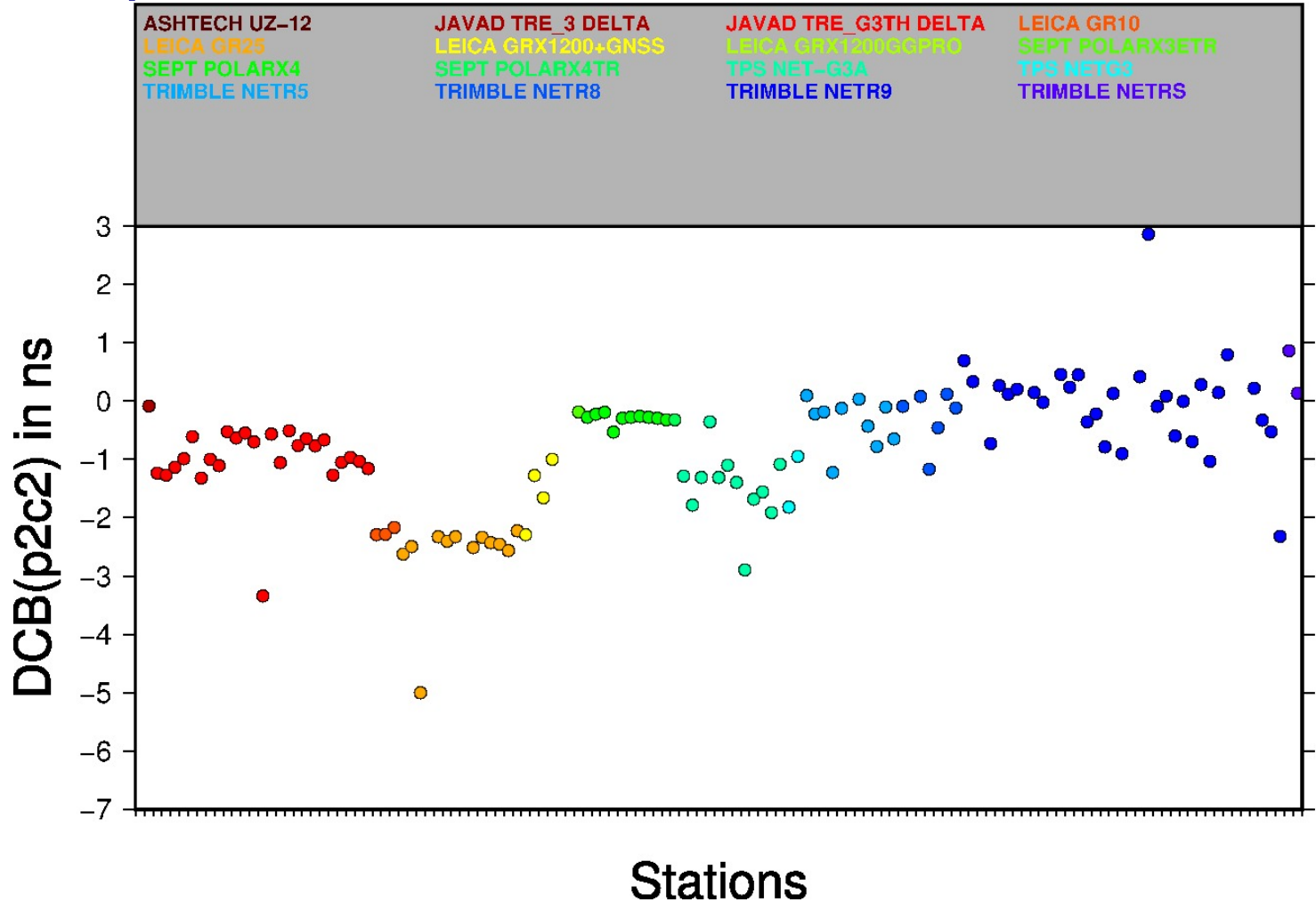


CODE's GLONASS P1-C1 DCB monthly solution, computed for September 2015 (directly from RINEX)



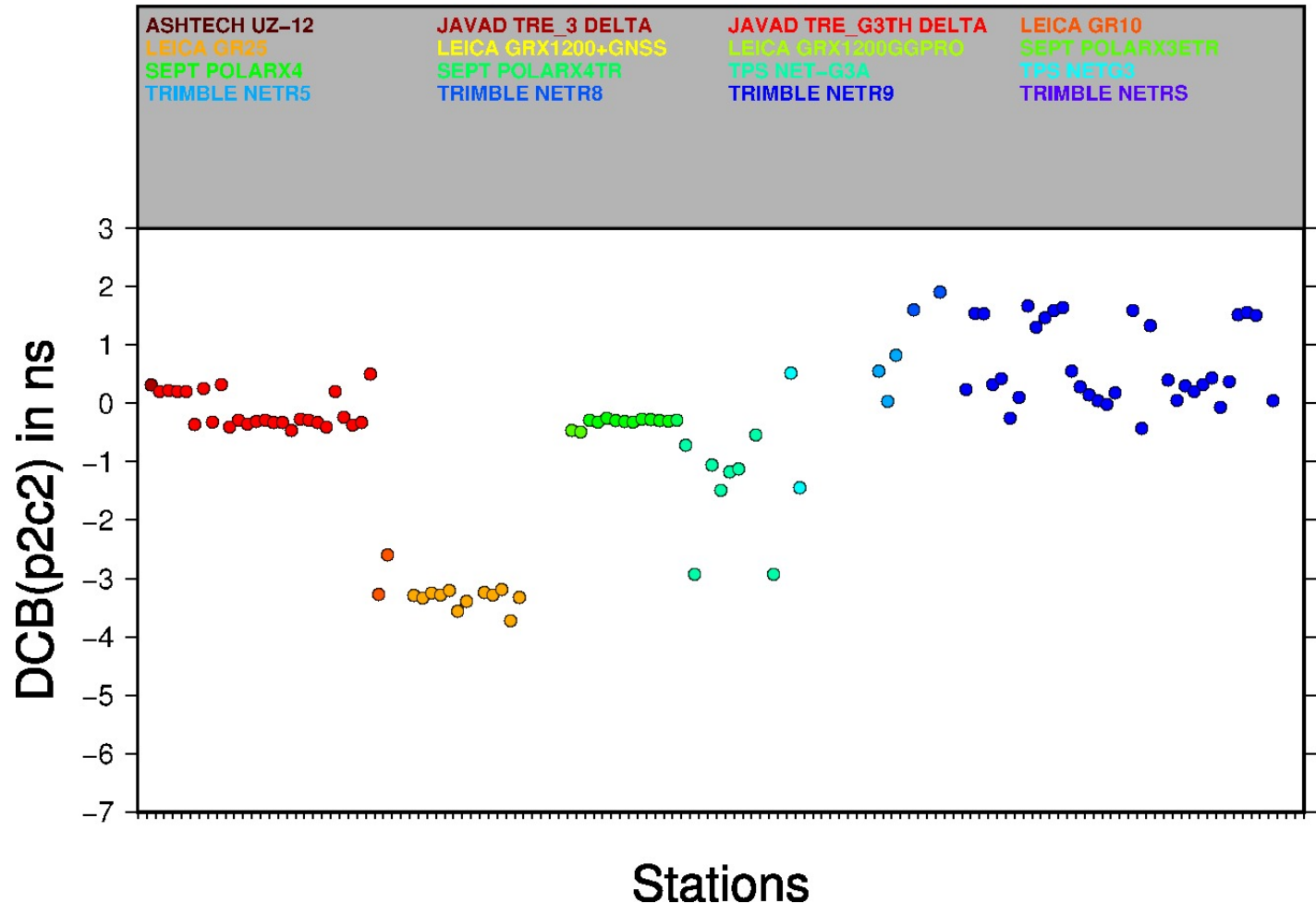


CODE's GPS P2-C2 DCB monthly solution, computed for September 2015 (directly from RINEX)



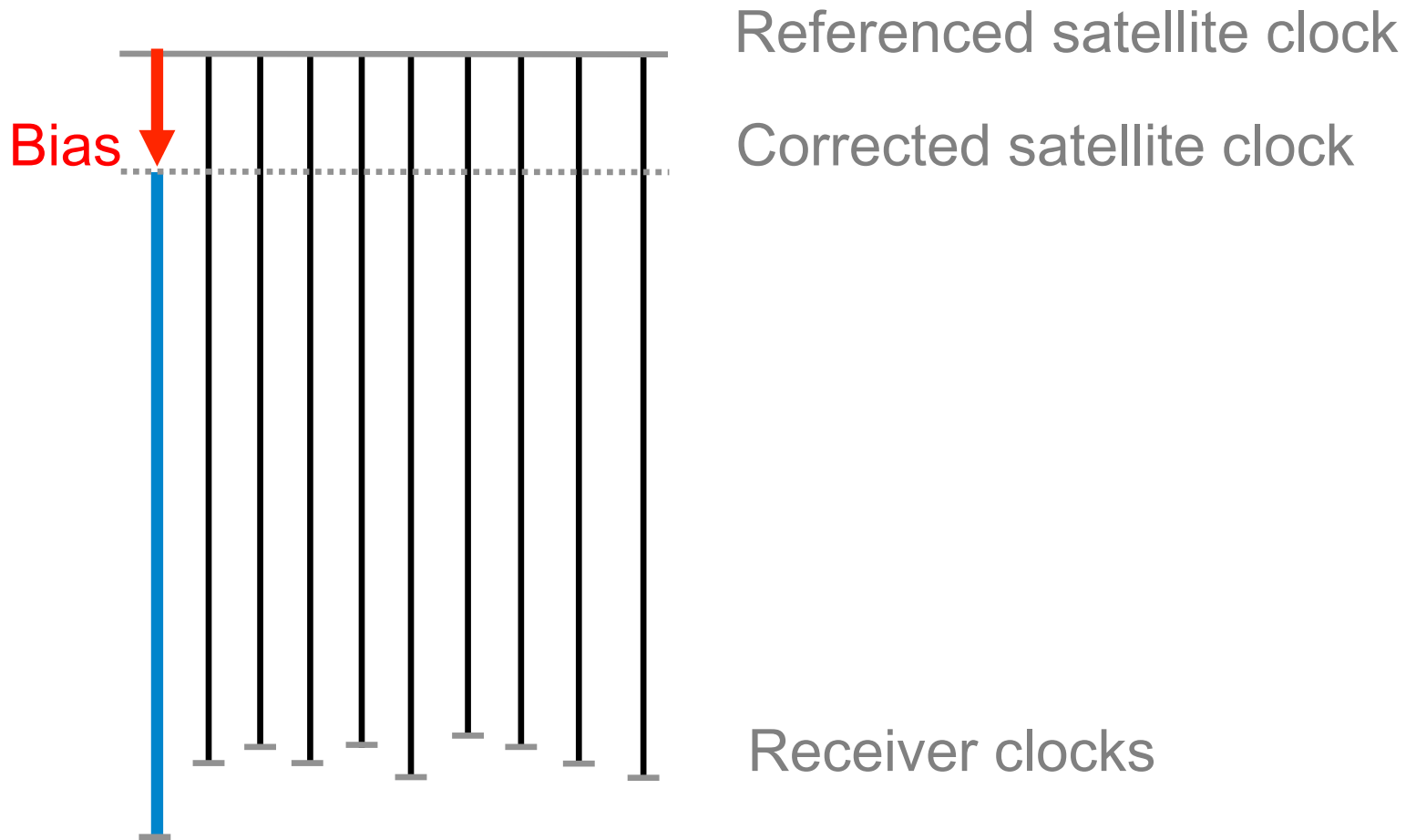


CODE's GLONASS P2-C2 DCB monthly solution, computed for September 2015 (directly from RINEX)





Illustrated impact of changed reference observable selection on clock and bias products (1/2)





Illustrated impact of changed reference observable selection on clock and bias products (2/2)

