

Introduction



Since the beginning of the 24th Solar cycle, the Solar activity increases (maximum expected in 2013) together with the ionospheric activity (Bergeot et al., 2012) (Figure 1). It requires therefore having a close eye on the ionosphere to better understand the Space Weather physics and its effects on radio communication and navigation.

In this frame, near real-time ionospheric models over Europe are now generated every 15 minutes at the Royal Observatory of Belgium (ROB). They are available on-line at www.gnss.be with a latency of 5-7 minutes with respect to the last GNSS measurement. The models are ionospheric Vertical Total Electron Content (VTEC) maps estimated on a 0.5°x0.5° grid based on Global Positioning System (GPS) observations.

The poster introduces :

- the processing strategy used to generate the VTEC maps
- the products available on-line developed around the VTEC maps
- the comparisons with Global Ionospheric Maps (GIM) and climatological ionospheric model.

I. Method

Data

- Real-Time GPS data of 122 EUREF Permanent Network (EPN) stations (Bruyninx et al., 2012) (Figure 2) provided by the ROB NTRIP broadcaster (Söhne et al., 2010)
- Ultra-Rapid Orbits from the International GNSS Service (IGS) (Beutler et al., 1995)
- Satellite Differential Code Biases (DCB) from the Center for Orbit Determination for Europe (CODE) (Schaer et al., 1998)

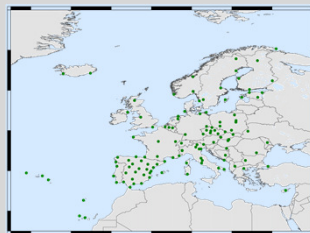


Figure 2: Real-time receiver network of the EPN

Estimation of the Total Electron Content from GNSS Data

- The Slant Total Electron Content (STEC) corresponds to the total number of electrons along a satellite-receiver path. It is expressed in TEC units (1TECu = 10¹⁶ electrons.m²). The STEC is estimated each 30s for each satellite/receiver pair using the geometry-free linear combination (Bergeot et al., 2003):

$$STEC = \frac{f_1^2 f_2^2}{40.3(f_1^2 - f_2^2)} * ((P_1 - P_2) - c(DCB_r + DCB_s))$$

P_1, P_2 : Phase-smoothed code observations (in m) at the two GNSS frequencies f_1, f_2

c : Speed of light

DCB_r : Receiver DCB estimated as the median over the 5 previous days using a priori rapid ionospheric model from CODE

DCB_s : Satellite DCB

- The STEC is then projected as a Vertical TEC (VTEC) at the ionospheric Pierce Point (IPP) at an altitude of 450 km, using an ionospheric single thin layer hypothesis (Figure 3).

$$VTEC = STEC \cos z'$$

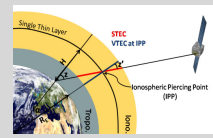


Figure 3: Geometry of the VTEC at the IPP from STEC

Data Cleaning, Filtering and Spline Interpolation

- Medians of VTEC along each satellite track are estimated, avoiding outliers and improving the distribution of the set of data.
- The spline interpolation is iterated with different degrees of smoothing, in order to perform outlier rejection (see Figure 4).
- VTEC grid : 0.5°x0.5° - 15 min
- Number of VTEC at IPP per map : 1692 ± 271
- Time-independent maps

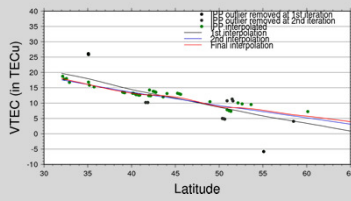


Figure 4 : Interpolation on a longitudinal slice

II.a. Ionospheric Products Available On-Line

Since December 2011, the ROB delivers Near Real-Time Ionospheric Products (Figure 5), dispatched as 3 different sub-products.

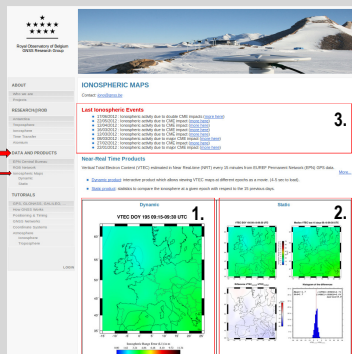


Figure 5: Web home page of the ionospheric products

1) Interactive Ionospheric VTEC Maps (Figure 6)

- Animated ionospheric VTEC maps (movie) for a requested period
- Display VTEC value at a given point and time

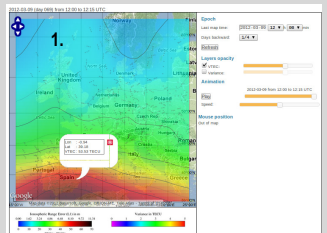


Figure 6: Interactive Ionospheric VTEC Map tool

II.b. Ionospheric Products Available On-Line

2) Statistics over the ionospheric VTEC maps :

Comparison of VTEC maps at a given time w.r.t the median of the 15 previous days (prediction model) highlighting the ionospheric activity. (Figure 7).

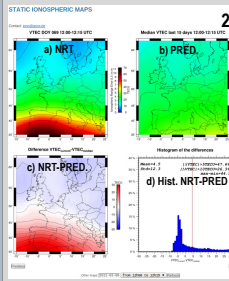
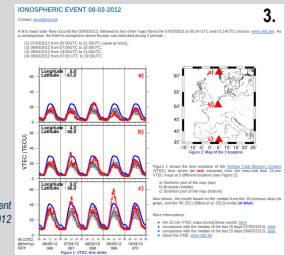


Figure 7: Statistical product web page with a) VTEC map, b) median VTEC of the 15 previous days, c) Differences current VTEC/median VTEC, d) Histogram of the differences

Figure 8: Web page of the event of the 07/03/2012

3) Ionospheric Events:

- ionospheric events are reported into dedicated web pages
- VTEC time serie of 2 days before and after the event at 3 locations in Europe, including the VTEC median w.r.t. the 15 previous days and the International Reference Ionosphere (IRI 2012) model (Blitz et al., 2008) (Figure 8).



III. Comparison with Global Ionospheric Maps and Climatological Model

To test the robustness of our ROB Near Real-Time ionospheric maps, we compared them with GNSS-based CODE final GIM (latency of 5 days) (Schaer et al., 1998) during an ionospheric quiet day (18/01/2012) and during a disturbed day (22/01/2012) due to a Solar Coronal Mass Ejection impact.

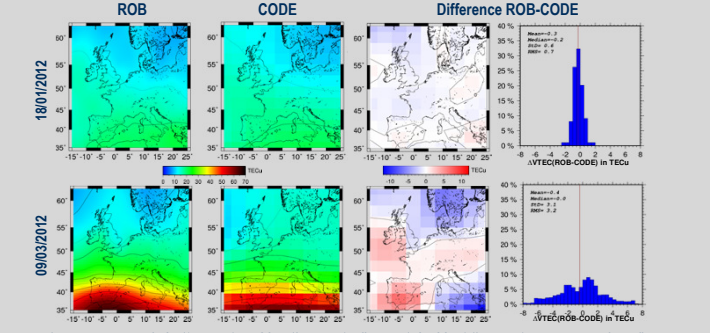


Figure 9: Ionospheric Maps of ROB (1st column) and CODE (2nd column), differences (ROB-CODE) (3rd column) and histograms of the differences; for a quiet day, the 18/01/2012 at 14:00 UTC (top row) and for a disturbed day, the 09/03/2012 at 12:00 UTC (top row) (bottom row)

- ROB maps are less smooth, fitting closer to the GNSS observations (Figure 9).
- ROB maps are not biased 0.0±1.1TECU (Figure 10) w.r.t. CODE products apart during ionospheric disturbed period (absolute bias of 2.4 ± 2.0 TECU) (Figure 9).

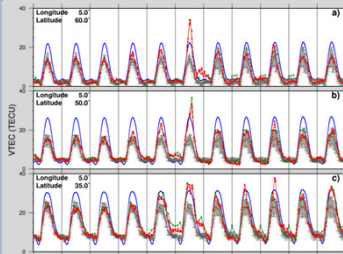


Figure 10: Differences between ROB and CODE VTEC for January 2012

VTEC extracted from ROB maps at 3 locations in January 2012 is compared with CODE GIM and the climatological model of IRI 2012 (Figure 11).

- Differences with CODE GIM and ROB VTEC are of the order of 0.0±1.3TECU in the North, 0.2±0.8TECU above Brussel and -0.9±1.5TECU in the South.
- Mainly at day time, a bias is observed w.r.t. IRI. For example at noon, there are biases of -6.4±3.9TECU in the North, -9.5±3.2 TECU above Brussel and -5.6±4.2TECU in the South.

Conclusion

- ✓ The Regional Near Real-Time Ionospheric VTEC Maps of ROB with a resolution of 0.5°x0.5° are available every 15 minutes with a latency of 5-7 minutes at www.gnss.be/Atmospheric_Maps/ionospheric_maps.php.
- ✓ Additional web pages show the ionospheric activity w.r.t to the 15 previous days and identified ionospheric events since January 2012.
- ✓ The ROB VTEC maps allow any user within the geographical scope of the maps to estimate in near real time the ionospheric delay induced along the signal of any observed satellite.
- ✓ The ROB VTEC maps demonstrate a good agreement with Final Global Ionospheric Map of CODE.
- ✓ New products will be developed to satisfy both ionospheric and GNSS communities : IONEX format, maps of the foF2 Critical Frequency, correlation GPS signal to noise ratio and solar events.

References

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