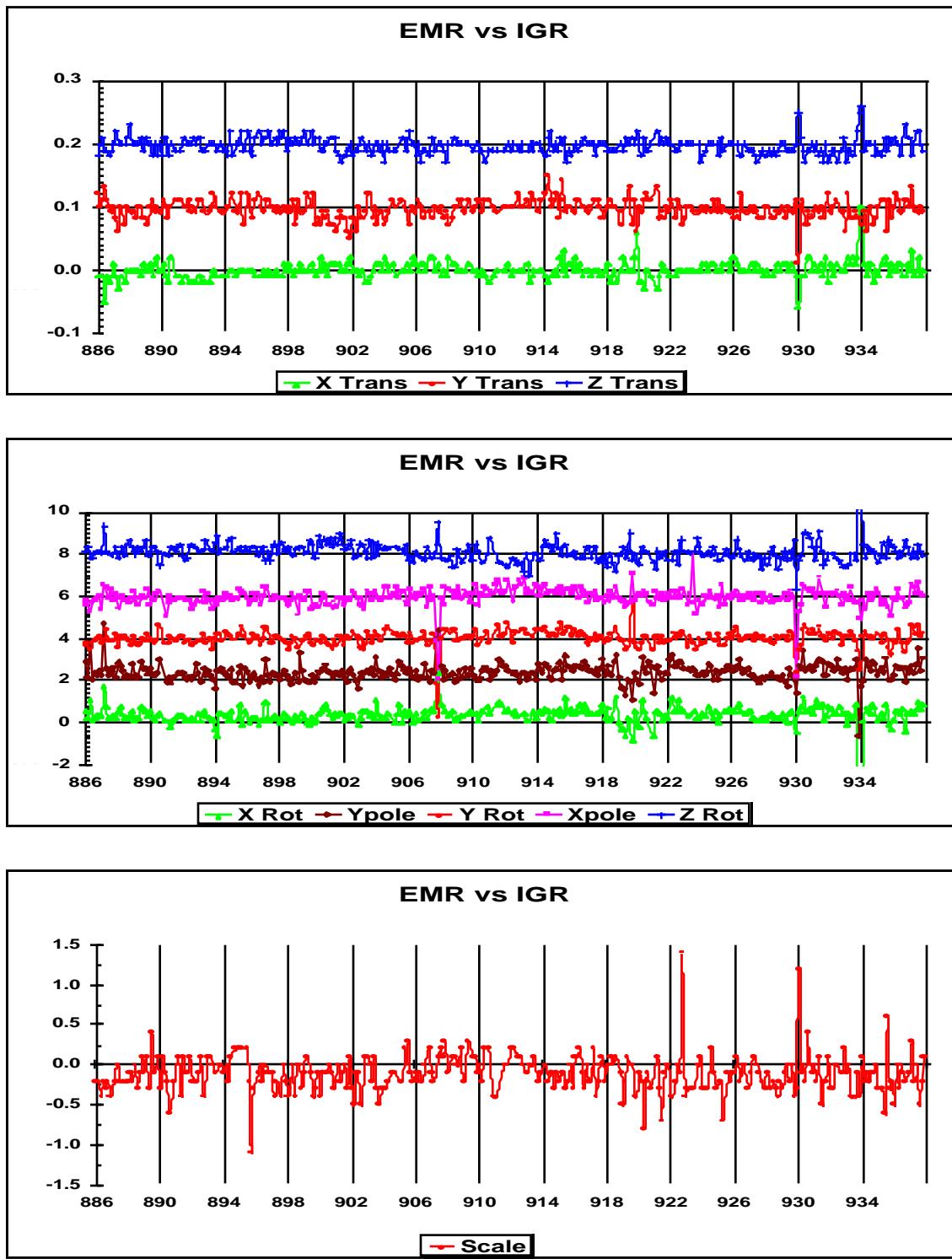
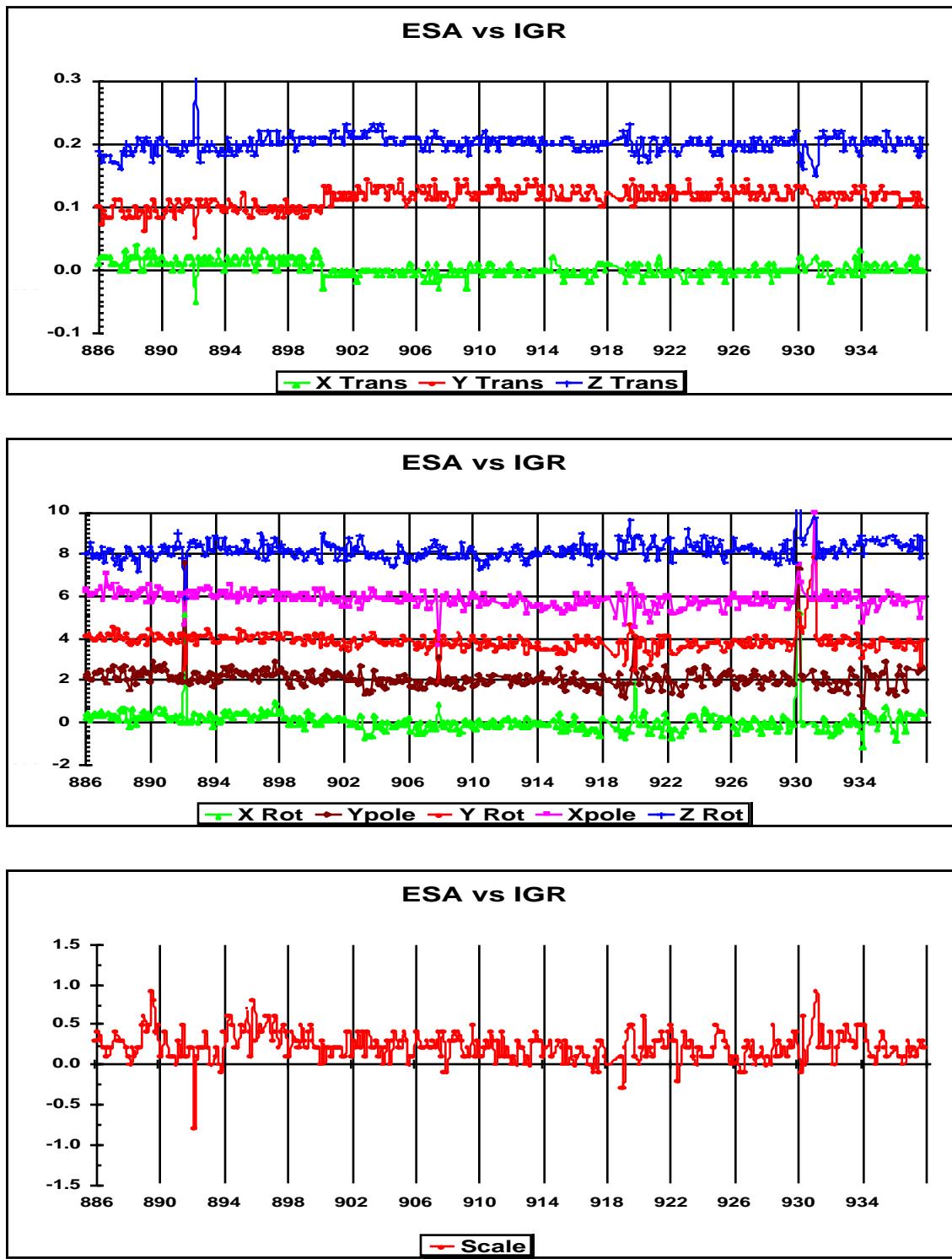


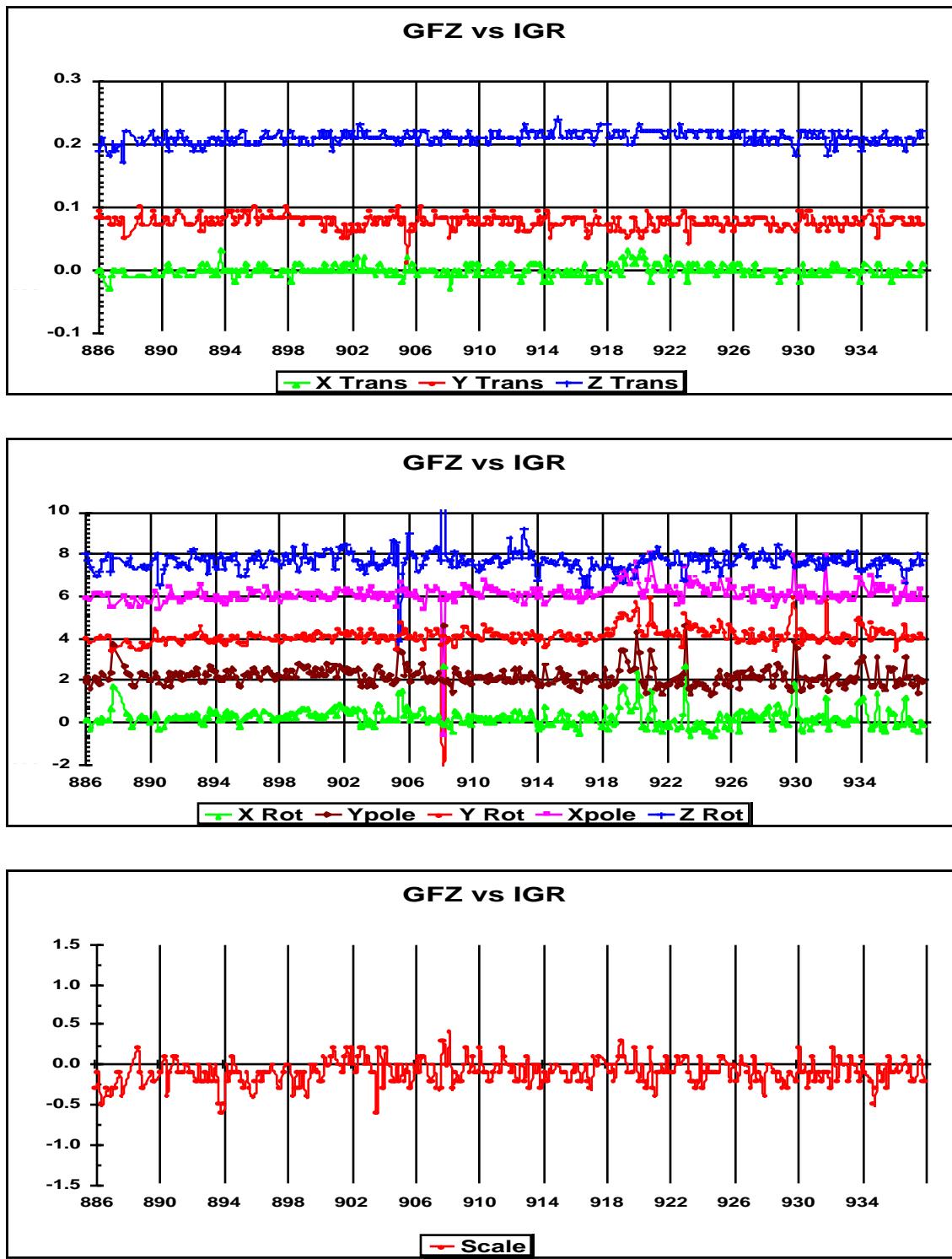
**Figure 10.** COD 1997: Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



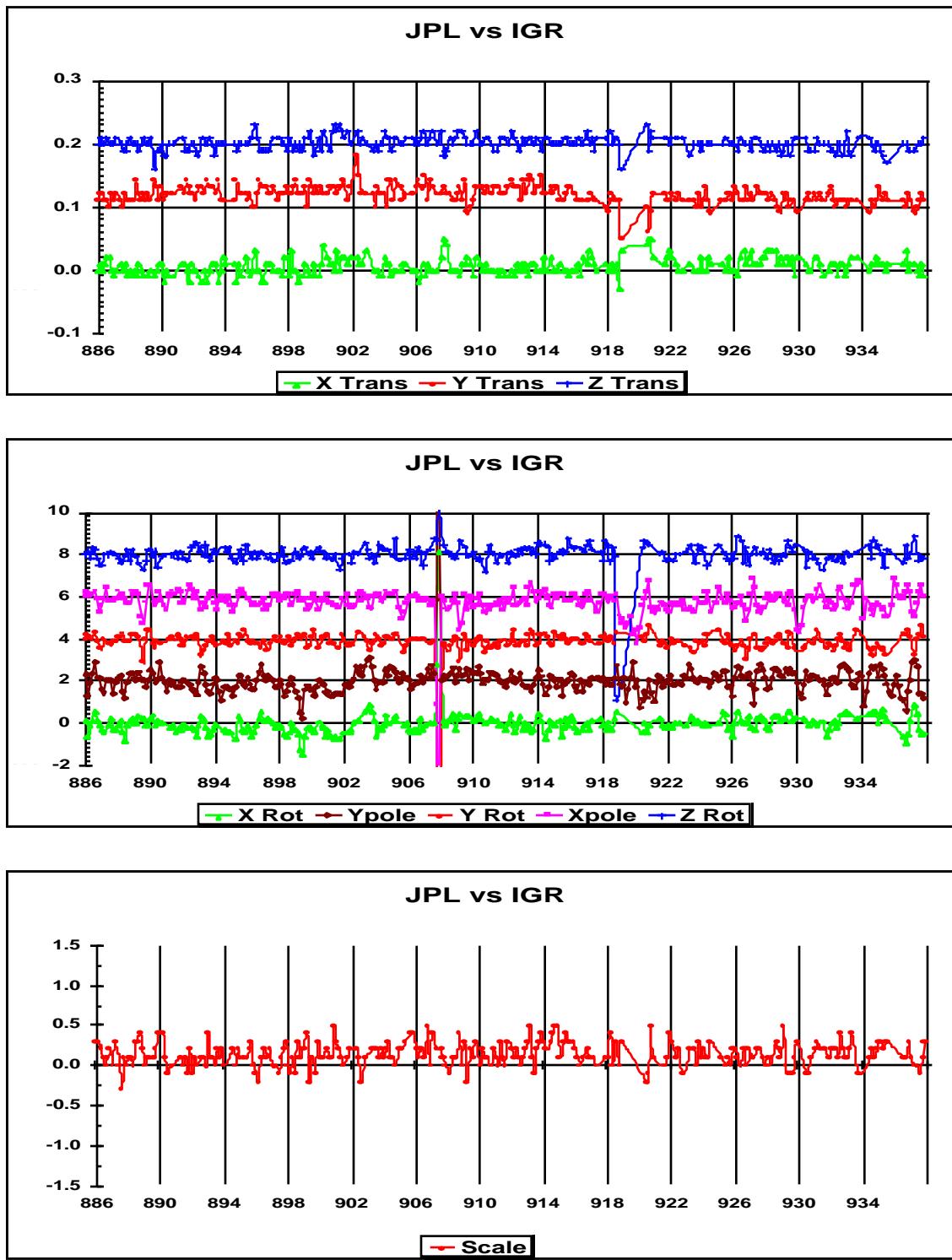
**Figure 11.** EMR 1997: Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



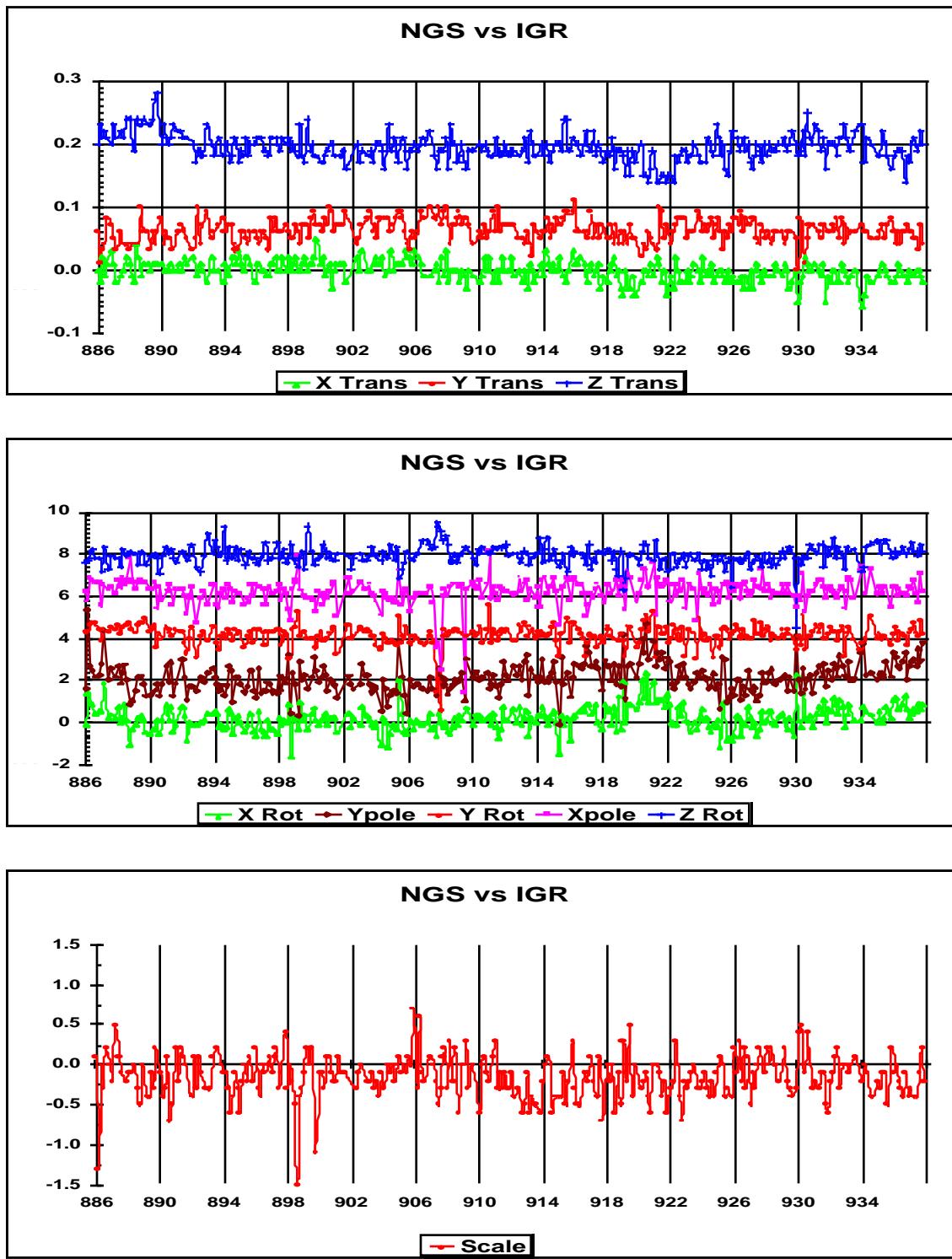
**Figure 12.** ESA 1997: Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



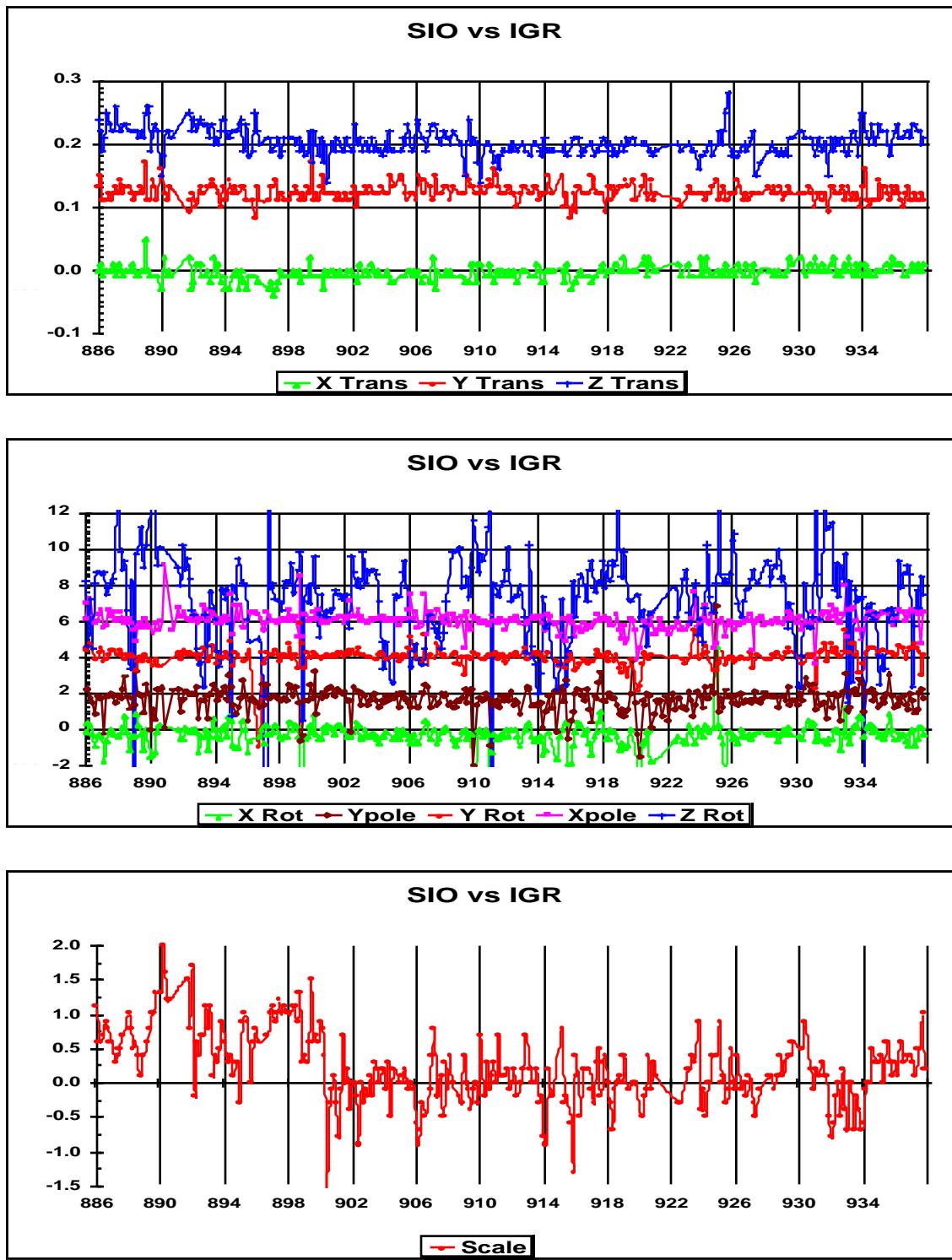
**Figure 13.** GFZ 1997: Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



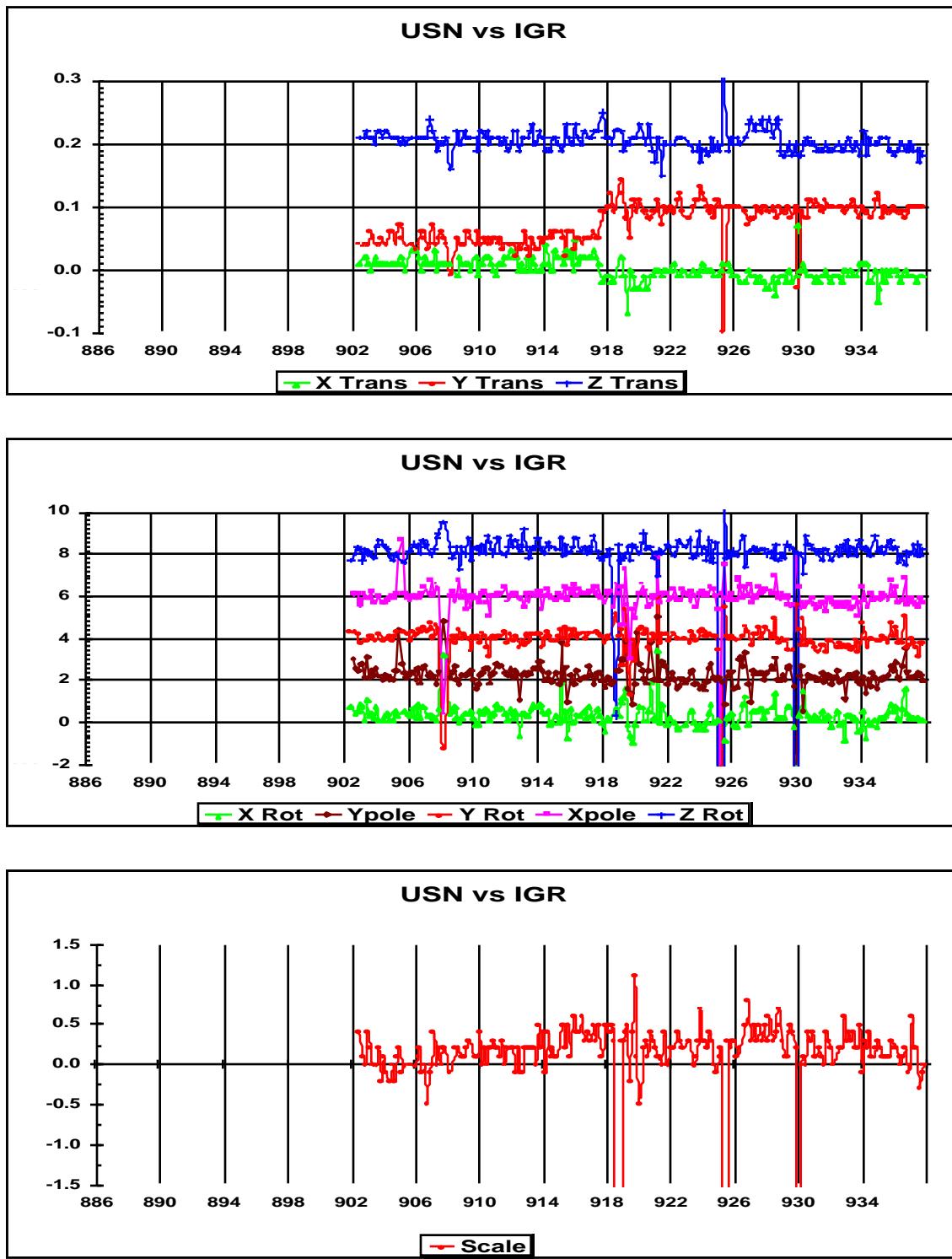
**Figure 14. JPL 1997:** Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



**Figure 15.** NGS 1997: Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



**Figure 16. SIO 1997:** Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



**Figure 17.** USN 1997: Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)