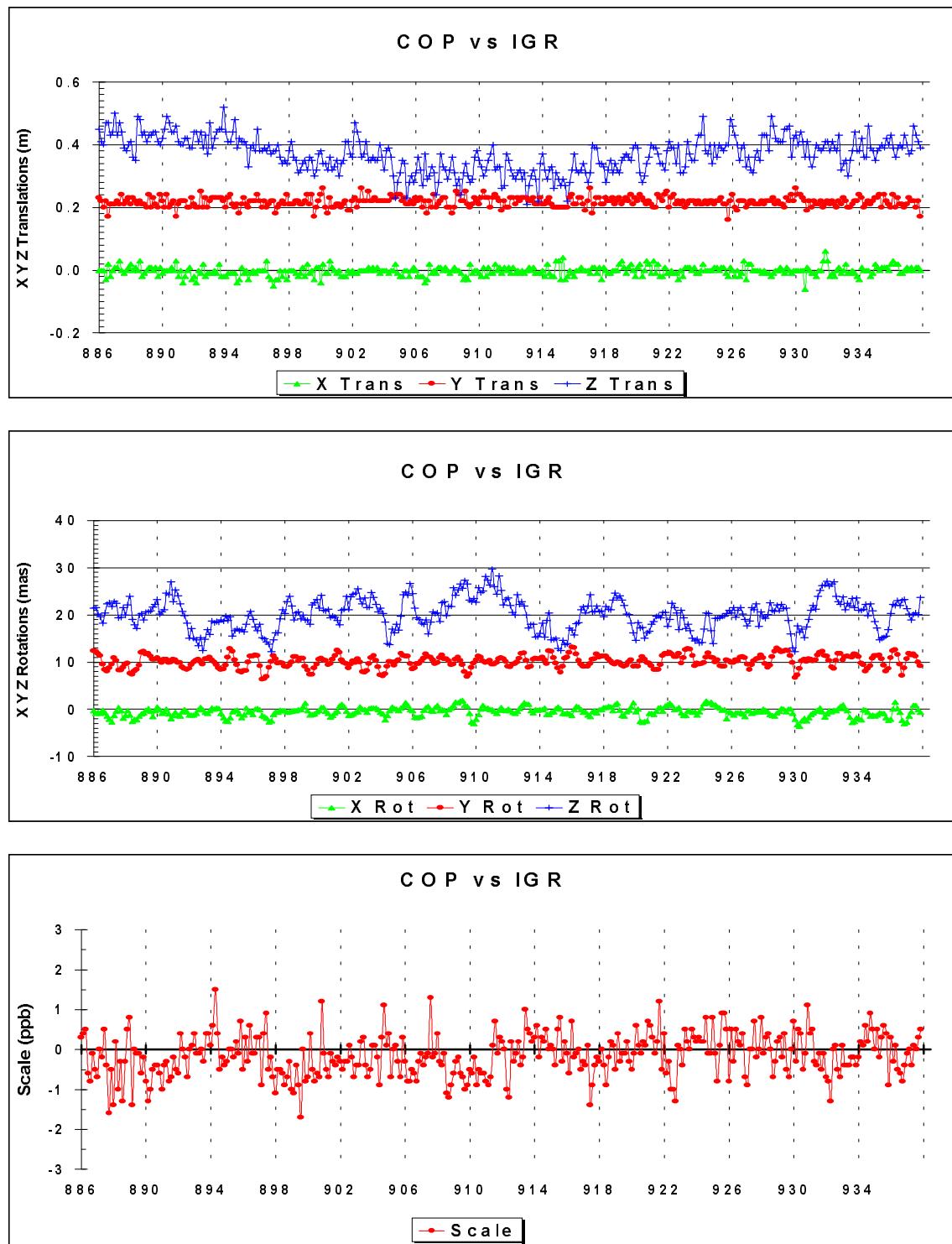
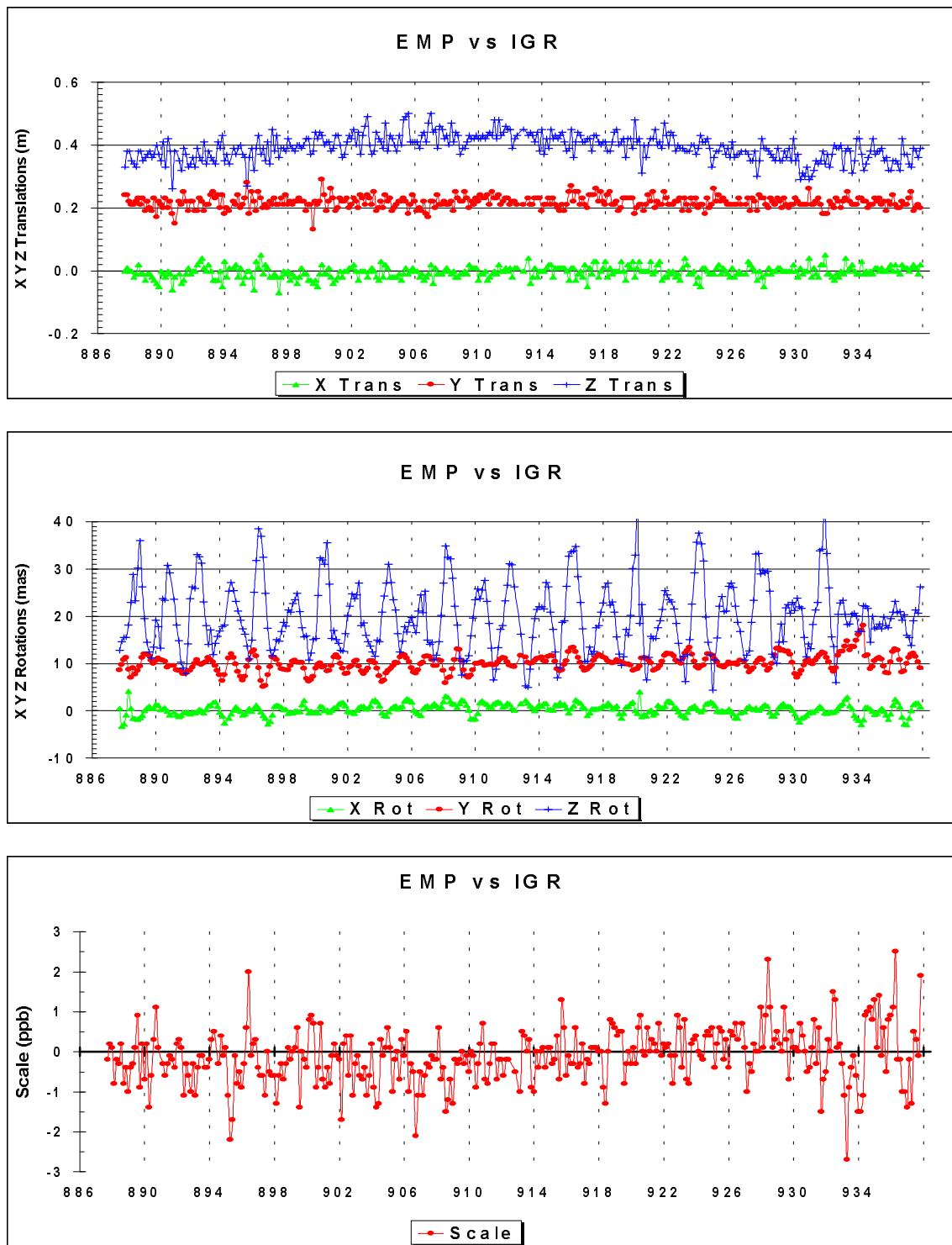


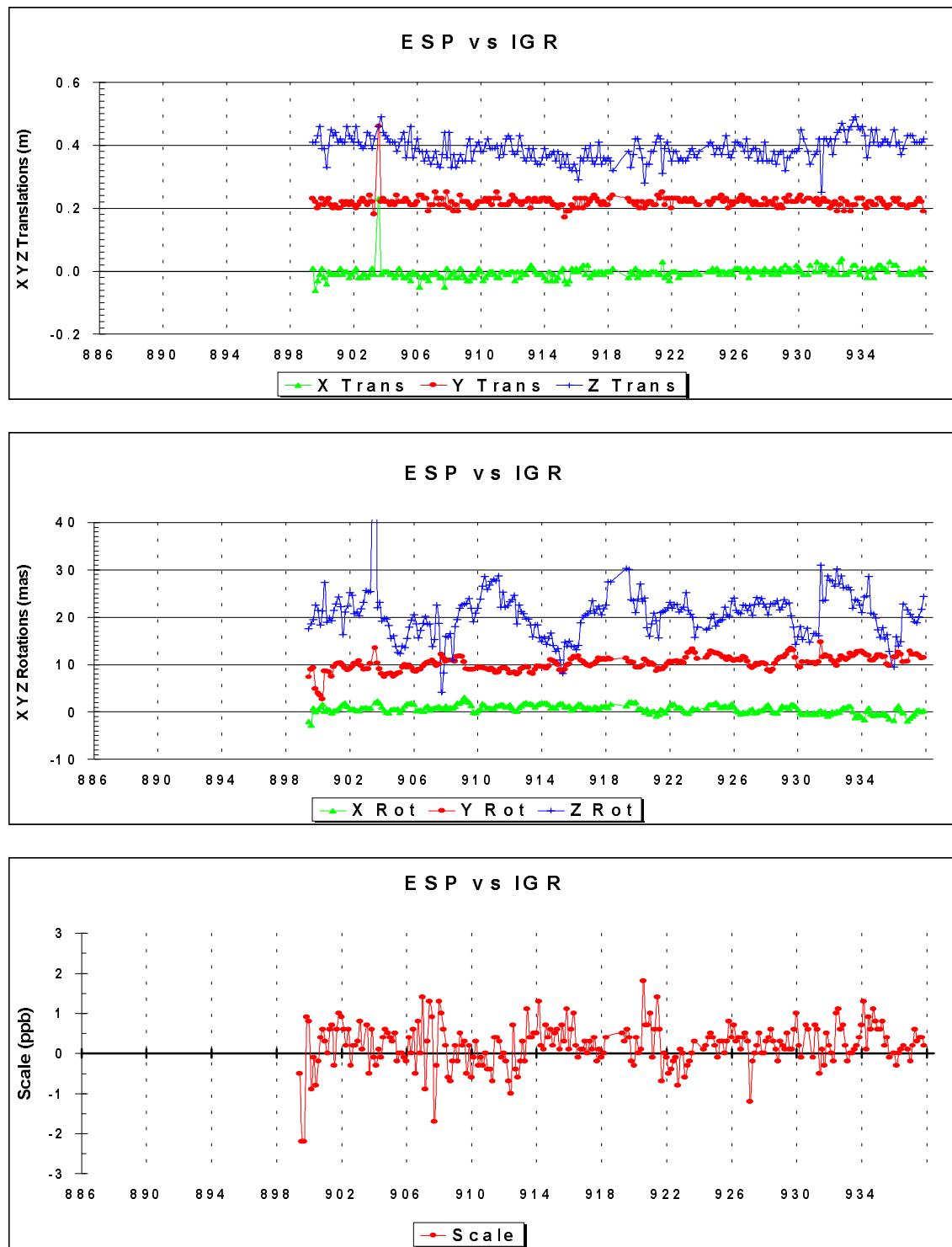
**Figure 2.** Daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 1 metre; X, Y and Z Rotations are each offset by 20 mas)



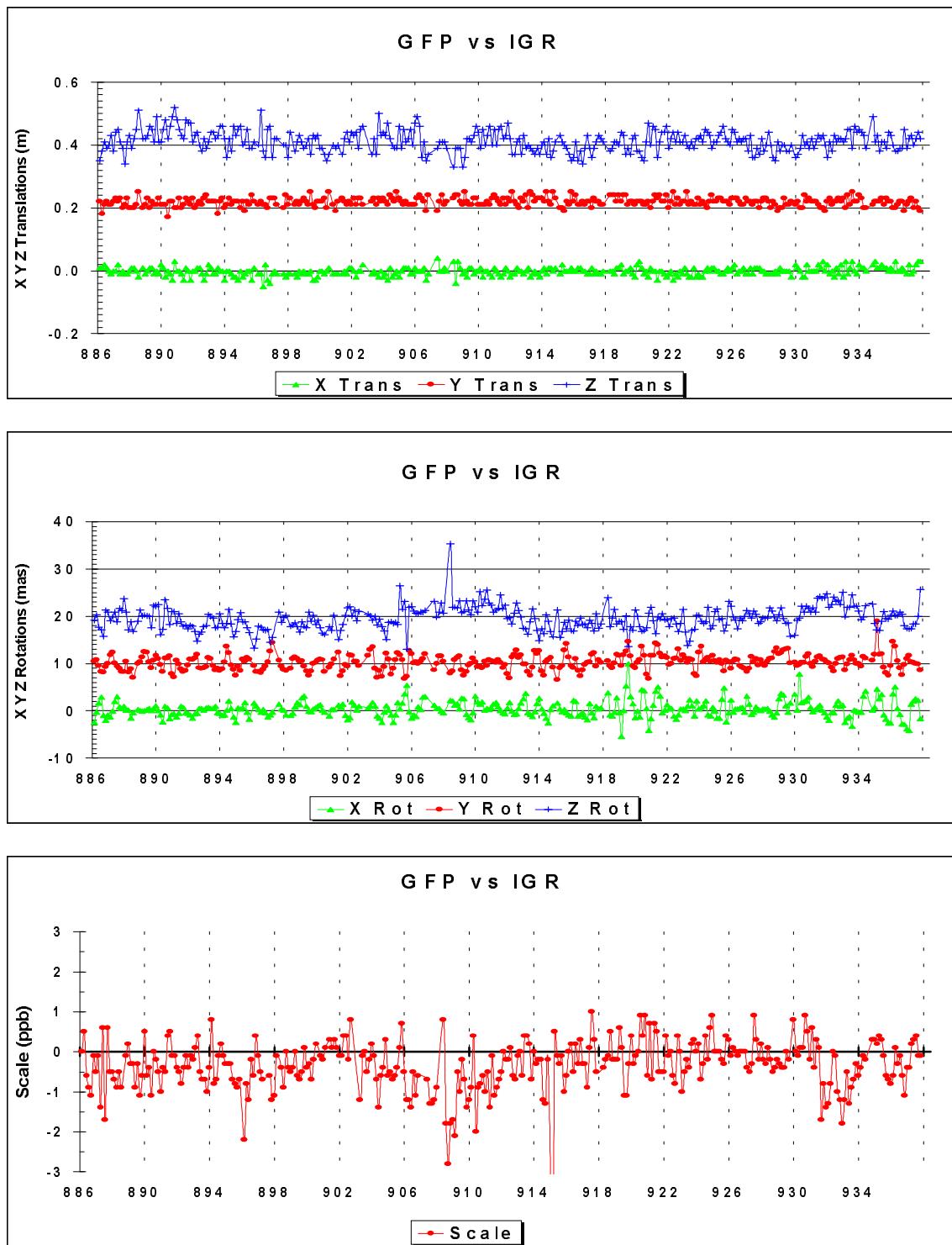
**Figure 3.** COP 1997: Prediction daily seven-parameter Helmert (X, Y and Z Translations are each offset by 0.2 metre; X, Y and Z Rotations are each offset by 10 mas)



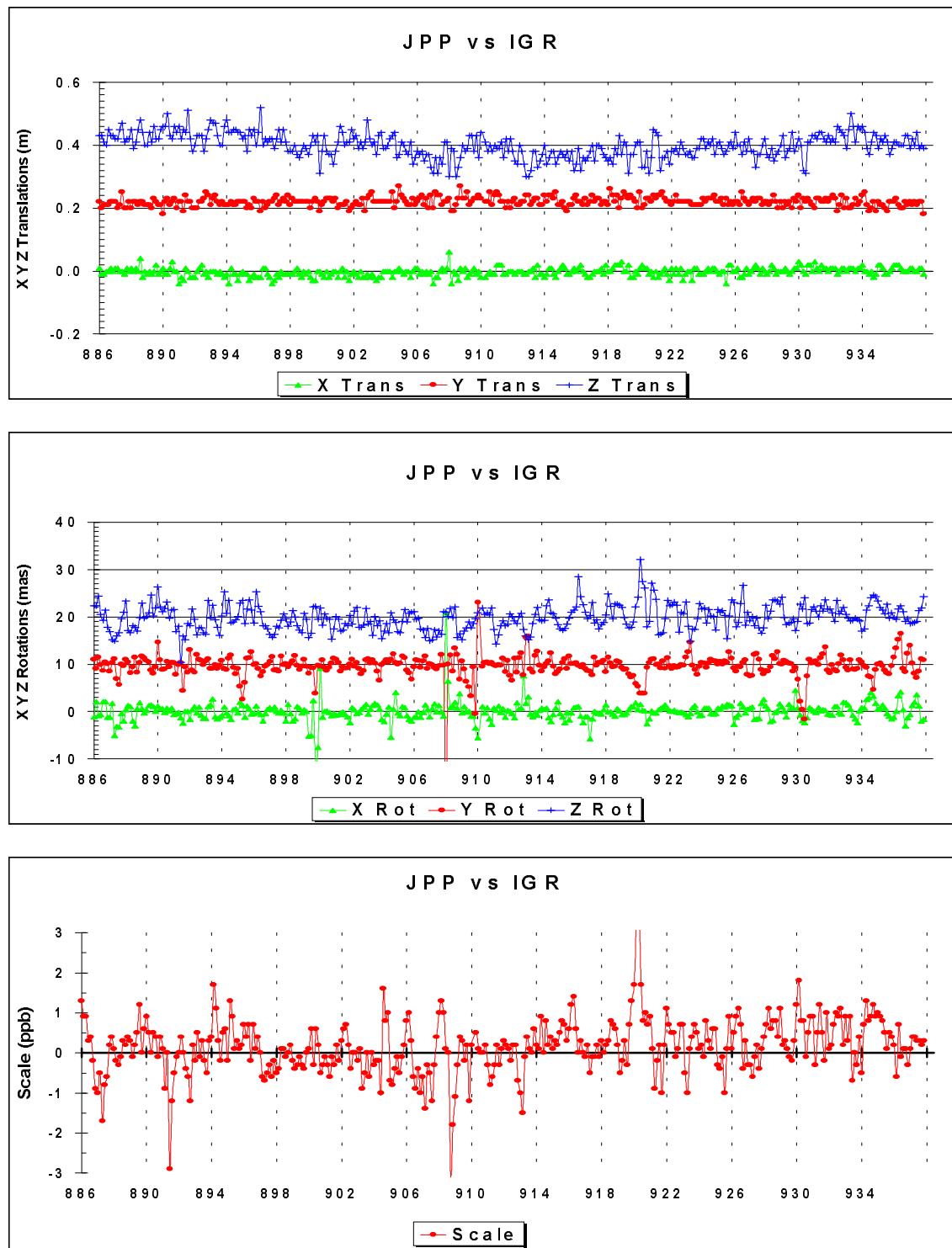
**Figure 4.** Prediction daily seven-parameter Helmert (X, Y and Z Translations are each offset by 1 metre; X, Y and Z Rotations are each offset by 10 mas)



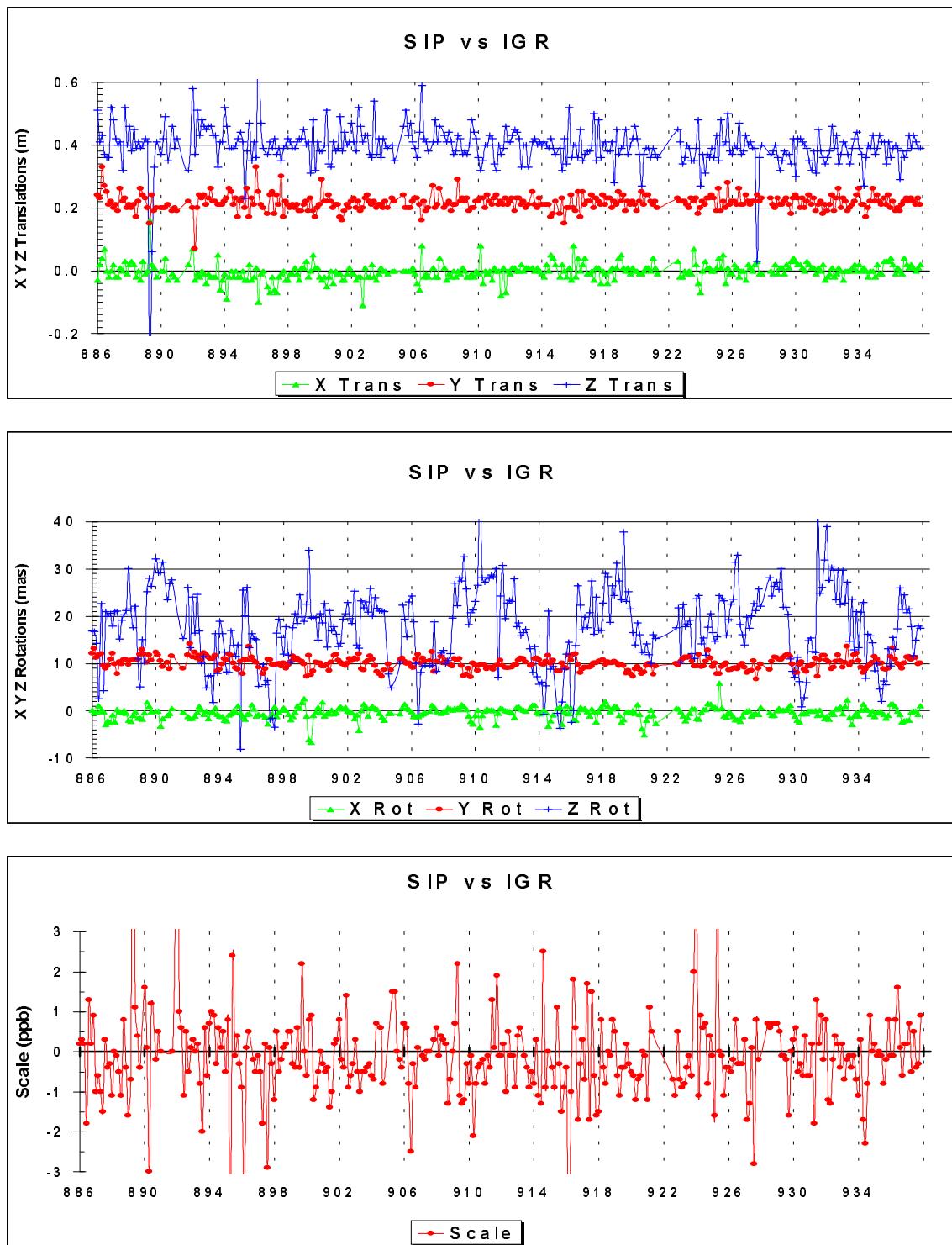
**Figure 5.** Prediction daily seven-parameter Helmert (X, Y and Z Translations are each offset by 1 metre; X, Y and Z Rotations are each offset by 10 mas)



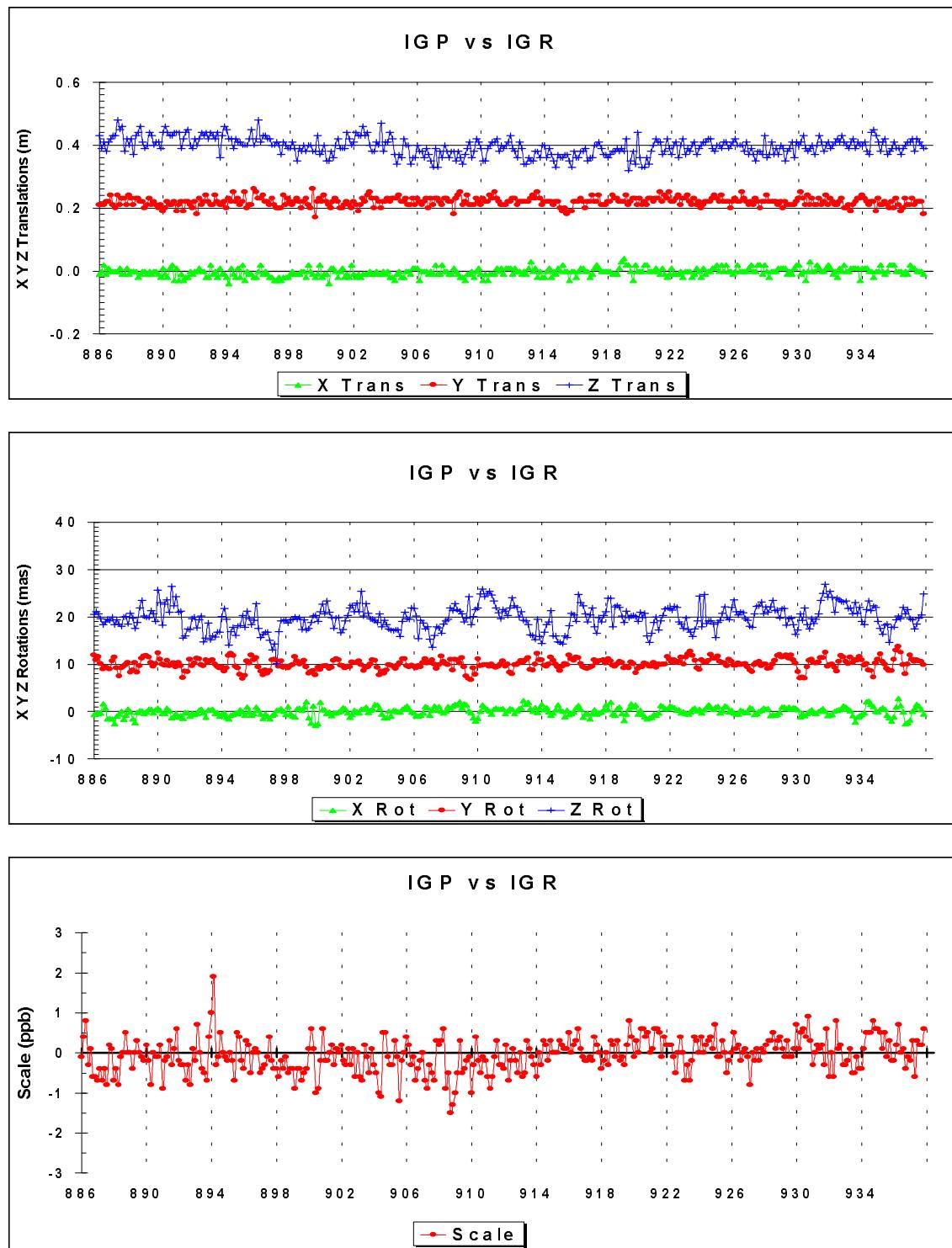
**Figure 6.** Prediction daily seven-parameter Helmert (X, Y and Z Translations are each offset by 1 metre; X, Y and Z Rotations are each offset by 10 mas)



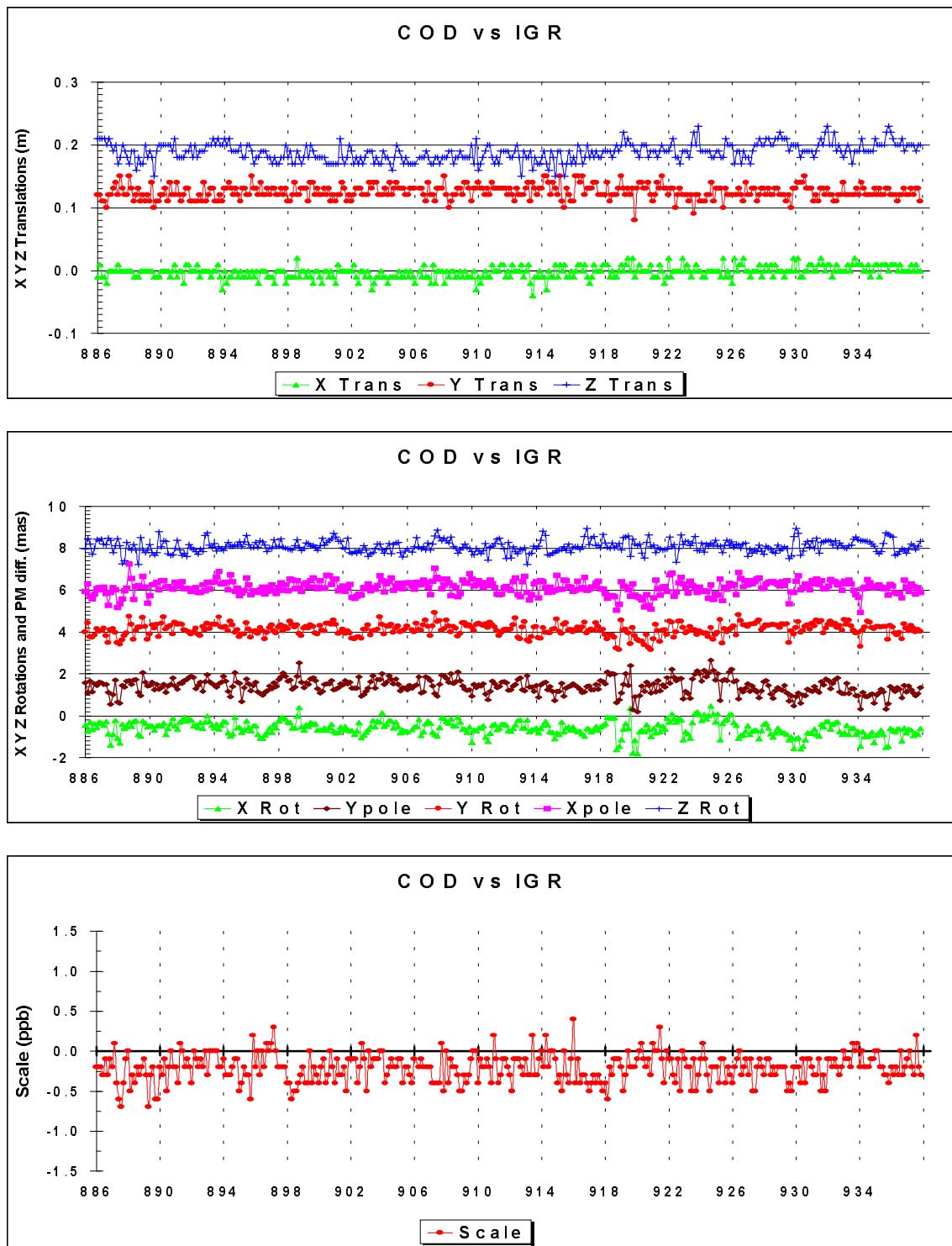
**Figure 7.** Prediction daily seven-parameter Helmert (X, Y and Z Translations are each offset by 1 metre; X, Y and Z Rotations are each offset by 10 mas)



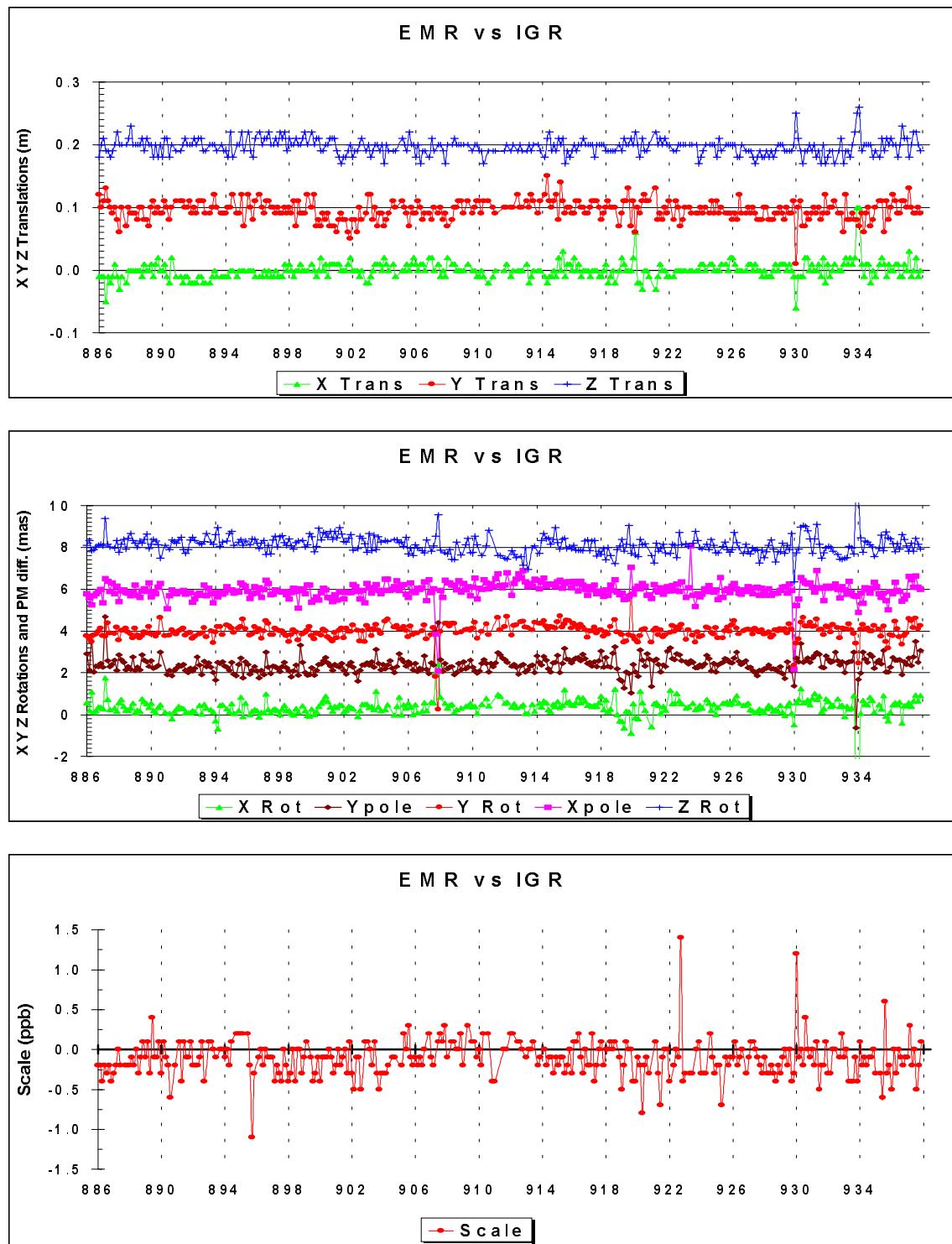
**Figure 8.** Prediction daily seven-parameter Helmert (X, Y and Z Translations are each offset by 1 metre; X, Y and Z Rotations are each offset by 10 mas)



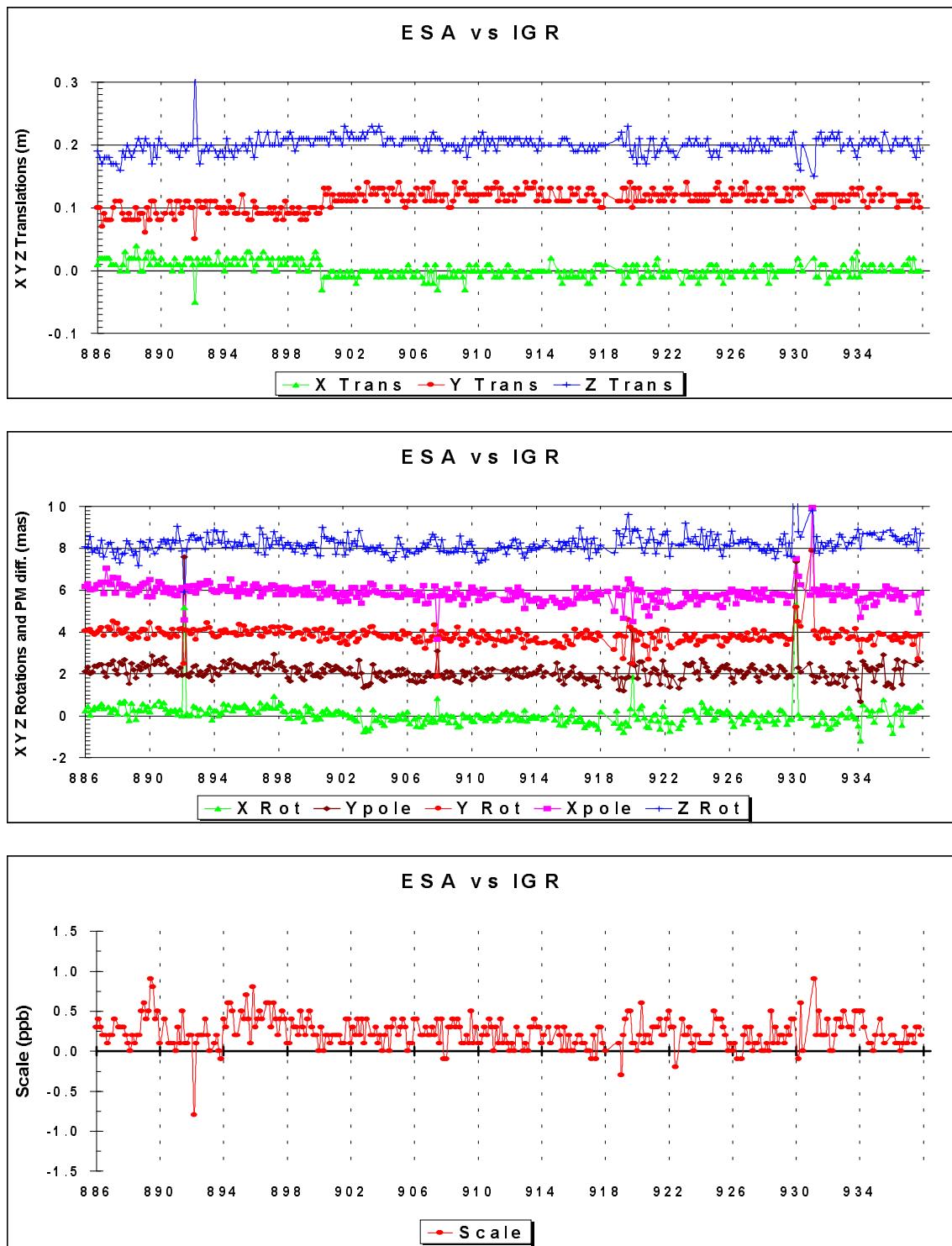
**Figure 9.** Prediction daily seven-parameter Helmert (X, Y and Z Translations are each offset by 1 metre; X, Y and Z Rotations are each offset by 10 mas)



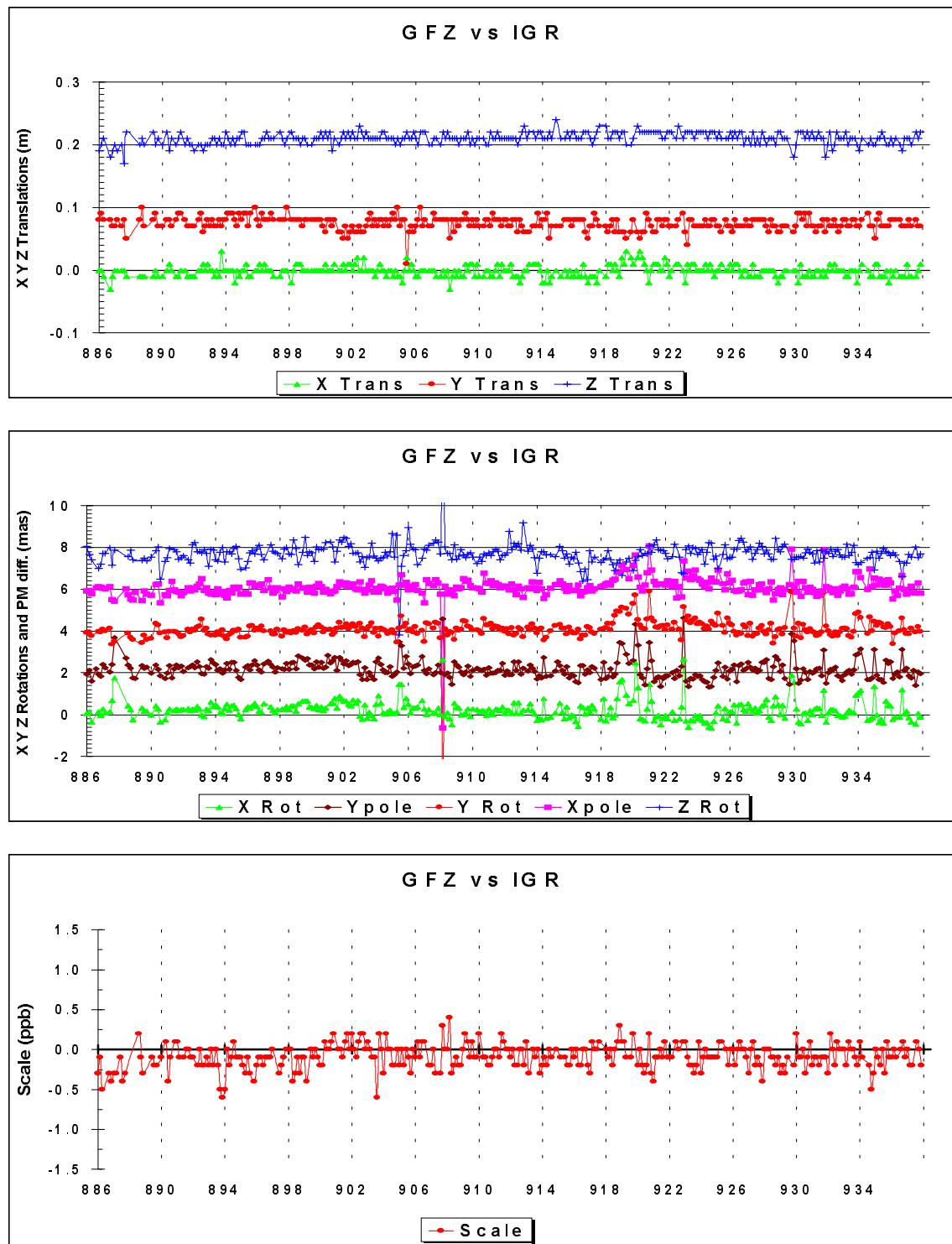
**Figure 10.** Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



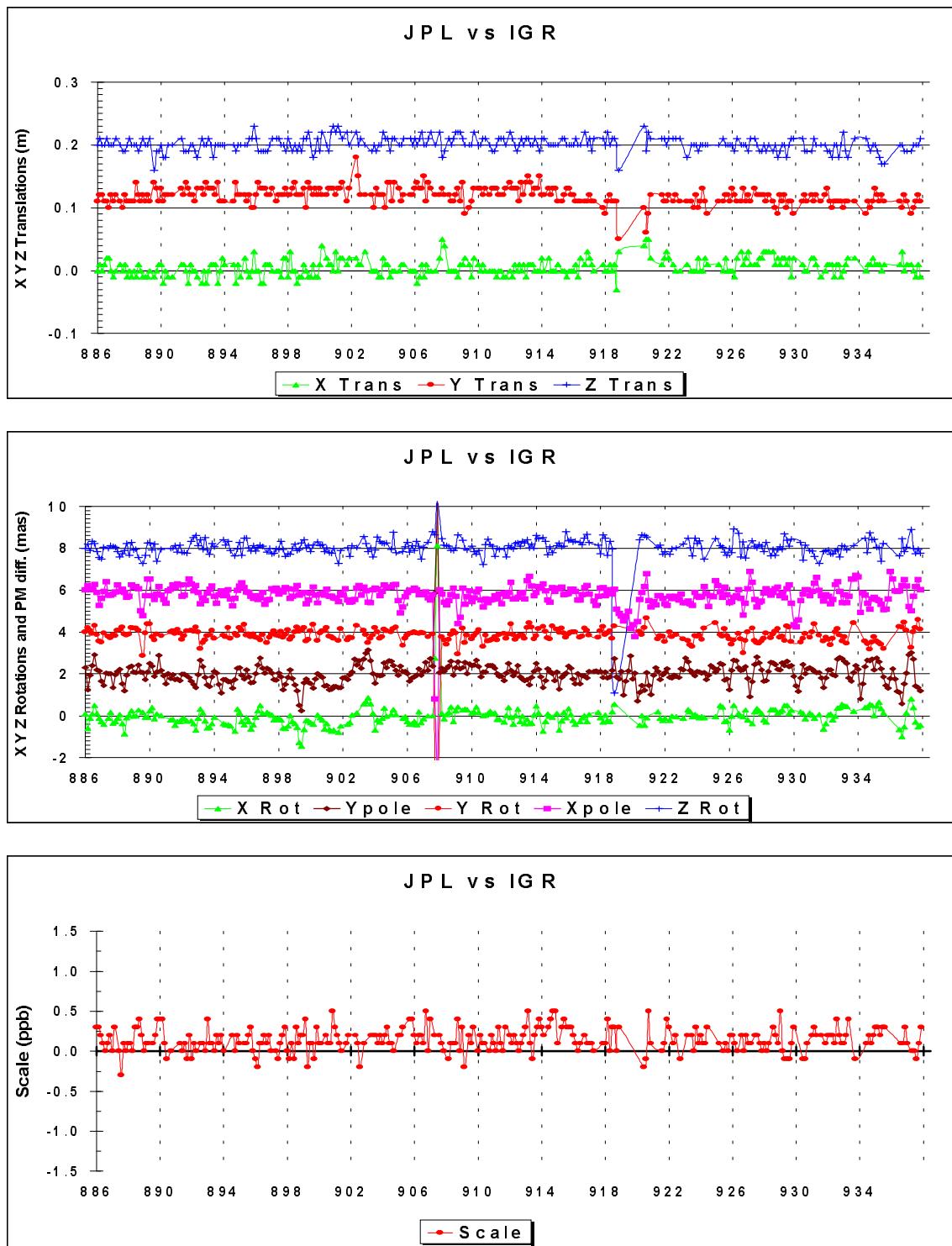
**Figure 11.** EMR 1997: Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



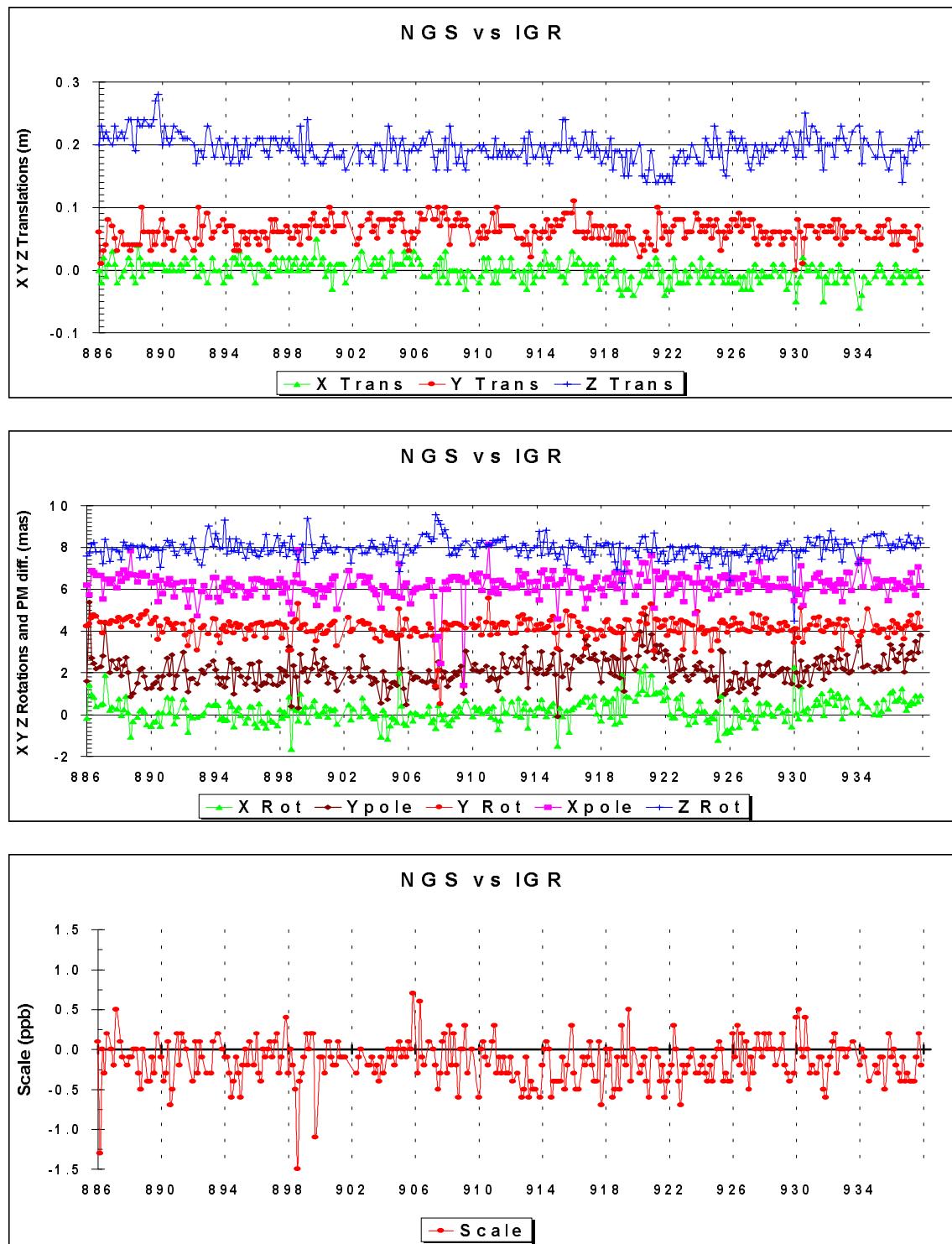
**Figure 12.** Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



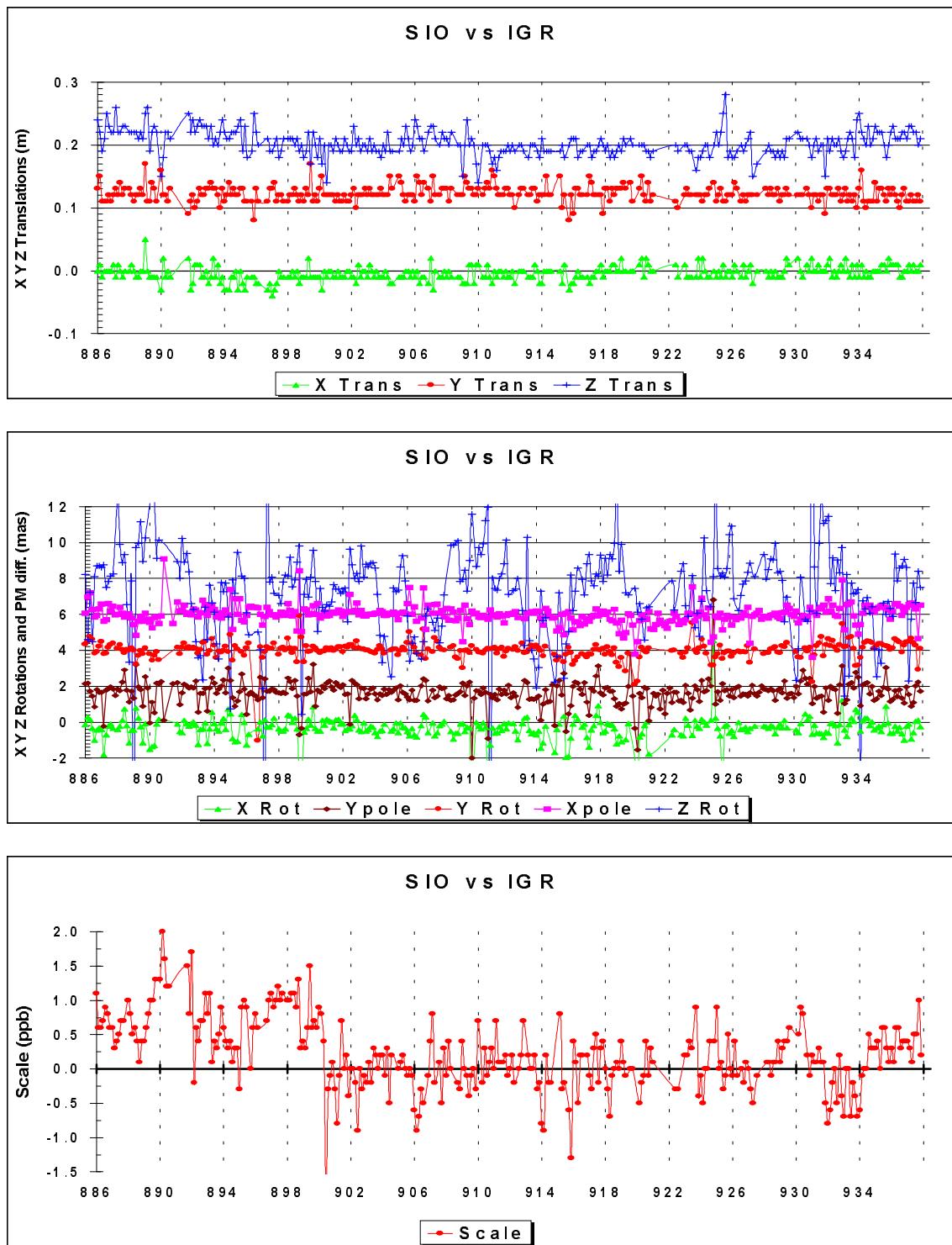
**Figure 13.** Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



**Figure 14.** Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



**Figure 15.** Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)



**Figure 16.** Rapid daily seven-parameter Helmert transformations (X, Y and Z Translations are each offset by 0.1 metre; X, Y, Z Rotations and Y and X pole differences are each offset by 2 mas)