

# Generation of igs05.atx – status quo

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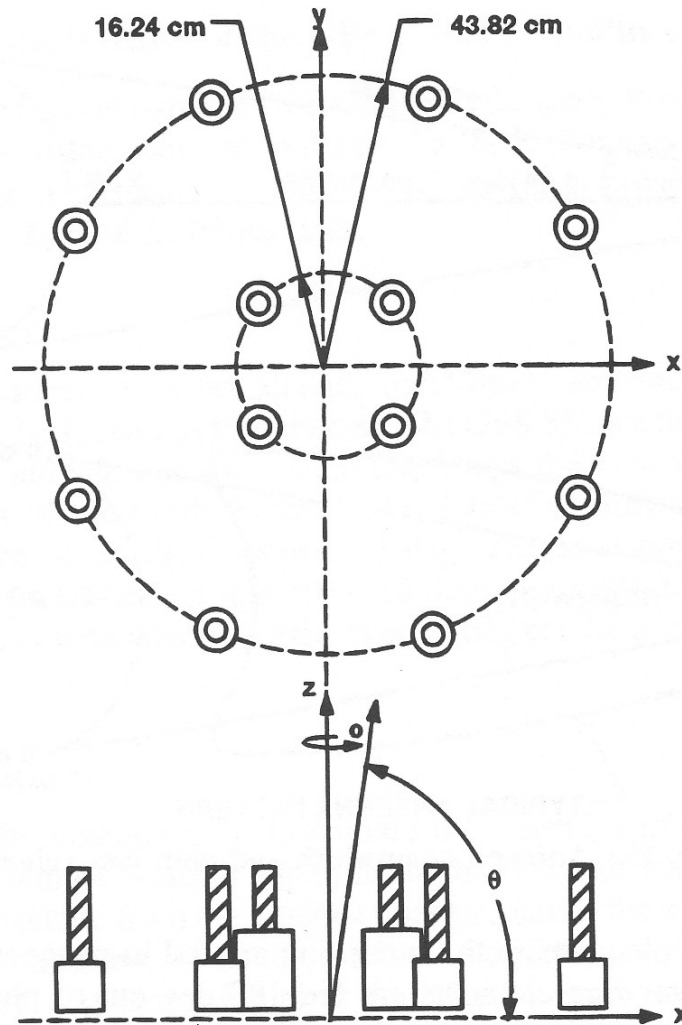
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# GPS satellite antenna types



Block I antenna (Czopek et al., 1993)

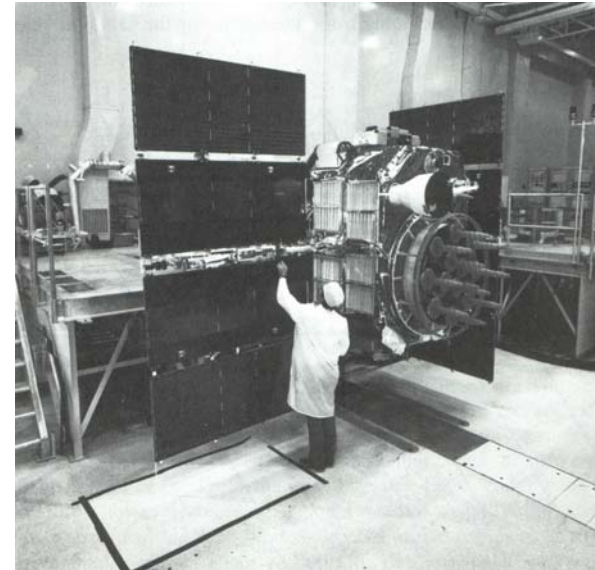


Photo: Rockwell International

4 different satellite antenna types:

- Block I
- Block II, Block IIA
- Block IIR-A
- Block IIR-B, Block IIR-M

# Block IIR-A/B

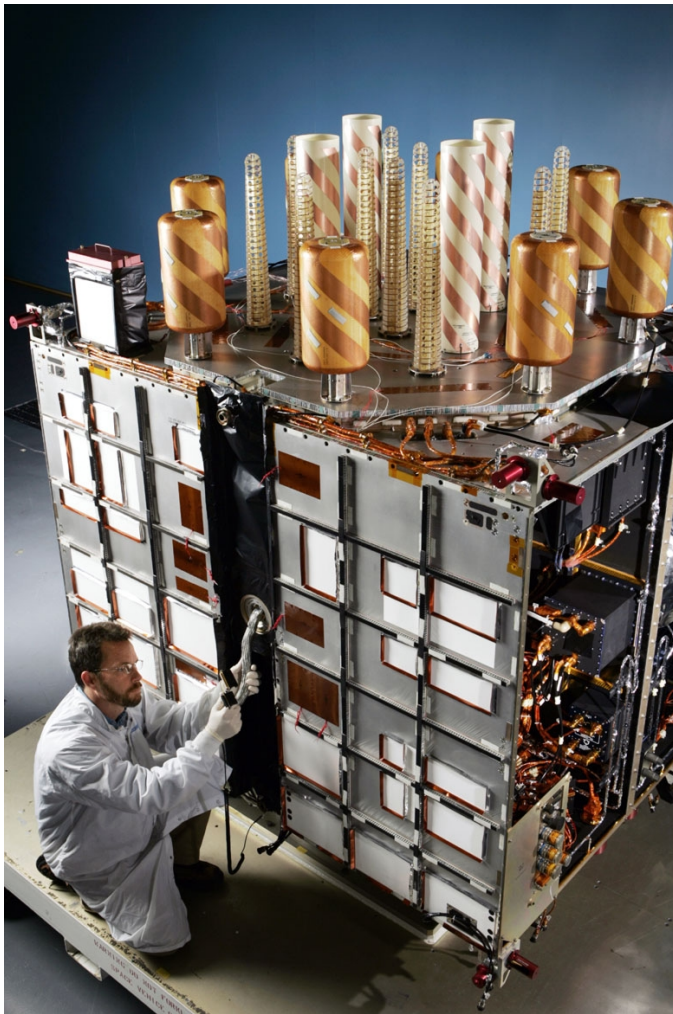
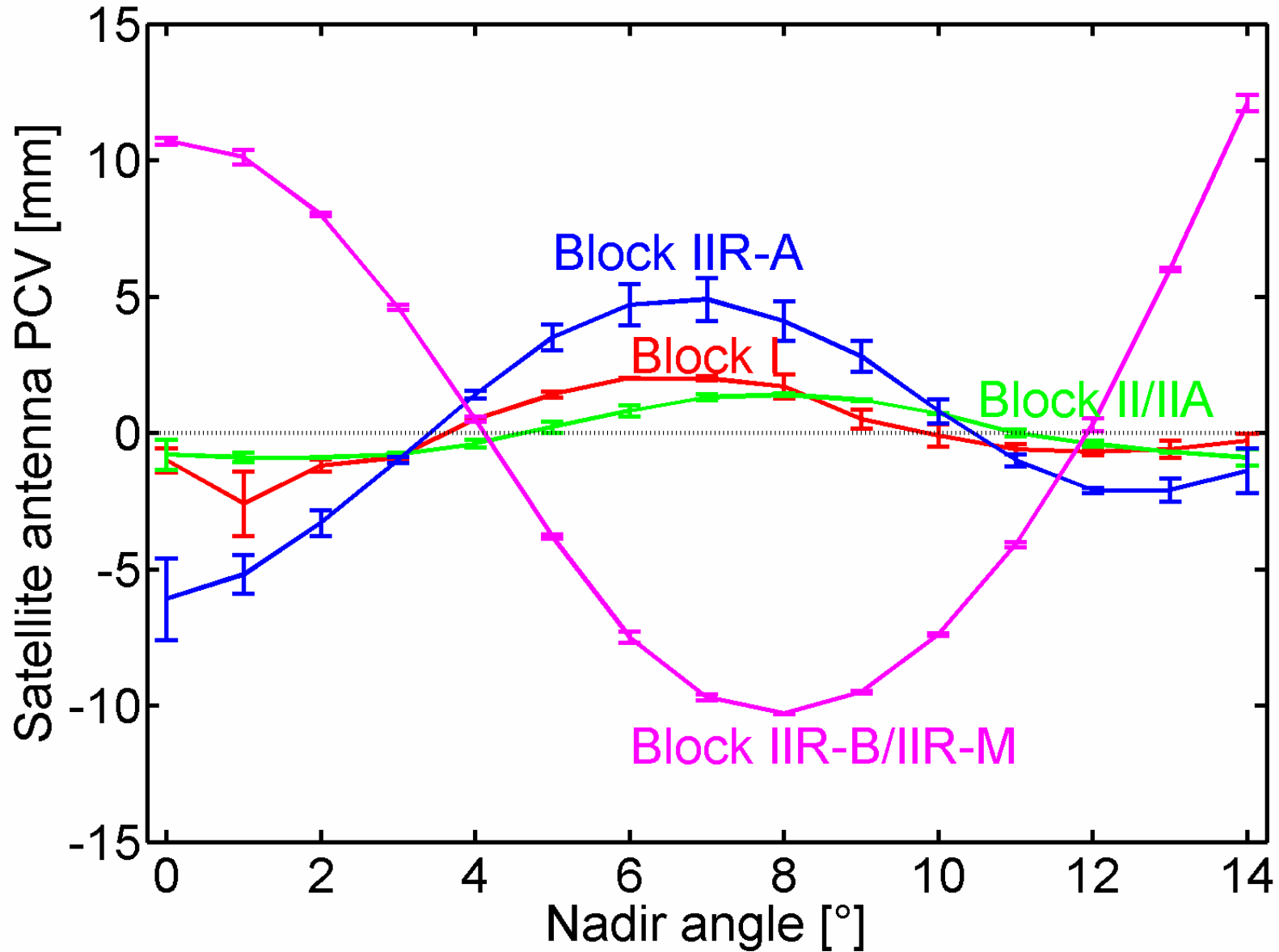


Photo: [www.lockheedmartin.com](http://www.lockheedmartin.com)

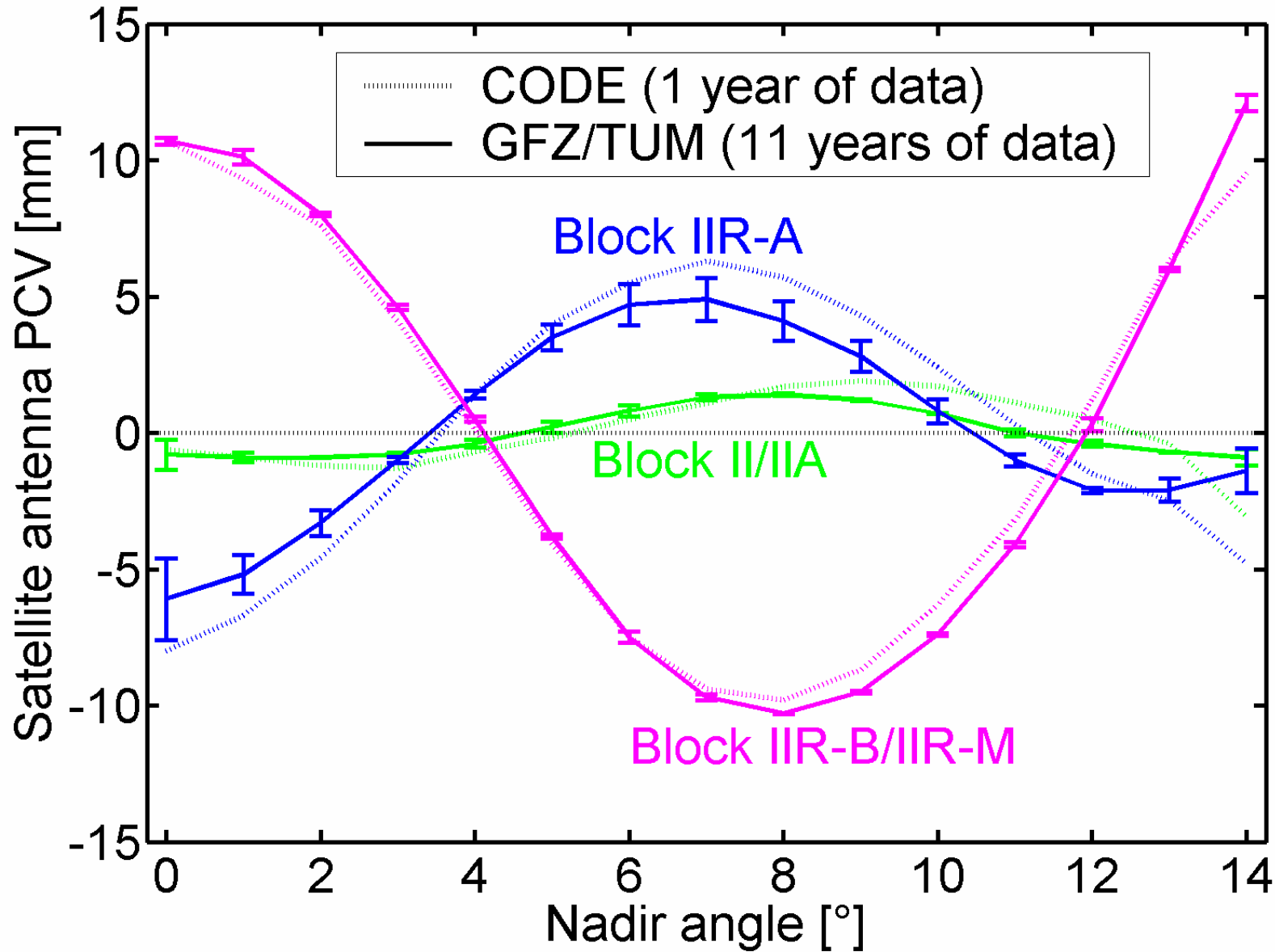
SVN	Legacy Antenna Panel	Improved Antenna Panel	IIR-M SV
41	x		
43	x		
44	x		
45	x		
46	x		
47		x	
48		x	x
49		x	x
50		x	x
51	x		
52		x	x
53		x	x
54	x		
55		x	x
56	x		
57		x	x
58		x	x
59		x	
60		x	
61		x	

Marquis & Reigh (2005)

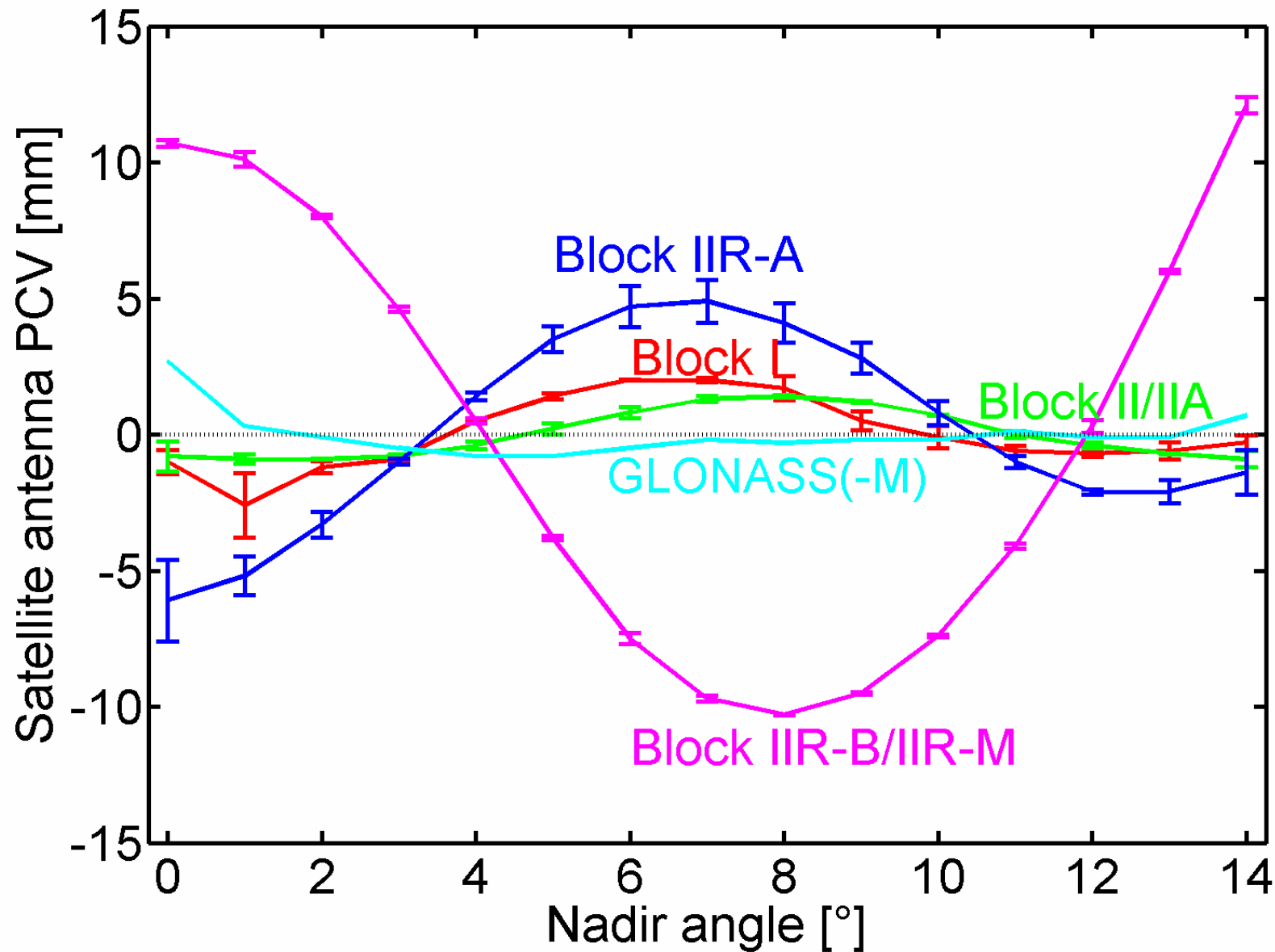
# Mean PCVs from GFZ and TUM



# Consistency check by CODE



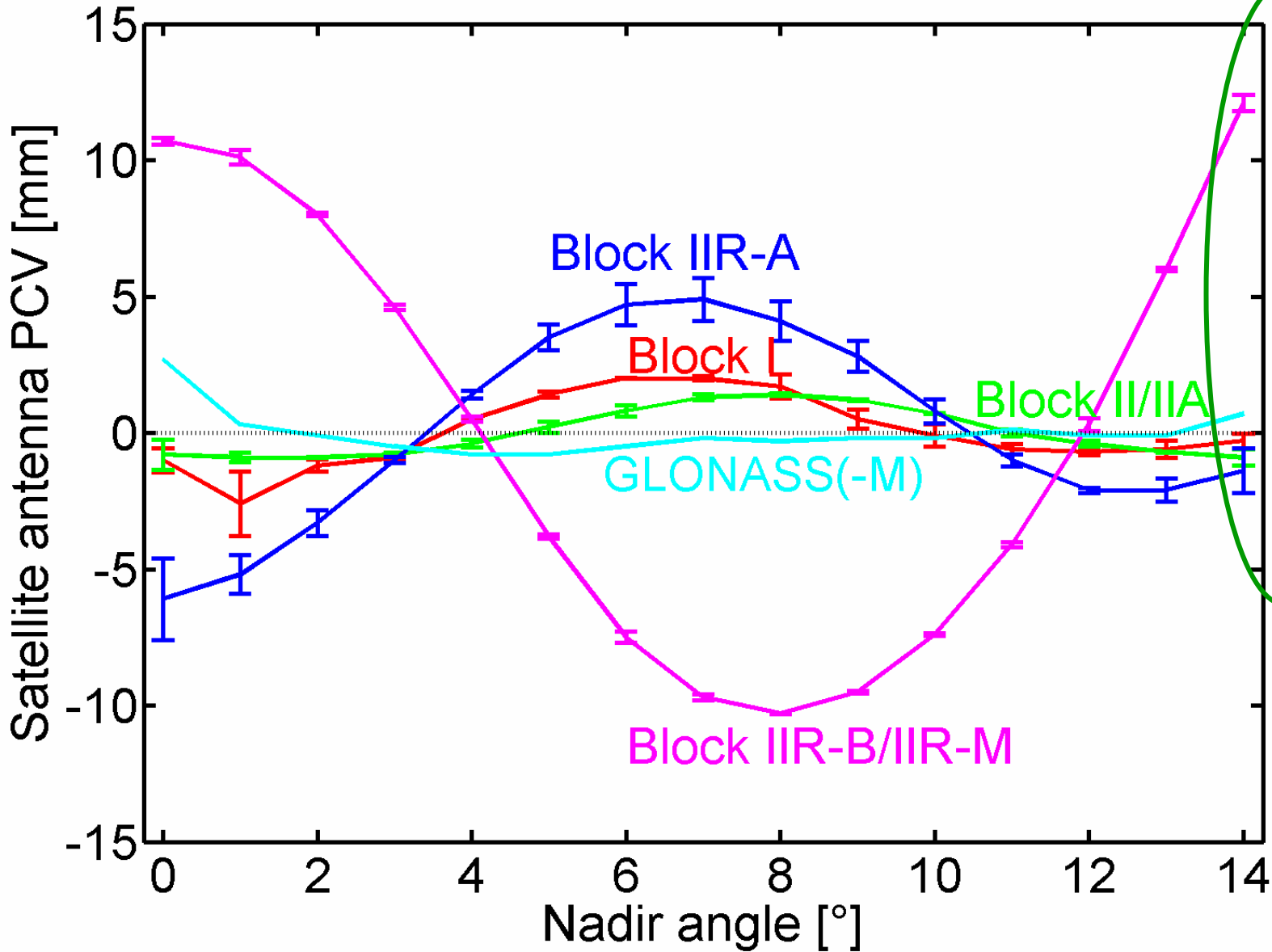
# GLONASS PCVs from CODE



Based on GPS  
PCVs for the  
tracking  
antennas

Nadir-dep.  
only!

# Large nadir angles



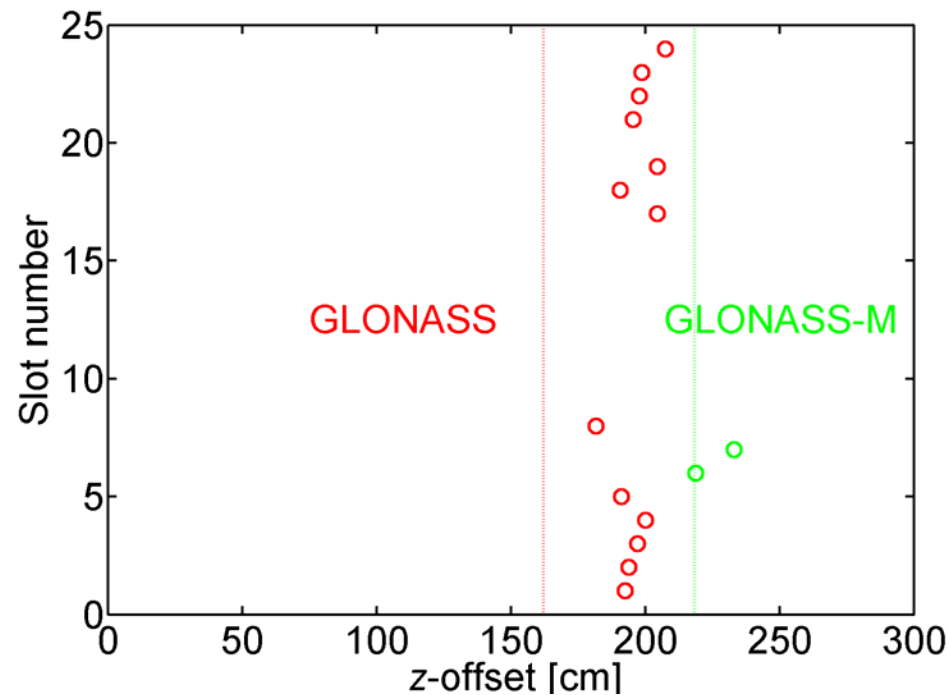
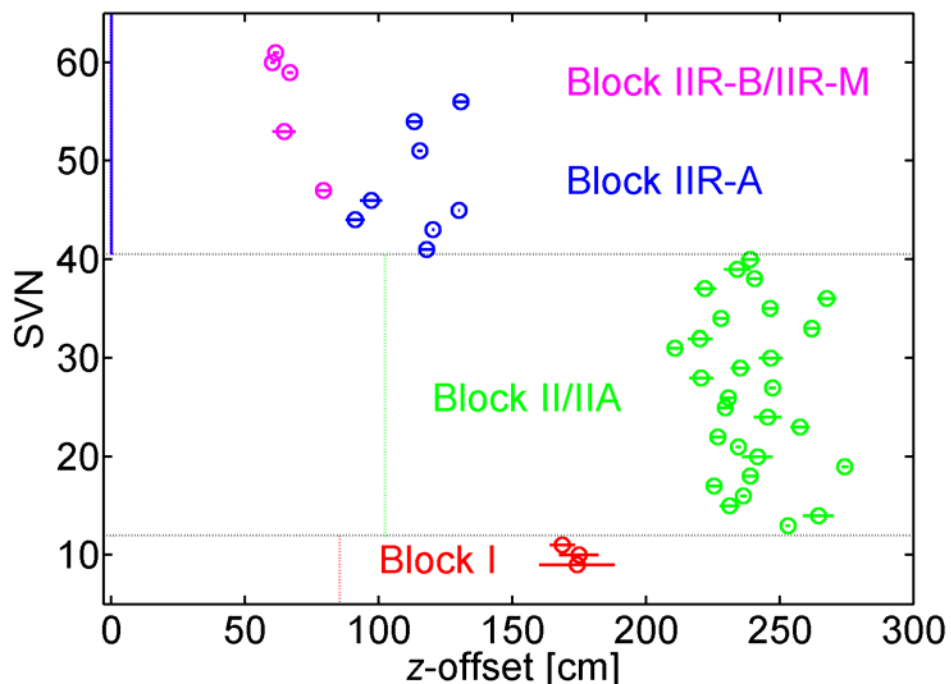
Should we add values from the JPL maps?



# GLONASS z-offsets from CODE

GFZ/TUM  
GPS:  
vs.  
IGS convention

CODE  
GLONASS:  
vs.  
nominal value



## 59 **satellite** antennas:

- 44 GPS
- 15 GLONASS (latest GLONASS-M missing: R714)

## 154 **receiver** antennas:

- 42 **robot** calibrations from Geo++ (az.+el.)
  - 32 without radome
  - 10 with radome
- **112** converted **field** calibrations from NGS (el. only)
  - 74 without radome
  - 38 with radome

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**Temporary solution!**

# Conversion of relative field calibrations

By adding the difference between the absolute and the relative values for the reference antenna AOAD/M\_T.



Photo: National Geodetic Survey

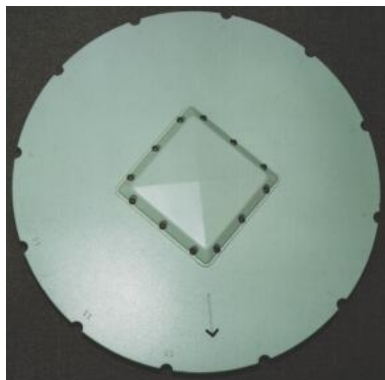
Phase center **offsets**:

$$PCO_{abs} = PCO_{rel} + (PCO_{abs}(AOAD/M_T) - PCO_{rel}(AOAD/M_T))$$

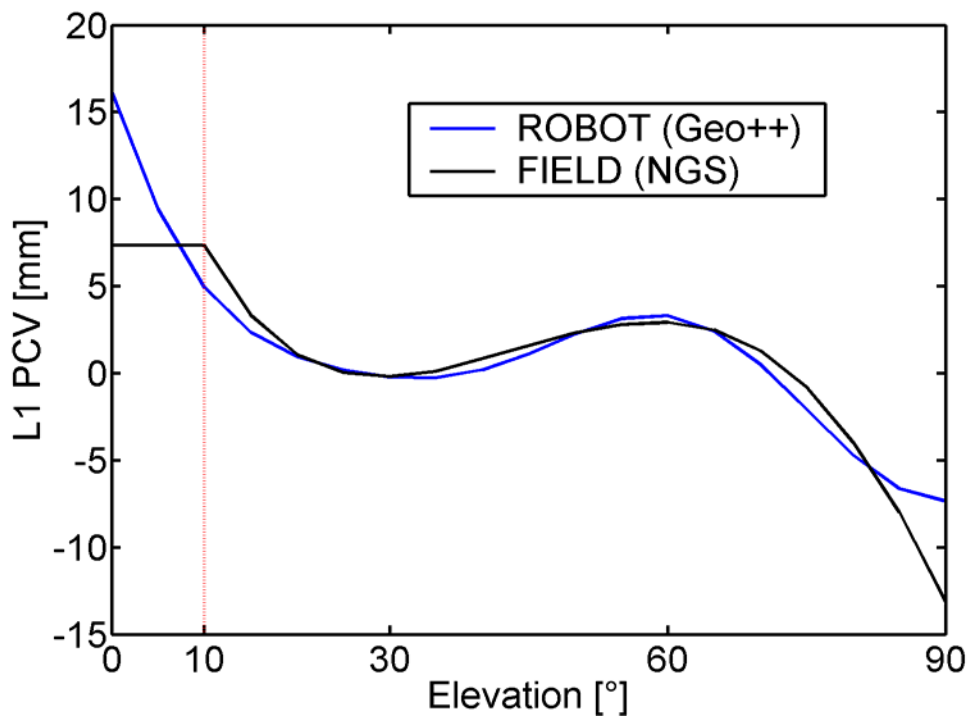
Phase center **variations**:

$$PCV_{abs} = PCV_{rel} + PCV_{abs}(AOAD/M_T)$$

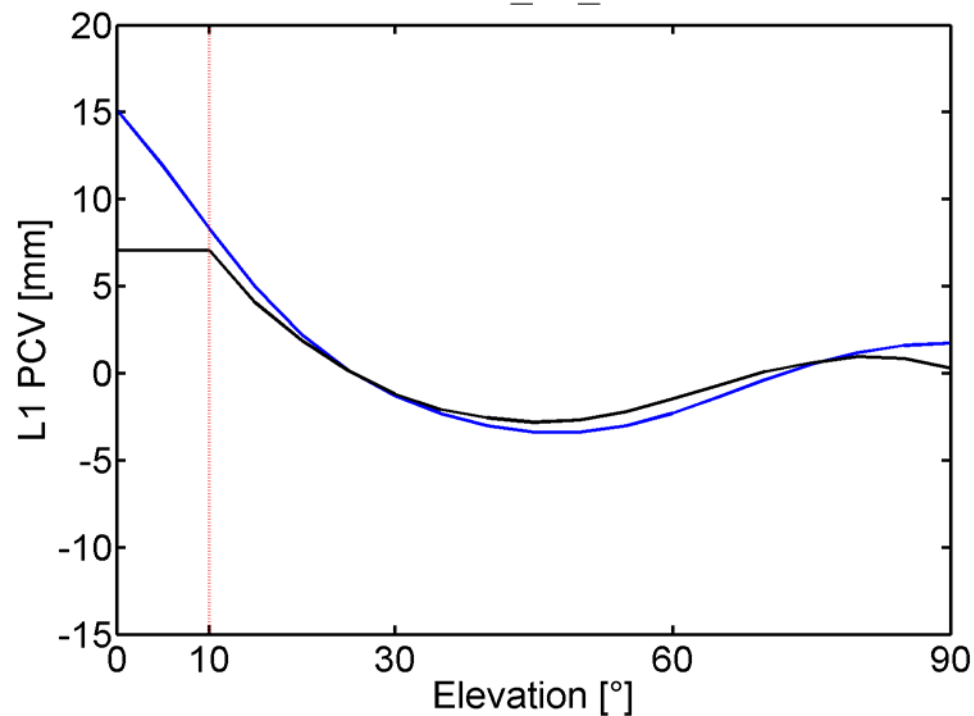
# NGS calibrations – limited elevation range



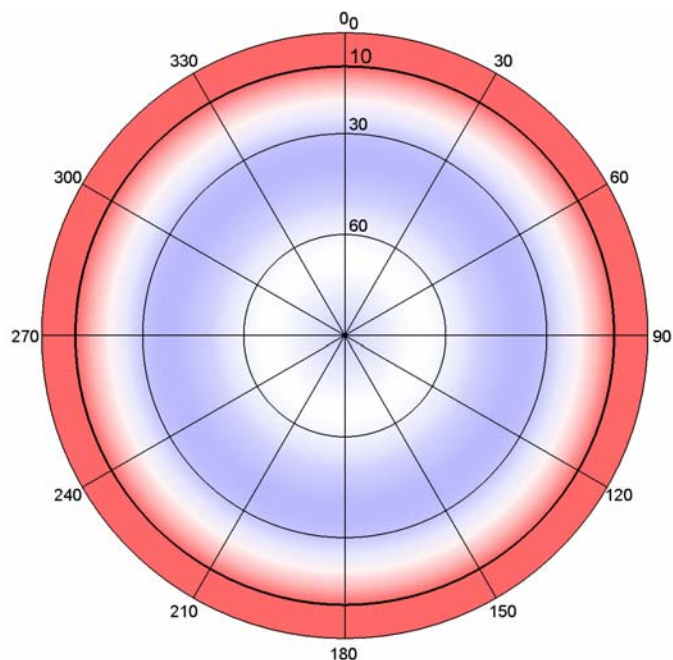
TRM14532.00 NONE



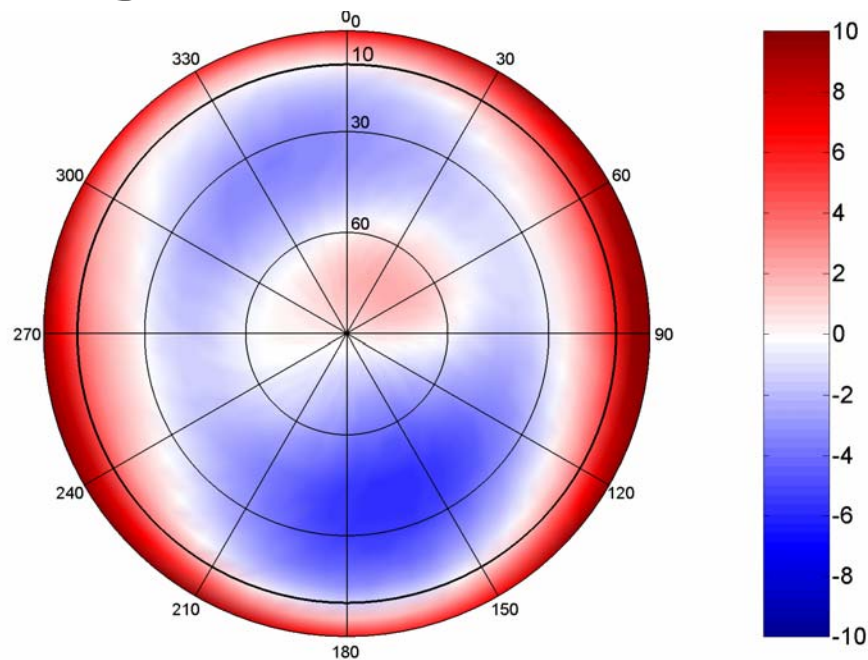
JPSREGANT\_SD\_E NONE



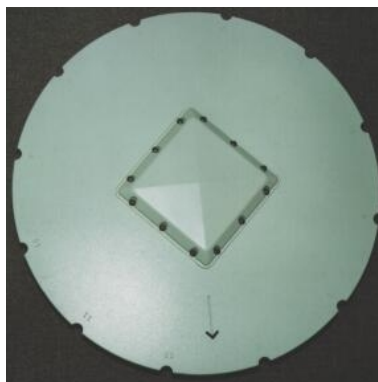
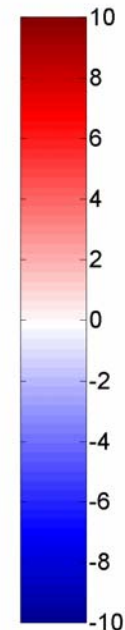
# NGS calibrations – missing azimuth-dependence



L2 PCV FIELD [mm]



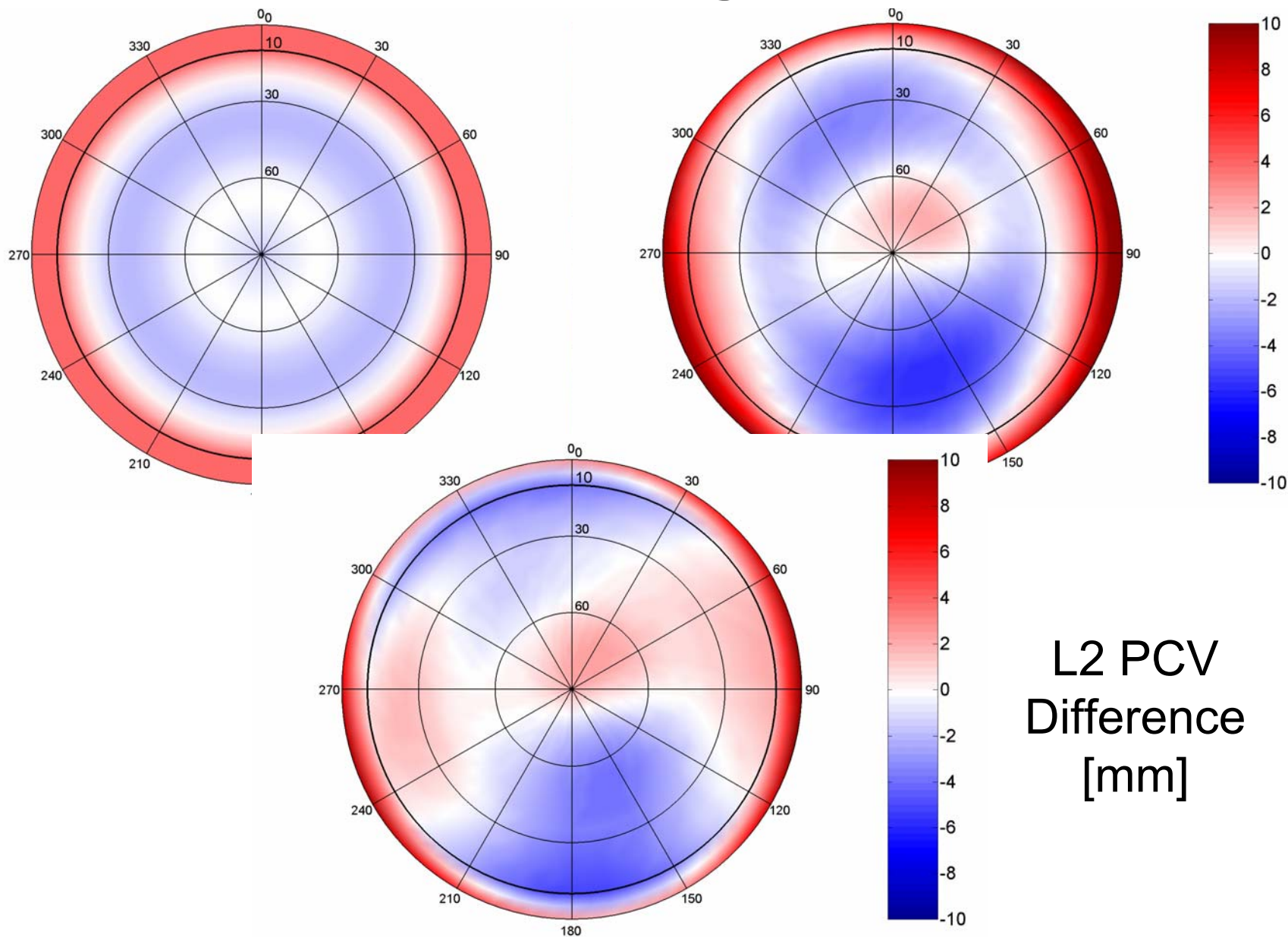
L2 PCV ROBOT [mm]



TRM14532.00

NONE

# NGS calibrations – missing azimuth-dependence



L2 PCV  
Difference  
[mm]

# Antennas in the IGS network

Data source: <ftp://igsceb.jpl.nasa.gov/igsceb/station/general/loghist.txt>

**37** different antenna types (cf. igs05.atx: 106):

- 22 → robot calibration (60%)
- 15 → converted field calibration

**81** antenna + radome combinations:

- 10 → robot calibration
  - 15 → converted field calibration
  - **42** → no calibration available
  - **14** → not calibratable (DOME)
- } 70%

When can field calibrations be replaced by robot calibrations?  
When can new radome calibrations be added?



# Radome problem – station FORT

8 April 2006: IGS station FORT decommissioned  
6 weeks before: radome (DOME) removed

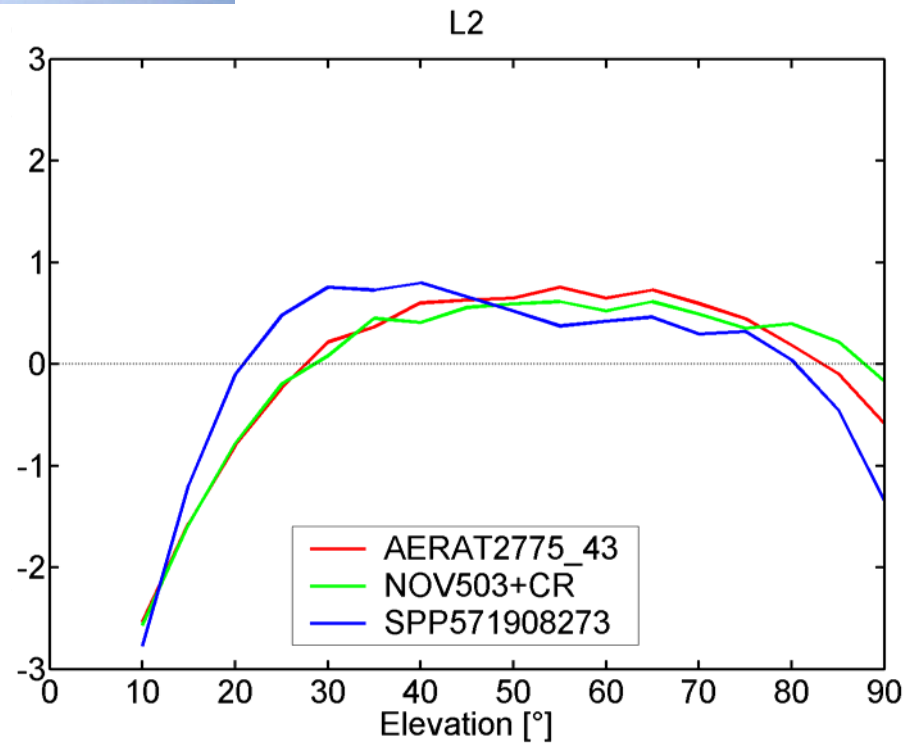
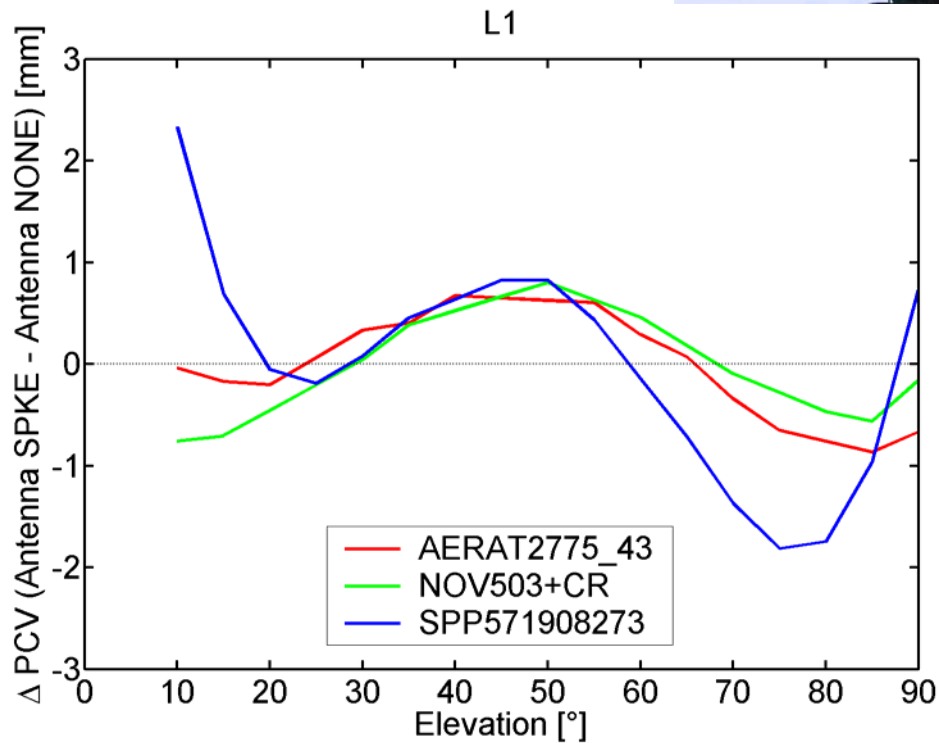


Photos: [www.roen.inpe.br](http://www.roen.inpe.br)

Ray et al. (2006): The effect of the radome has been an apparent height bias of about 16 mm downward.

How to deal with stations with uncalibrated radomes?

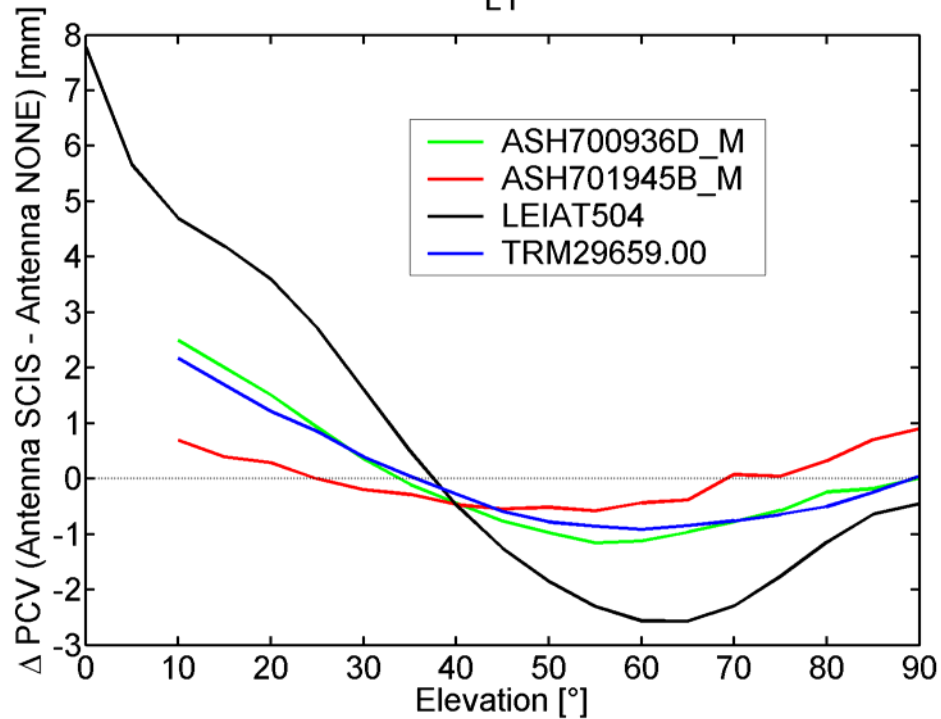
# Radome effect – radome SPKE



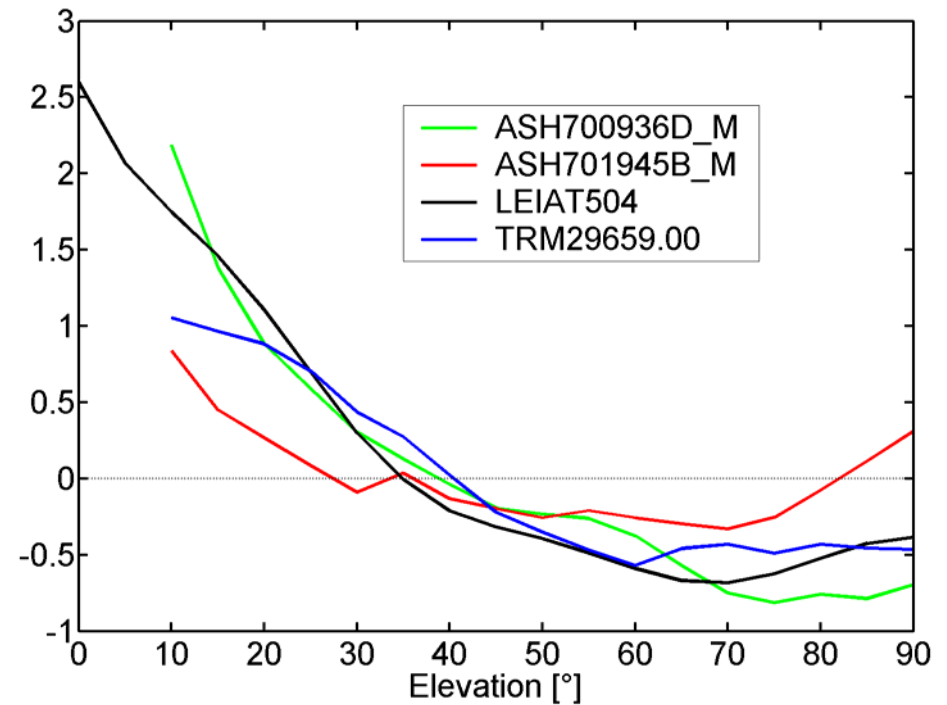
# Radome effect – radome SCIS



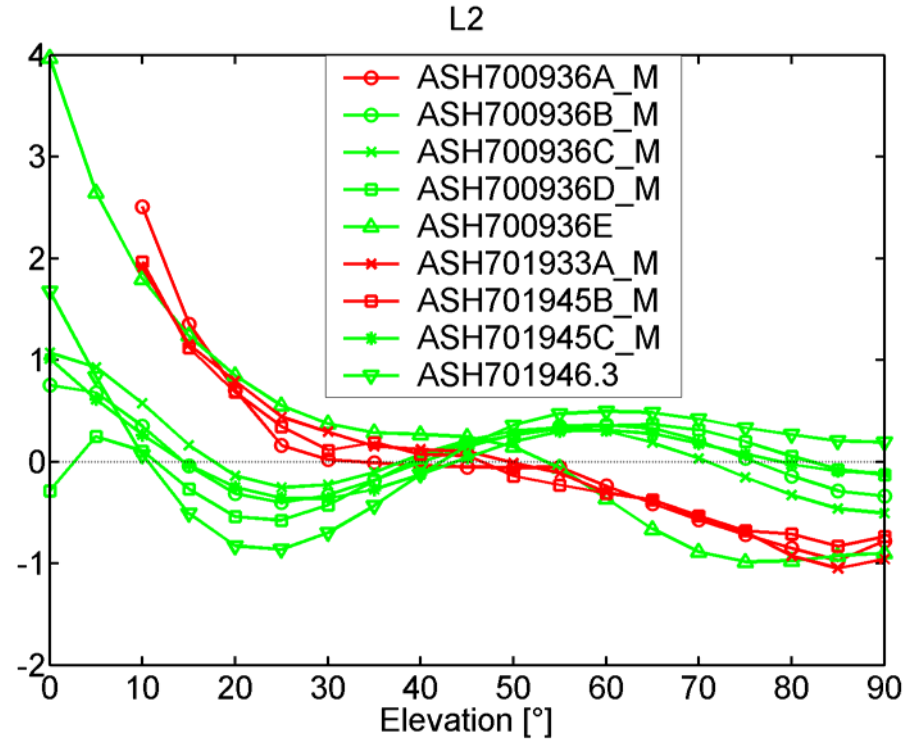
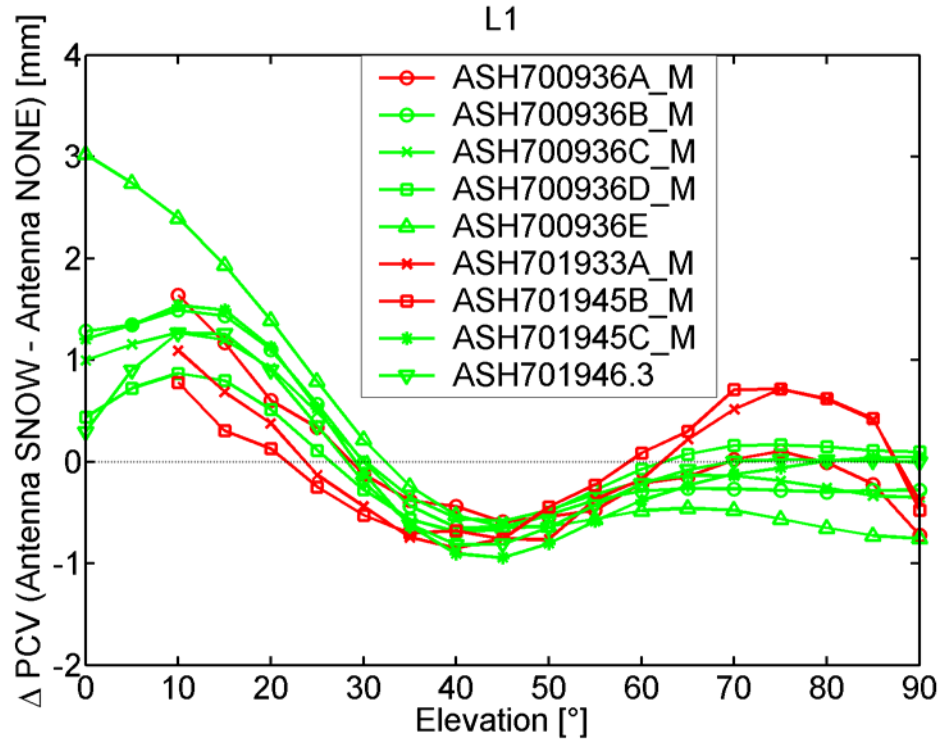
L1



L2



# Radome effect – radome SNOW



# Propagation to other antennas

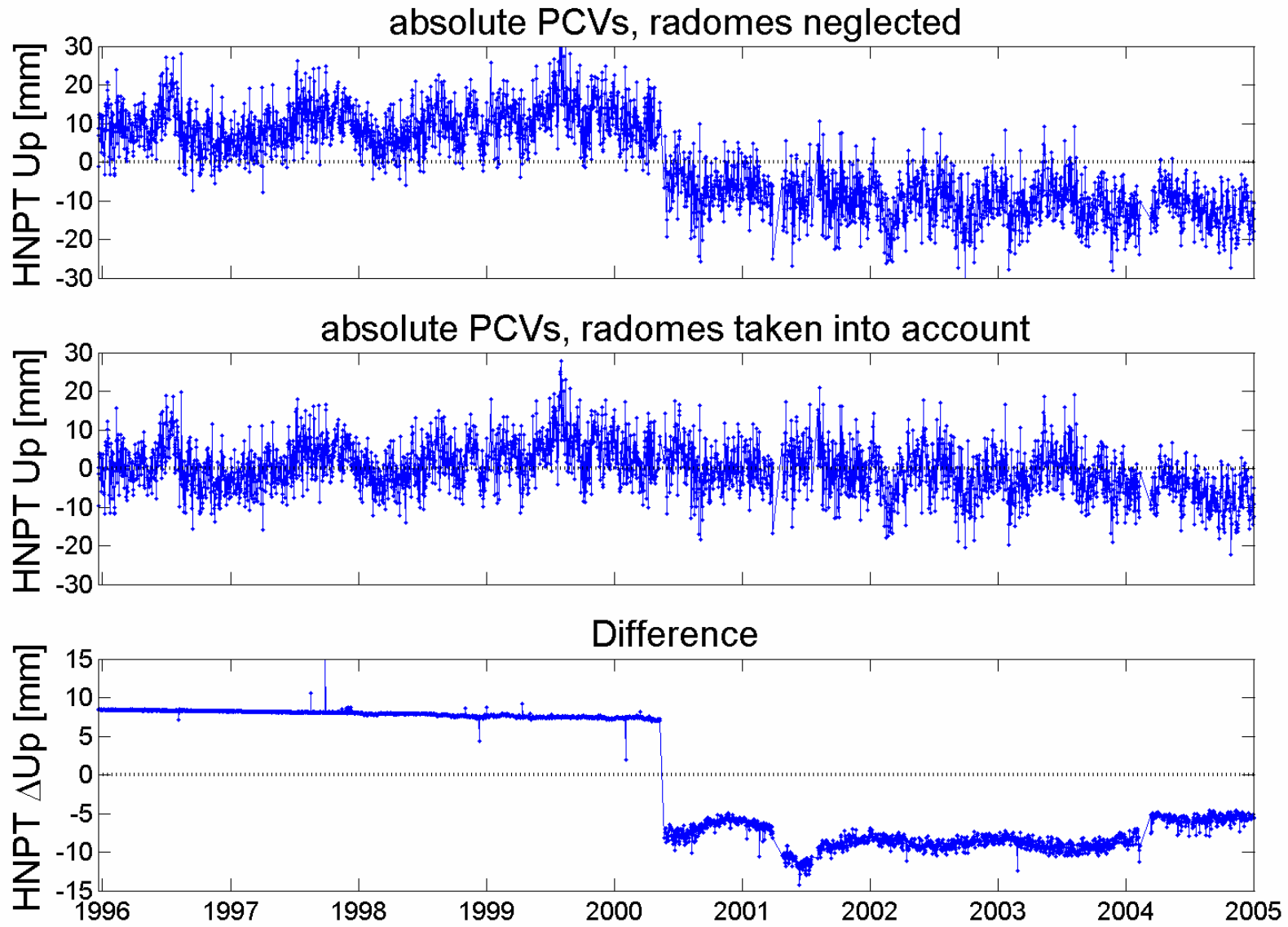
## Pros:

- Better than ignoring the radome effect
- Smaller effort than needed for additional calibrations
- Surprisingly good agreement for some radomes/frequencies

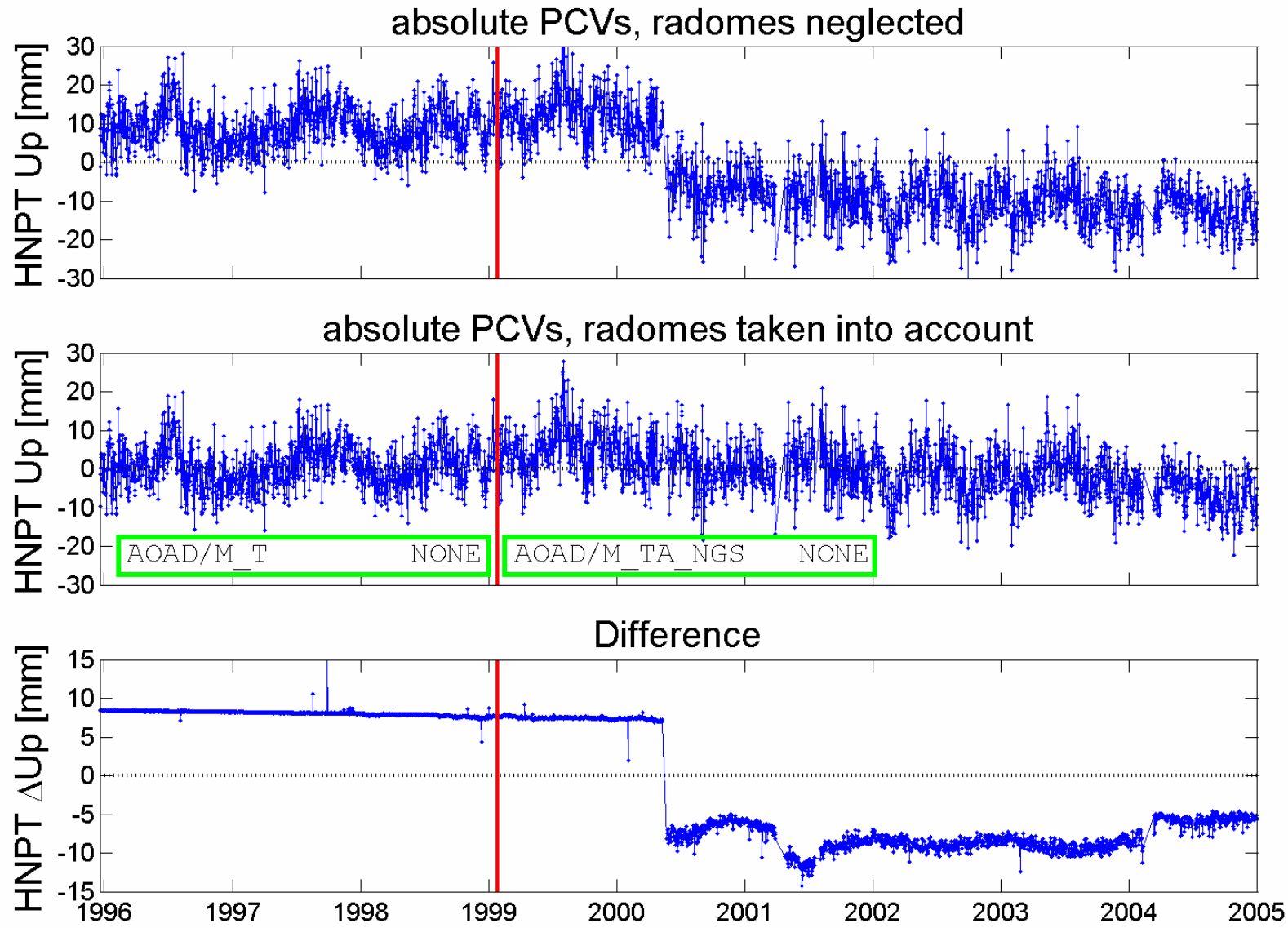
## Cons:

- How to deal with discrepancies?
- Multiple calibrations only for very few radomes
- Azimuth-dependent (NONE) + elevation-dep. (radome) ?
- Generation of a "three-class society" in igs05\_www.atx:
  1. robot calibrations
  2. converted field calibrations
  3. converted field calibrations + propagated radome effect

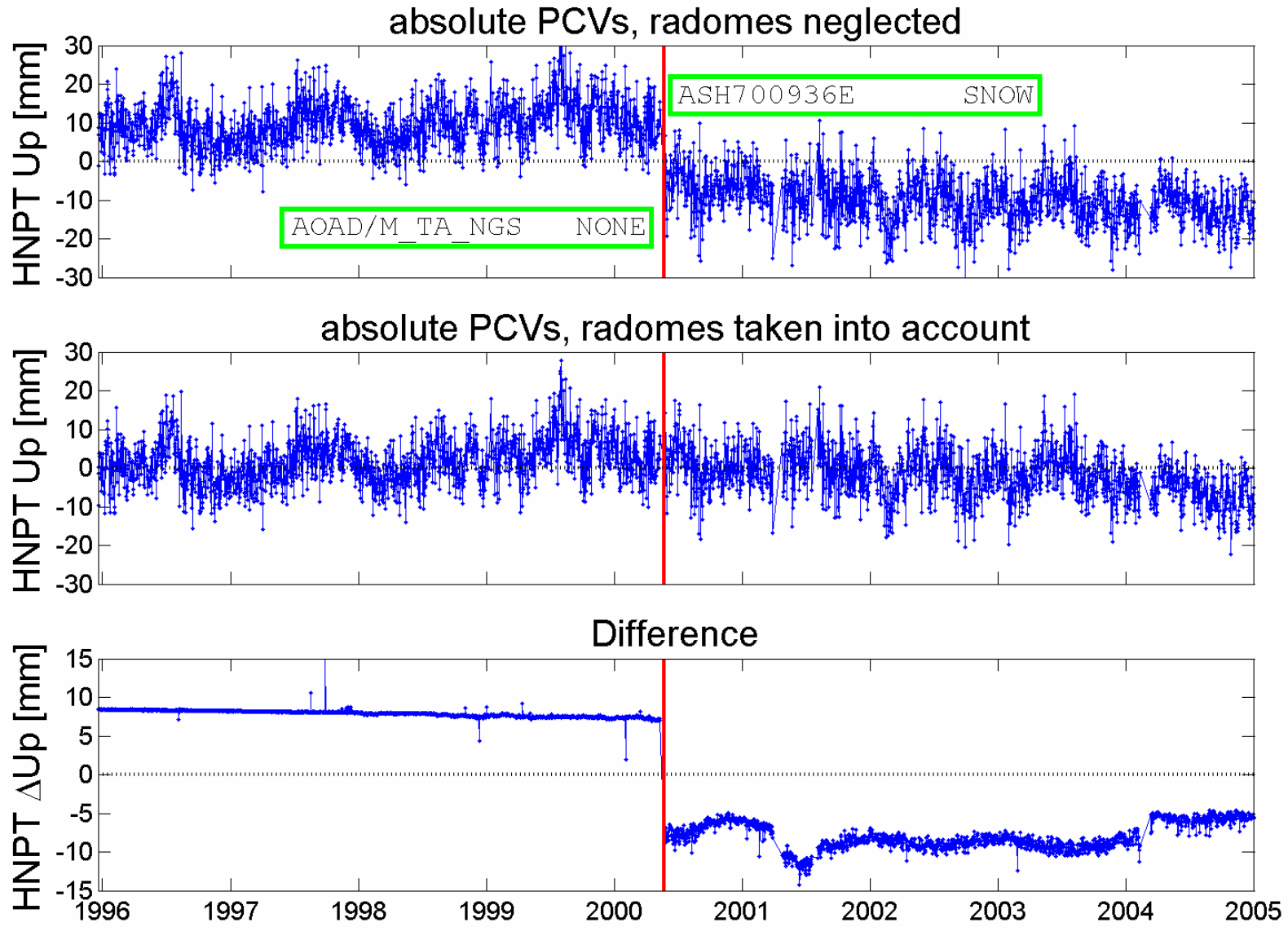
# Benefit from radome calibrations



# Benefit from radome calibrations




# Benefit from radome calibrations





# Conclusions

- Fully consistent antenna phase center model for all **GPS and GLONASS** satellites available (nadir-dependent only)
- **Converted field calibrations** should eventually be replaced by azimuthal PCVs down to  $0^\circ$  (How? When?)
- Big need for calibrations of **antenna + radome** combinations
- **Propagation** of the radome effect from one antenna to another is possible, but not trouble-free and of questionable accuracy
- Radome calibrations avoid **height biases of several cm**
- **Transition** to absolute PCVs is planned in parallel with the switch to ITRF2005 **in the coming months**

A large, shiny, metallic dome-shaped antenna or sensor is mounted on a structure, overlooking a town and mountains at sunset. The dome is highly reflective, showing a bright vertical streak of light from the setting sun. The background features a hazy landscape with buildings, trees, and distant mountains under a clear sky.

**Thanks for  
your attention!**

Photo: Enrique Cabral, UNAM