Relationships between mass redistribution, station position, geocenter, and Earth rotation: Results from IGS GNAAC analysis



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### Introduction

#### "Three Pillars of Geodesy"

- **1.** Earth's geometric shape
- **2.** Earth's gravity field
- **3.** Earth's orientation in space



- All are connected by Earth's response to mass redistribution
  - Earth's shape dominated by surface mass loading (0.1-10 yr)
- Effects of (seasonal) loading:
  - (Seasonal) variation in IGS station coordinate time series
  - Degree-0: <u>apparent</u> (seasonal) scale in IGS network
    - <u>biased</u> Helmert transformations, hence <u>frame-related errors</u>
  - Degree-1: <u>real</u> (seasonal) motion of solid Earth center of mass
    - several mm <u>common-mode</u> signal in GPS coordinate time series
    - theory predicts that this is not simply a translation
  - Degree-2: <u>real</u> (seasonal) polar motion from moment of inertia

# IGS GNAAC analysis since 1995: polyhedron construction (weekly)



# Physical Love-Shida model

 Earth deformation & geoid height all depend on surface mass distribution by load Love numbers (LLNs) within spherical harmonic expansions

• Total load  $T(\Omega) = \sum T_{nm}^{\Phi} Y_{nm}^{\Phi}(\Omega)$ 

o Height

$$H(\Omega) = \sum_{n,m,\Phi} h'_n \frac{3\rho_S}{(2n+1)\rho_E} T^{\Phi}_{nm} Y^{\Phi}_{nm}(\Omega)$$

• 2-D Lateral 
$$\mathbf{L}(\Omega) = \sum_{n,m,\Phi} l'_n \frac{3\rho_S}{(2n+1)\rho_E} T^{\Phi}_{nm} \nabla Y^{\Phi}_{nm} (\Omega)$$

Λ

o Geoid

$$V(\Omega) = \sum_{n,m,\Phi} (1 + k'_n) \frac{{}^{3\rho_S}}{(2n+1)\rho_E} T^{\Phi}_{nm} Y^{\Phi}_{nm} (\Omega)$$

# Load to degree 6 (GPS & Model)

#### Water-equivalent depth of load (mm)

#### Estimated Load - GPS



#### Modeled Load

- Soil moisture, snow depth: Milly et al.
- Atmosphere: NCEP/NCAR reanalysis + inverted barometer
- Ocean circulation: ECCO



### Deg-0: Total mass

- Conservation of surface mass implies
  - degree-0 load = 0
  - average change in Earth radius = 0

#### Problem of network scale

- Scale change = degree-0 deformation
- ...and GPS scale is defined by the speed of light
- Therefore variation in network scale ought to be <u>zero</u>
- But scale often used in 7 or 14-parameter transformation
- So why include scale in Helmert transformations?
  - to remove systematic error in orbit models, etc.?
  - or (incorrectly), to remove apparent scale due to real loading signals that are aliased by the non-uniform IGS network?
  - can lead to frame errors and can bias the load signal

# Effect of removing scale on load

#### Top plot

- Two step estimation remove scale parameter
  - Dong et al., 2003, n=1
  - Wu et al, 2003, n=6
- One step estimation No scale parameter removed
  - Blewitt et al., 2001, n=1
  - This work, n=1, n=6
- Poor agreement for deg-1

#### Bottom plot

- Two step estimation Both groups remove scale parameter first
- Good agreement for deg-1
- But degree-1 now more sensitive to truncation!



### Effect of load estimation on scale

- Estimated scale as part of Helmert transformation has significant (α=0.01) annual signal: 3.2 ppb
- Simultaneous estimation of scale + load coefficients eliminates annual scale signal !
- ...and load parameters are unaffected by simultaneous scale estimation!
- Helmert parameters should be simultaneously estimated with load coefficients !



# Deg-1: Center of mass & origin

#### Degree-1 displacements appear differently in various frames



# **Deg-1: Independent confirmation**

- GPS degree-1 deformation estimated every week
- Used to predict baseline length variations on VLBI baselines not used in the GPS analysis
  - Plot shows Westford-Gilcreek baseline
  - Dots from GPS "model"
  - Lines from VLBI observations
  - Correlation significant  $\alpha$ =0.0002



# Deg-2: Earth rotation consistency

#### Angular Momentum of Surface Fluids

• Motion & Mass: angular velocity & moment of inertia

#### Use Earth rotation measurements to test the GPSinferred mass load

- Degree-2 coefficients related to Earth's inertia tensor and hence to changes in Earth's rotation
- Changes in (2,0) mass load coefficient cause length-ofday to change
- Changes in (2,1) mass load coefficients cause the Earth to wobble as it rotates (excites polar motion)
- Compare Earth rotation changes predicted by GPSderived mass load coefficients to observed changes
- after removing tidal and motion effects (winds and currents) from observed changes

### Results: Degree-2 & Earth rotation

- Poor correlation with LOD excitation residual
  - Motion model error is believed to dominate
  - Mass load series exhibits less variability, is likely to be more accurate
- Significant correlation with polar motion excitation
  - Particularly so for the y-component which has a large seasonal cycle
  - Motion model error is believed to be very small



# Consistency with gravity field



# GRACE experiment... Monthly gravity fields, 2002–2007



- and SLR also gives
  - o geocenter
  - o and low-degree gravity field
- GPS gives
  - o geocenter
  - o and surface geometry
- Relationship between
  - geometry (surface height)
  - o and gravity (geoid height)

$$\mathbf{H}_{nm}^{\Phi} = \frac{h_n'}{1+k_n'} N_{nm}^{\Phi}$$

• Hence invert for LLN ratio with no explicit knowledge of load

# Constraints on Earth's elasticity

GPS degree-1/GPS geocenter:

$$\frac{h_1'}{1+k_1'} = -0.20 \pm 0.01$$

#### GPS degree-1/SLR geocenter:

$$\frac{h_1'}{1+k_1'} = -0.21 \pm 0.02$$

o Earth Model (PREM): -0.25

• At degree-2:

$$\frac{h_2'}{1+k_2'} = -0.81 \pm 0.15$$

• Earth Model (PREM): -1.4





# Self-consistent mass redistribution



# Non-steric global mean sea level

 GPS weekly results
o 11.7 mm peak-to-peak max on 10 Sep

 Compare with seasonal models derived from:

• hydrological models

o TOPEX altimetry

o with various assumptions

Ocean heat budget?



# **Prospects: Physical assimilation**

- Consider 3 Levels of Data Assimilation:
  - Station coordinate level
  - o Kinematics level
  - o Physical (dynamics) level
- Physical level has the potential
  - To enforce consistency in Earth system
  - To combine GPS, VLBI, SLR, GRACE, Jason, tide gauge data, surface gravity, Earth rotation,...
  - But it requires careful treatment of reference frames and consistency within and between models
  - assimilation should clarify our thinking and should help to resolve problems in models and data

# "Grand Unified Geodesy"





# Conclusions: What can IGS do to improve Global GPS Science?

- IGS GNAAC analysis has demonstrated the physical connections between coordinates, loading, gravity, sea level, & Earth rotation
- IGS can incrementally improve current products by improving:
  - station distribution: uniformity, density, and stability
  - station configuration: uniformity and stability
  - station data & metadata: accuracy and availability
  - duration of IGS network: 20+ years!

#### PROPOSAL: IGS should adopt a new product:

- spherical harmonic coefficients (weekly)
- simultaneously estimated Helmert parameters (to ITRF)
- This will create an important physical connection to other types of observations, and to other IAG Services & scientific communities

#### It will be back to the "good old days" in global GPS geodesy!

• by taking IGS to the next level - *dynamics* 

#### Our recent publications on this...

#### Some PDFs at: http://www.nbmg.unr.edu/staff/geoff.htm

- Gross, R., G. Blewitt, P. Clarke, D. Lavallee, Degree-2 harmonics of the Earth's mass load estimated from GPS and Earth rotation data, *Geophys. Res. Lett.* (in press, 2004)
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- Blewitt, G., Clarke, P.J., D. Lavallee, and K. Nurutdinov, Application of Clebsch-Gordan coefficients and isomorphic frame transformations to invert Earth's changing geometrical shape for continental hydrological loading and sea level's passive response, in *Proc. of the IUGG 2003 General Assembly* (in press, 2004)
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- Lavallee, D., and G. Blewitt, Degree-one Earth deformation from very long baseline interferometry, *Geophys. Res. Lett., Vol 29(20)*, doi:10.1029/2002GL015883, 2002.
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